Vera Sacristán

Computational Geometry
Facultat d'Informàtica de Barcelona
Universitat Politcnica de Catalunya

A polygon triangulation is the decomposition of a polygon into triangles. This is done by inserting internal diagonals. · o intersección de los AIS PD vacía

An internal diagonal is any segment...

union de los 1's connecting two vertices of the polygon and

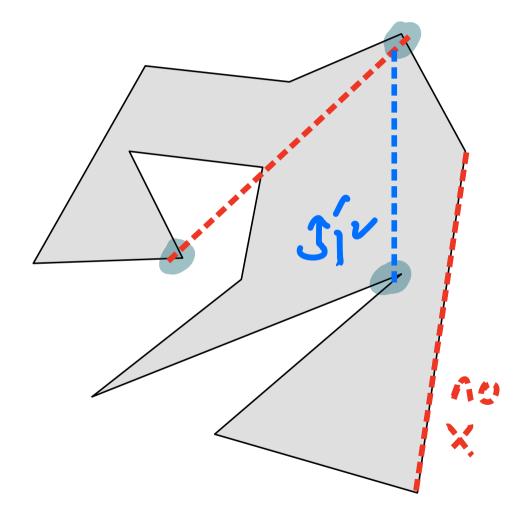
es el poligono

• completely enclosed in the polygon.

o vértices de 215 Endinterior del poligono es una grafica plana maximal, 508 aristas son seguentos de recta = vértices del poligono.

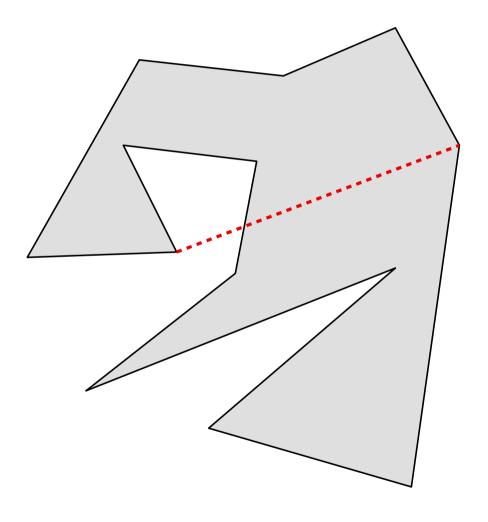
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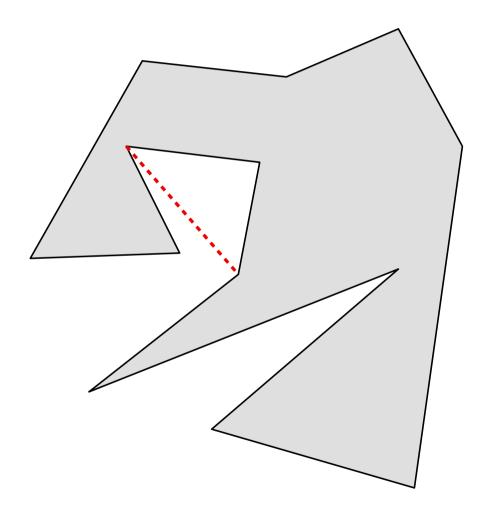
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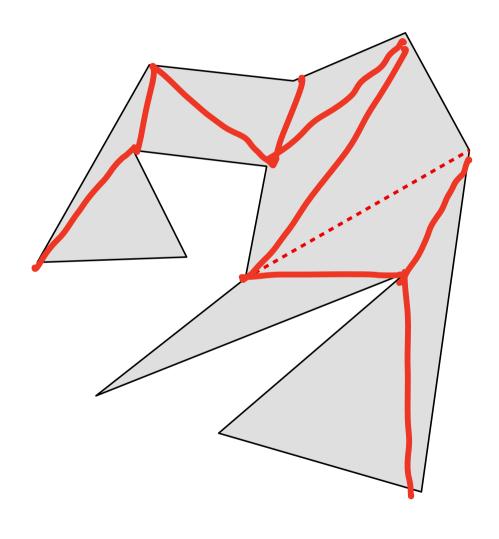


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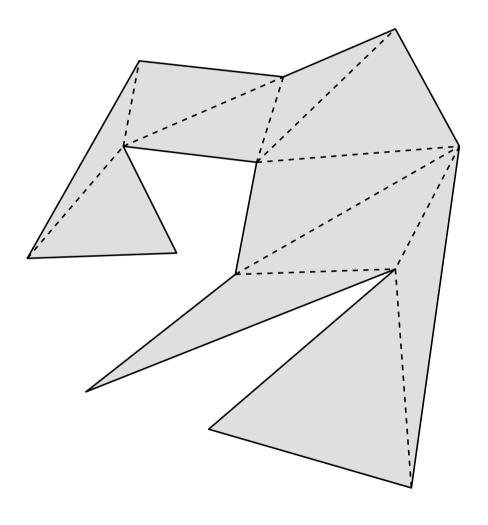
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oNb hay cruces.

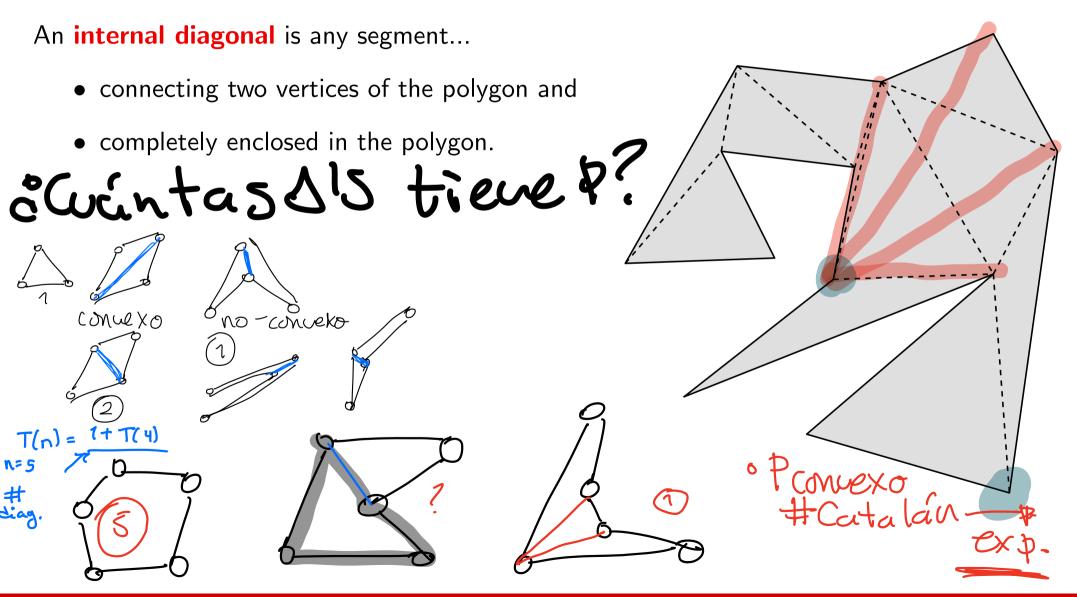


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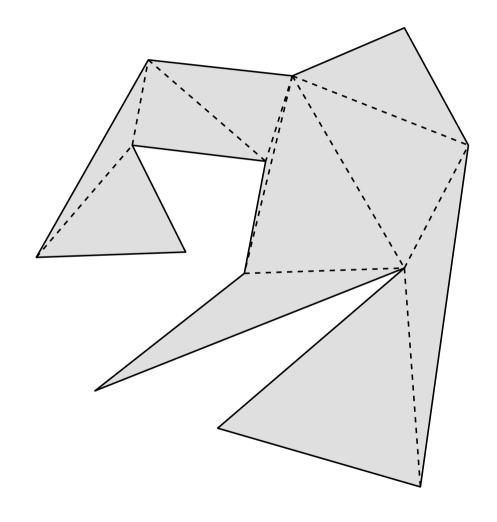
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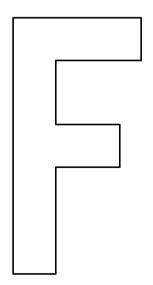
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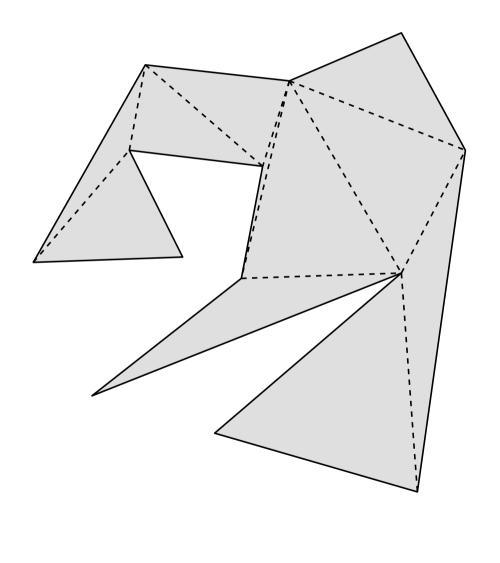


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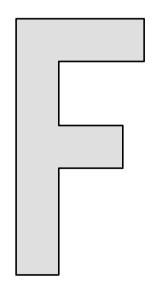


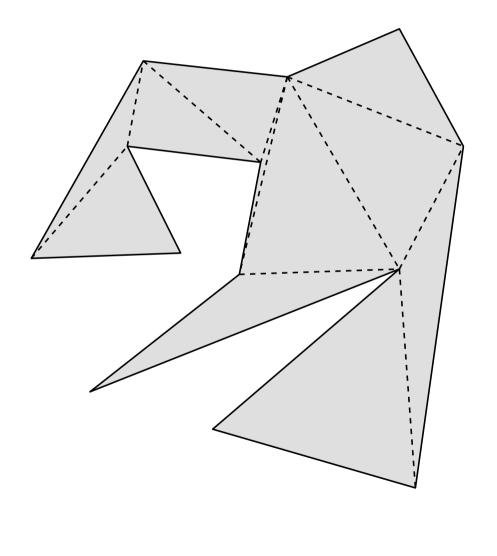


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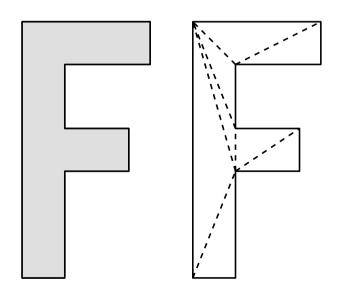


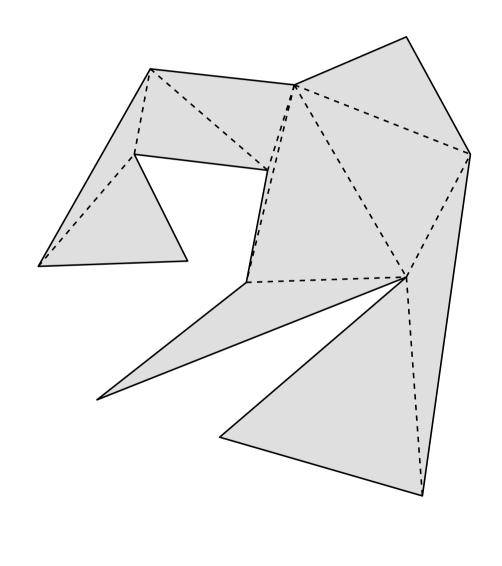


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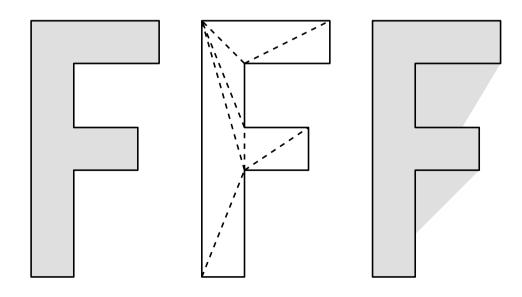


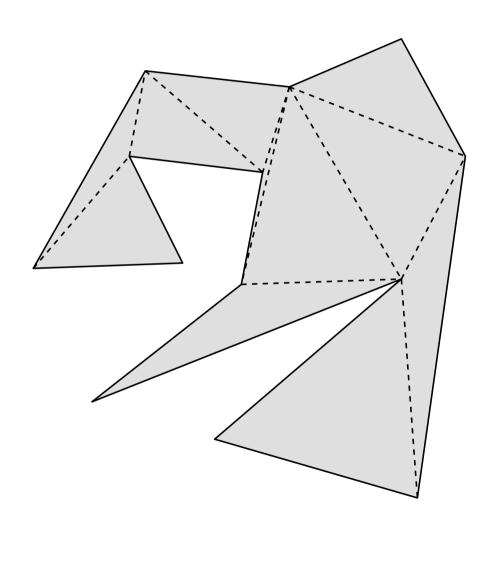


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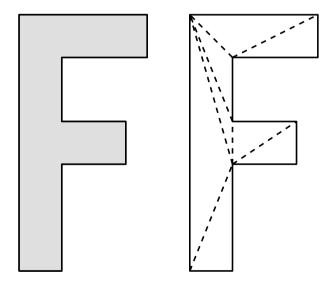


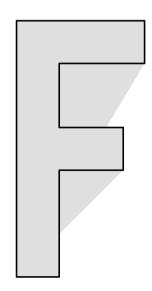


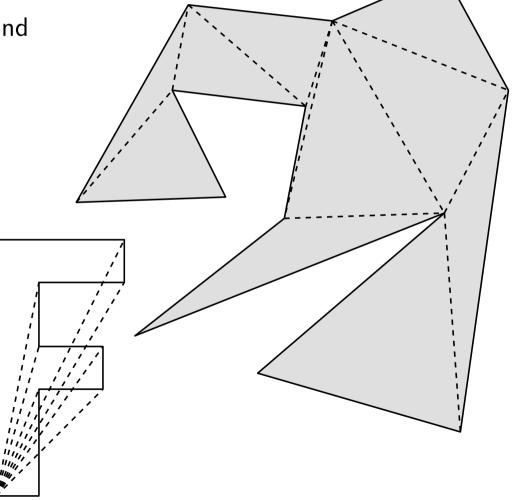
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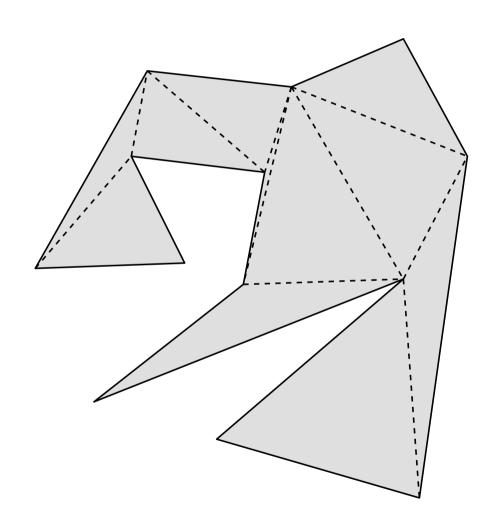






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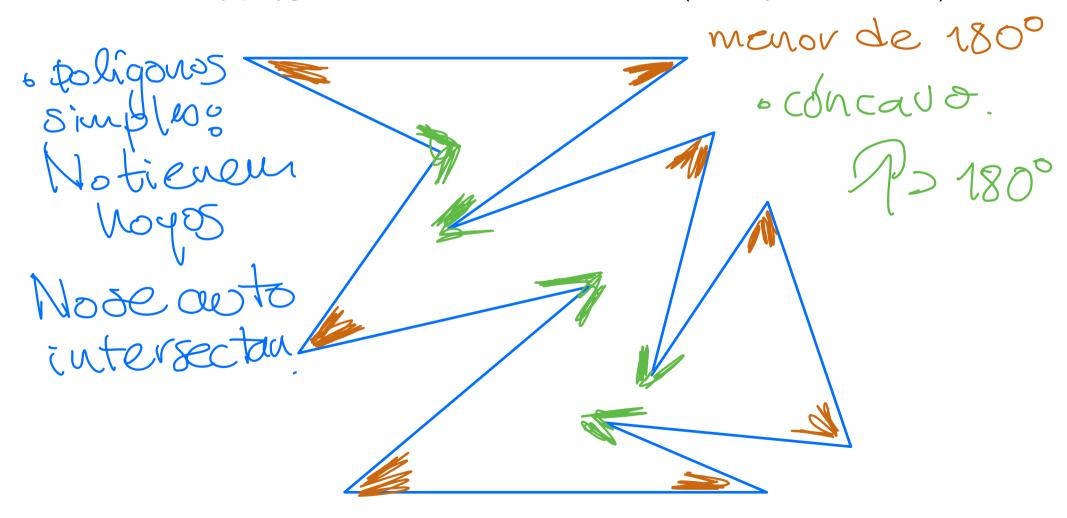
- 1. Every polygon can be triangulated
- 2. Properties of polygon triangulations
- 3. Algorithms
 - (a) Triangulating by inserting diagonals
 - (b) Triangulating by subtracting ears
 - (c) Triangulating convex polygons
 - (d) Triangulating monotone polygons
 - (e) Monotone partinioning



Every polygon admits a triangulation > description of triangulation + triangul

Every polygon admits a triangulation

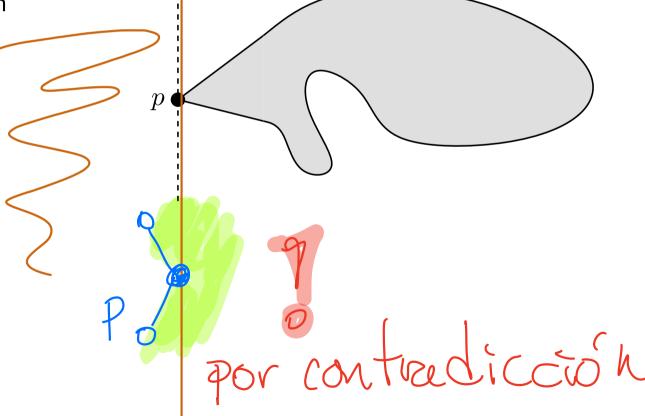
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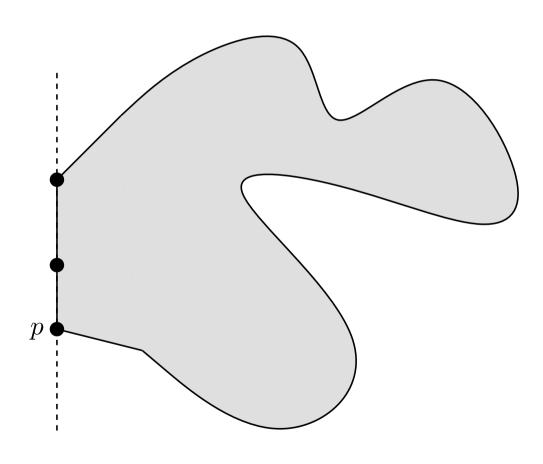
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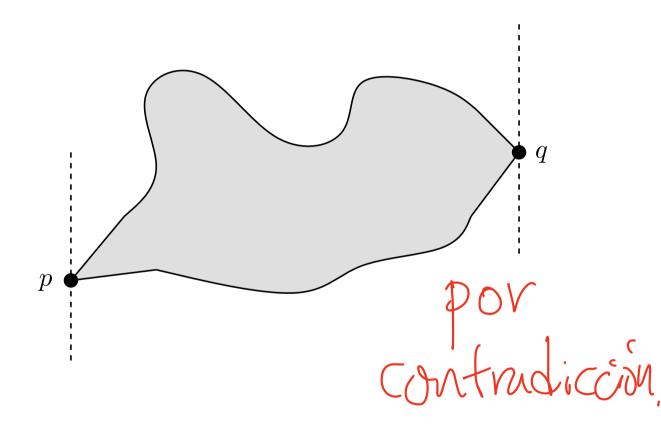


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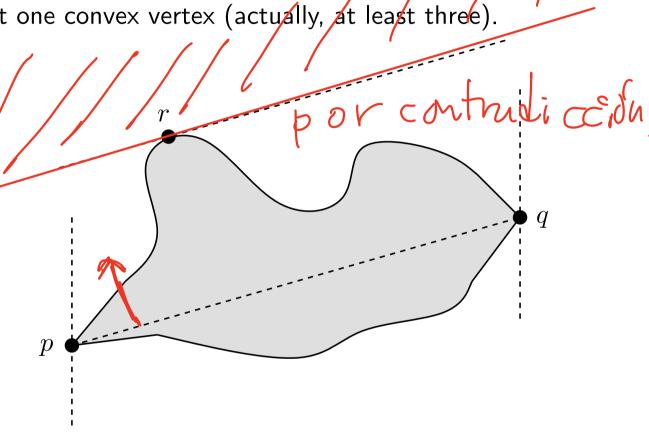
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Finally, there is at least one vertex which is extreme in the direction orthogonal to pq and does not coincide with any of the above. This third vertex r is necessarily convex.



Every polygon admits a triangulation

Lemma 1. Every polygon has at least one convex vertex (actually, at least three).

Lemma 2. Every n-gon with $n \geq 4$ has at least one internal diagonal. poligono con n vérticos.

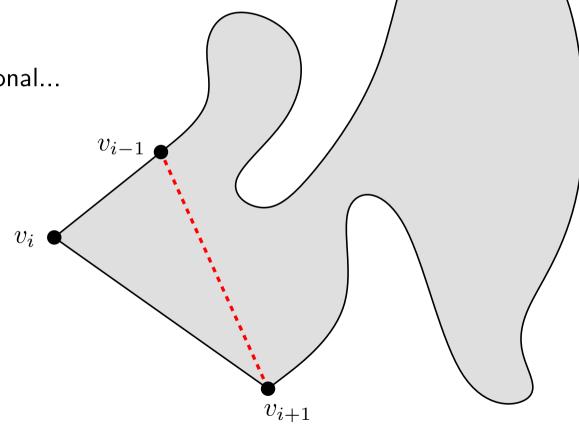
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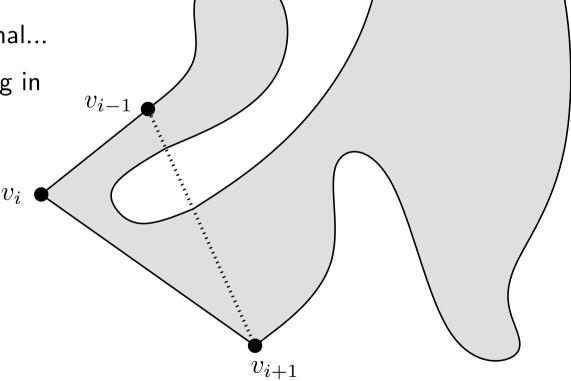
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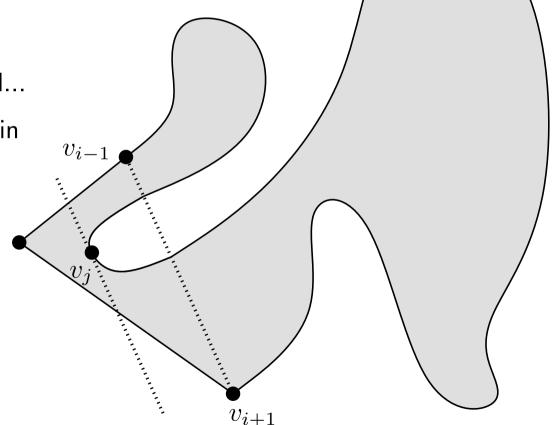
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In this case, among all the vertices lying in the triangle, let v_j be the farthest one from the segment $v_{i-1}v_{i+1}$. Then v_iv_j is an internal diagonal (it can not be intersected by any edge of the polygon).



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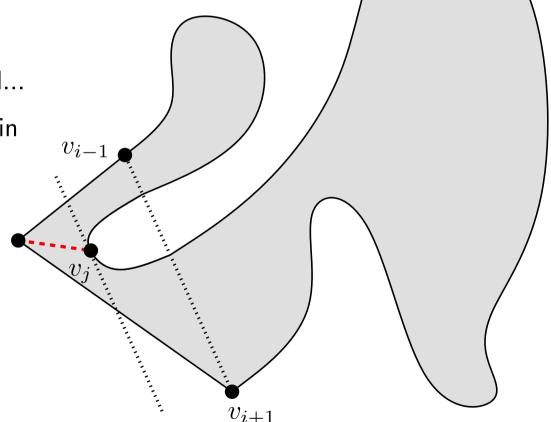
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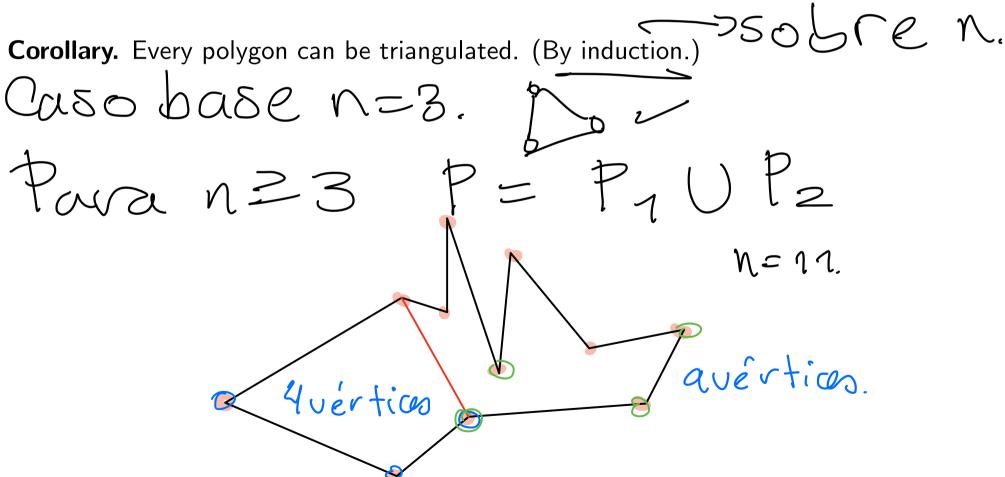
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Properties of the triangulations of polygons

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Let P be a simple n-gon.

Property 1. Every triangulation of P has n-3 diagonals.

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Proof by induction.

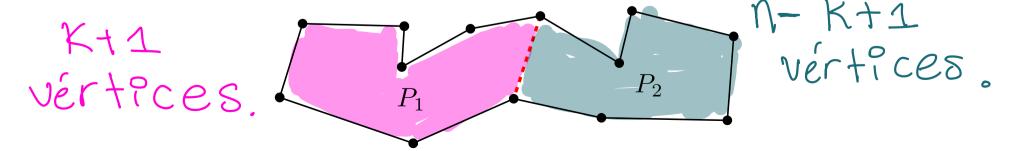
Base case: When n=3, the number of diagonals is d=0=n-3.

Inductive step: Consider a diagonal of a triangulation T of P, decomposing P into two subpolygons: a (k+1)-gon P_1 and an (n-k+1)-gon P_2 . By inductive hypothesis, the number of diagonals of the triangulations induced by T in P_1 and P_2 are:

$$d_1 = k + 1 - 3,$$

$$d_2 = n - k + 1 - 3,$$

therefore,
$$d = d_1 + d_2 + 1 = k + 1 - 3 + n - k + 1 - 3 + 1 = n - 3$$
.

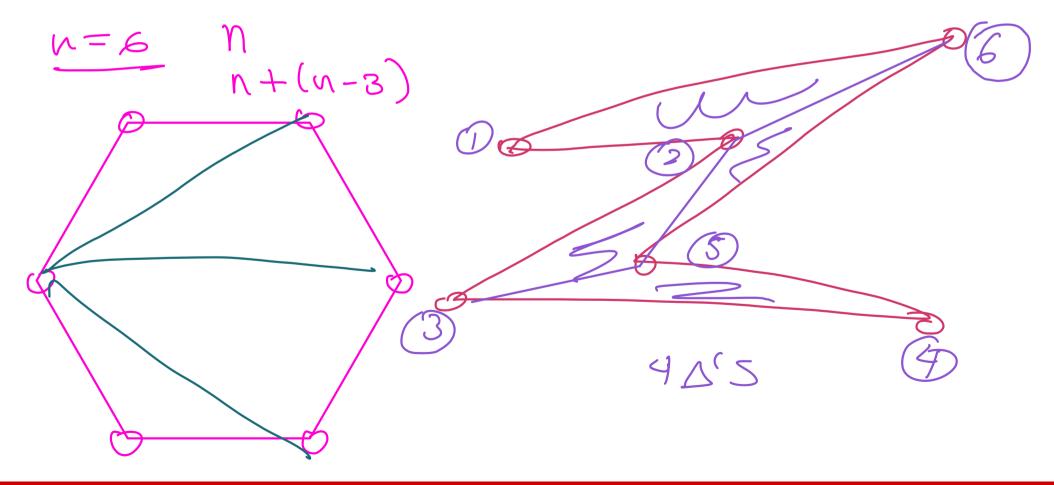


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Teorema. (Identidad de Foler). aplanable
Para cada gráfica conexa con V vértices, E aristas y F caras
Ocorre que:
V-E+F=2.

Teorema: Si G es una gráfica aplanable con 123 y Faristas, entonces. E = 31-6.

Lema. Et # de diagonain de feriores en una gráfica plana maximal es 11-3.

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Again, the proof is by induction.

Base case: When n=3, the number of triangles is t=1=n-2.

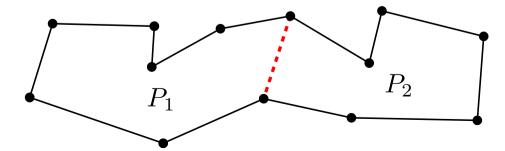
Inductive step: With the same conditions of the previous proof,

$$t_1 = k + 1 - 2,$$

 $t_2 = n - k + 1 - 2,$

hence,

$$t = t_1 + t_2 = k + 1 - 2 + n - k + 1 - 2 = n - 2.$$



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acyclic. V= un vértice porcada triangulo

E= 2 (v1, v;) l'el triángulo correspond. a

vir y el scorresq. a uz tienen

una diagonal en consón?

lul=n-2; |E|= h-3

Octobera 2 para demostrar que es un Octobelo.

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(2) acíclica - Dhoyos.

The graph is trivially connected.

About the acyclicity: Notice that each edge of the dual graph "separates" the two endpoints of the internal diagonal of P shared by the two adjacent triangles. If the graph had a cycle, it would enclose the endpoint(s) of the diagonals intersected by the cycle and, therefore, it would enclose points belonging to the boundary of the polygon, contradicting the hypothesis that P is simple and without holes.

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Corollary. Every n-gon with $n \ge 4$ has at least two non-adjacent ears.

Oreja: Sean a,b,c tres vértices consecutivos de P. Decimos que a,b,c forman una oreja si ac es una diagonal.

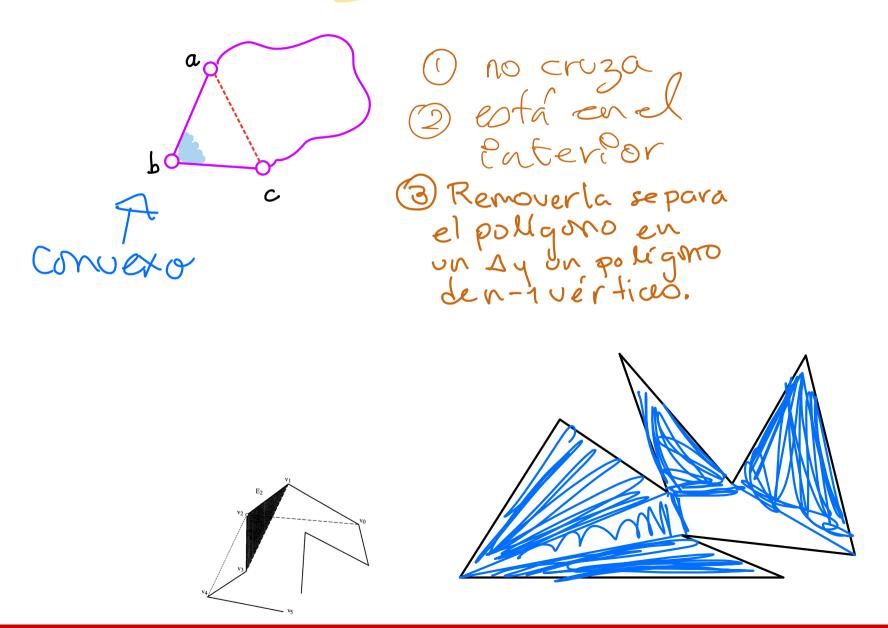
de remover el s'elpoligono nose desconecta. ab y bc son avistas del polígono

Bastaria con demostrar que todo árbol

vertice de grandon = hoja. En la gráfica dual corresp.

ALGORITHMS FOR POLYGON TRIANGULATION

Tringulating a polygon by subtracting ears



Tringulating a polygon by subtracting ears

Input: v_1, \ldots, v_n , sorted list of the vertices of a simple polygon P.

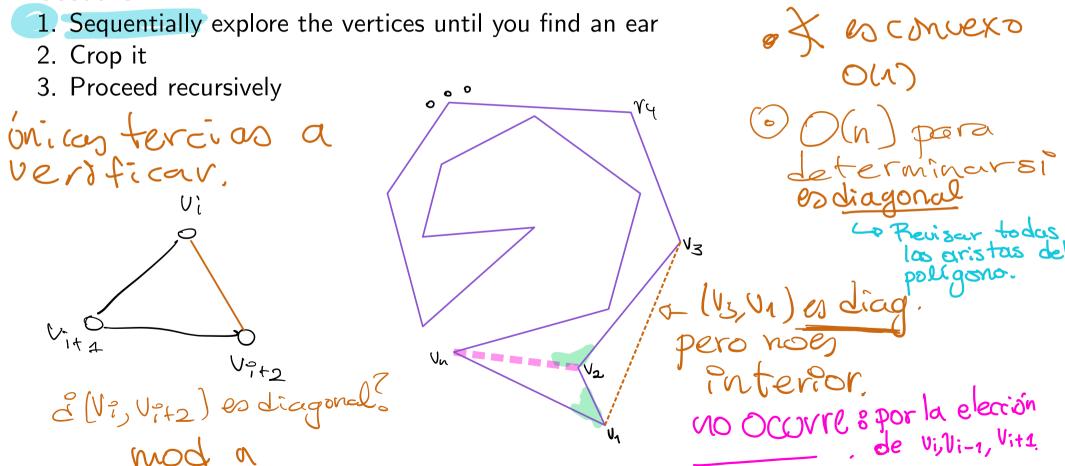
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Procedure

- 1. Sequentially explore the vertices until you find an ear
- 2. Crop it
- 3. Proceed recursively

Running time

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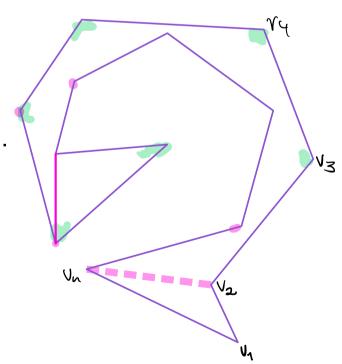
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Overall running time:

$$T(n) = O(n^2) + O((n-1)^2) + O((n-2)^2) + \dots + O(1) = O(n^3).$$

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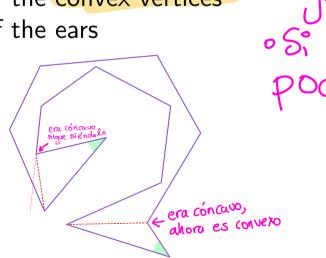
Improved procedure

Initialization

- 1. Detect all convex vertices
- 2. Detect all ears

Next step

- 1. Crop an ear
- 2. Update the information of the convex vertices
- 3. Update the information of the ears



olos únicos angulos afectados son el 3 Con á pice en v:-1 y con á pice en v:+1. PSi v:-1 (V:+1) era convexo sigue siendo convexo. Podría ser ahora conlexo.

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Improved procedure	Running time
Initialization 1. Detect all convex vertices 2. Detect all ears	$O(n) \ O(n^2)$ Only once
Next step 1. Crop an ear	O(1)
2. Update the information of the convex vertices 3. Update the information of the ears Supongamos gue borramos la convex afectarse Vy?	O(1) $O(n)$ times $O(n)$
de orejos afectados versia de orejos de orejos afectados versia de orejos afectados versia de orejos de orej	
yesto no cambia yesto no cambia o v ₃ v ₅ no es diagonal. o v ₃ v ₅ es externa o está blogreada: Alvo,	.V4,V5) noestá vacío.

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Improved procedure	Running time
Initialization	
1. Detect all convex vertices	O(n)
2. Detect all ears	$O(n^2)$ Only once
Next step	
1. Crop an ear	O(1)
2. Update the information of the convex vertices	O(1) $O(n)$ times
3. Update the information of the ears	O(n)
bool InCone (tVertex & Sea Kel punto en el interior (tVertex a0, a1; /* a0 de hecho un angulo cónce a1 = a->next; a0 = a->prev; al remover la oreja (b) /* If a is a convex vertex */ if (Lefton (a->v, a1-:	fuera eliminago

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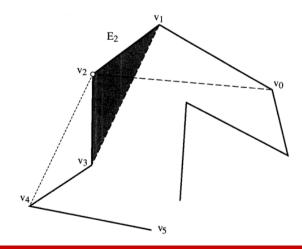
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Running time

$$O(n)$$
 Only once

O(1) O(1) O(n) times

O(n)

Algorithm: TRIANGULATION
Initialize the ear tip status of each vertex.
while n > 3 do
Locate an ear tip v_2 .
Output diagonal v_1v_3 .
Delete v_2 .
Update the ear tip status of v_1 and v_3 .

Algorithm 1.1 Triangulation algorithm.

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Improved procedure	Running time	
Initialization		
1. Detect all convex vertices	$O(n)$ $O(n^2)$	Only once
2. Detect all ears	$O(n^2)$	Only once
Next step		
1. Crop an ear	O(1)	
2. Update the information of the convex vertices	O(1)	O(n) times
3. Update the information of the ears	O(n)	

Running time: $O(n^2)$

Tringulating a polygon by inserting diagonals

Input: v_1, \ldots, v_n , sorted list of the vertices of a simple polygon P.

Output: List of internal diagonals of P, $v_i v_j$, determining a triangulation of P.

Tringulating a polygon by inserting diagonals

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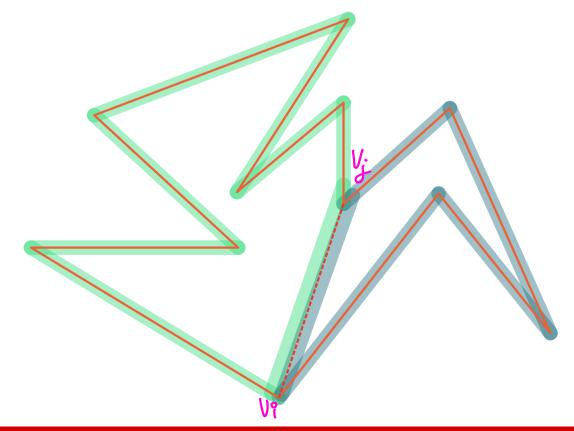
Output: List of internal diagonals of P, $v_i v_j$, determining a triangulation of P.

Procedure:

1. Find an internal diagonal

2. Decompose the polygon into two subpolygons

3. Proceed recursively



Tringulating a polygon by inserting diagonals

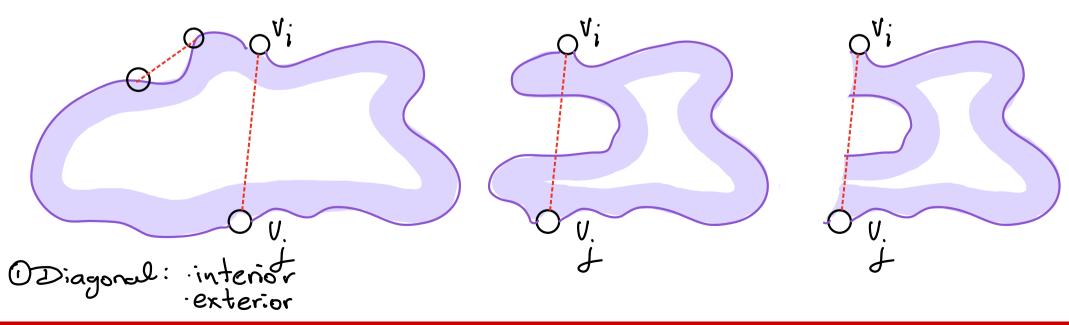
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Test. How to decide whether a given segment $v_i v_j$ is an internal diagonal?



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Procedure:

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Test. How to decide whether a given segment v_iv_j is an internal diagonal? Is it a diagonal?

Tringulating a polygon by inserting diagonals

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- 3. Proceed recursively

Test. How to decide whether a given segment $v_i v_j$ is an internal diagonal?

Is it a diagonal?

Check $v_i v_j$ against all segments $v_k v_{k+1}$ for intersection.

Tringulating a polygon by inserting diagonals

Input: v_1, \ldots, v_n , sorted list of the vertices of a simple polygon P.

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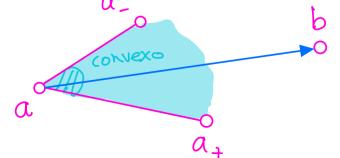
Procedure:

- 1. Find an internal diagonal
- 2. Decompose the polygon into two subpolygons
- 3. Proceed recursively

Test. How to decide whether a given segment $v_i v_j$ is an internal diagonal?

Is it a diagonal?

Check v_iv_j against all segments v_kv_{k+1} for intersection. Is it internal? Noten que en este caso vi v_j no necesariament son consecutivos 8 Cómo podemos determinour si es diagonalinterior? (antes si)



si a es convexo, ab es interior si: a-está a la izq de ab a+ está a la der de ab

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8Cómo podemos determinour si es diagonalinterior?

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ab es interna si no es externa

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Is it internal?

8 Cómo podemos determinar si es diagonal interior?

Lema El segmento s= vivj es una diagonal interior de P

iff:

9 toristas e de Pque noson adyacentes o vi nia v;

sne=0

2 s es interna a Pen una vecindad de vi y de v;

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Is it internal?

8 Cómo podemos determinour si es diagonal interior? tVertex a0, a1; /* a0,a,a1 are consecutive vertices. */

a0 = a->prev; /* If a is a convex vertex . . . */ if(LeftOn(a->v, a1->v, a0->v)) return Left(a->v, b->v, a0->v) && Left(b->v, a->v, a1->v); return !(LeftOn(a->v, b->v, a1->v)

Code 1.11 InCone.

Tringulating a polygon by inserting diagonals

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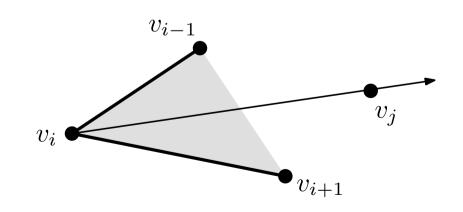
Test. How to decide whether a given segment $v_i v_j$ is an internal diagonal?

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Check $v_i v_j$ against all segments $v_k v_{k+1}$ for intersection.

Is it internal?

If v_i is convex, the oriented line $\overrightarrow{v_iv_j}$ should leave v_{i-1} to its left and v_{i+1} to its right.



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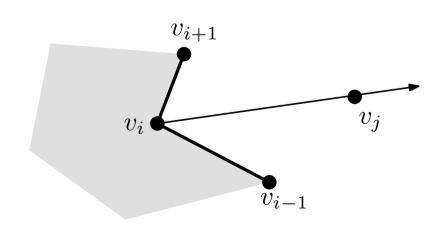
Is it a diagonal?

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Is it internal?

If v_i is convex, the oriented line $\overrightarrow{v_iv_j}$ should leave v_{i-1} to its left and v_{i+1} to its right.

If v_i is reflex, the oriented line $\overrightarrow{v_iv_j}$ should not leave v_{i-1} to its right and v_{i+1} to its left.



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Running time

Test. How to decide whether a given segment $v_i v_j$ is an internal diagonal? O(n)

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Search. How to find an internal diagonal?

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Brute-force solution:

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Running time

Test. How to decide whether a given segment $v_i v_j$ is an internal diagonal? O(n)

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Brute-force solution:

Apply the test to each candidate segment.

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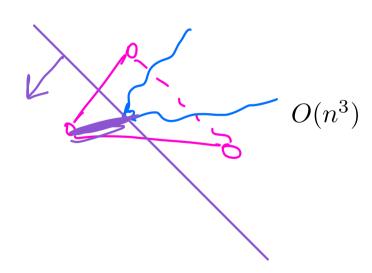
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O(n)

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Apply the test to each candidate segment.

 $O(n^3)$

Testing each candidate takes O(n) time, and there are $\binom{n}{2}$ of them.

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Running time

Test. How to decide whether a given segment $v_i v_j$ is an internal diagonal?

O(n)

Search. How to find an internal diagonal?

Brute-force solution:

Apply the test to each candidate segment.

 $O(n^3)$

Applying previous results:

- 1. Find a convex vertex, v_i .
- 2. Detect whether $v_{i-1}v_{i+1}$ is an internal diagonal.
- 3. If so, report it. Else, find the farthest v_k from the segment $v_{i-1}v_{i+1}$, lying in the triangle $v_{i-1}v_iv_{i+1}$.

Tringulating a polygon by inserting diagonals

Input: v_1, \ldots, v_n , sorted list of the vertices of a simple polygon P.

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Procedure:

1. Find an internal diagonal

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Search. How to find an internal diagonal? O(n)

Partition. How to partition the polygon into two subpolygons?

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Partition. How to partition the polygon into two subpolygons?

From the diagonal found, create the sorted list of the vertices of the two subpolygons.

Computational Geometry, Facultat d'Informàtica de Barcelona, UPC

Tringulating a polygon by inserting diagonals

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Test. How to decide whether a given segment $v_i v_j$ is an internal diagonal?	O(n)

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Partition. How to partition the polygon into two subpolygons? O(n)

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Test. How to decide whether a given segment v_iv_j is an internal diagonal?	O(n)

O(n)**Search.** How to find an internal diagonal?

O(n)**Partition.** How to partition the polygon into two subpolygons?

Total running time of the algorithm: $O(n^2)$

It finds n-3 diagonals and each one is found in O(n) time.

Is it possible to triangulate a polygon more efficiently?

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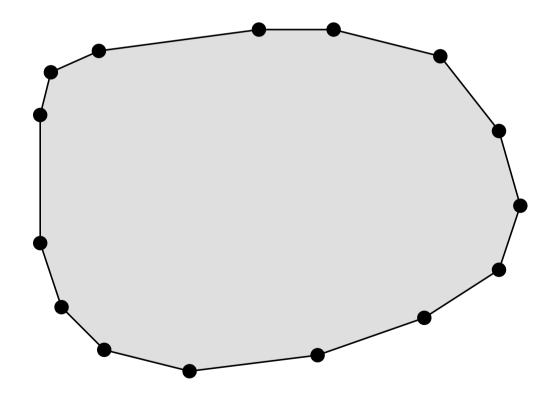
Triangulating a convex polygon

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Triangulating a convex polygon

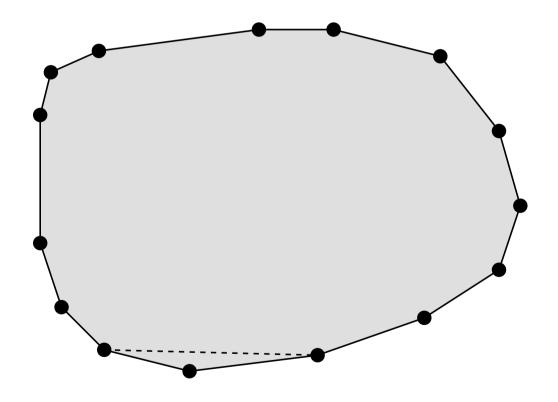
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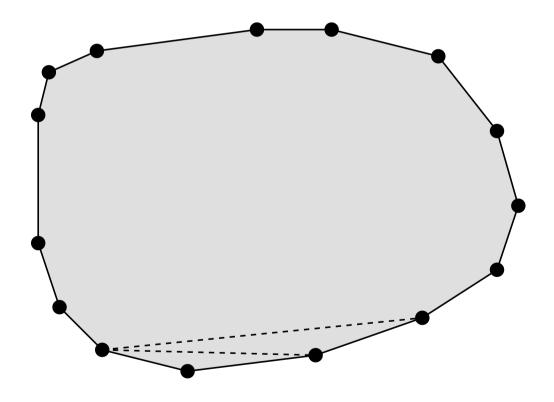
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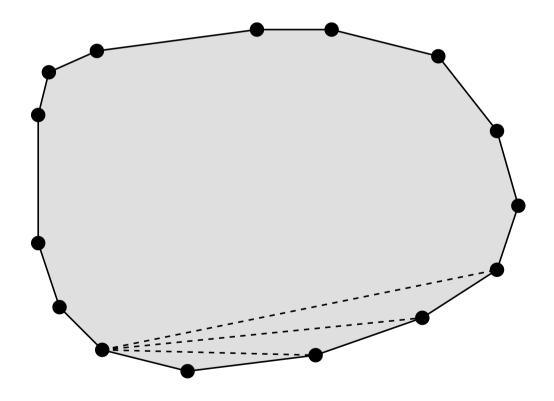
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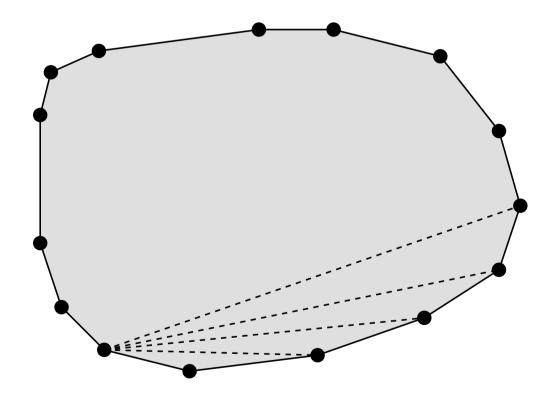
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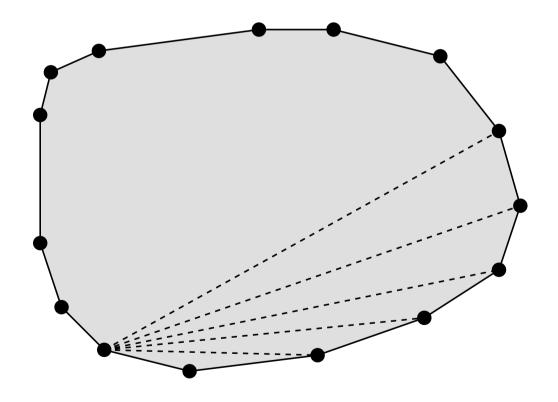
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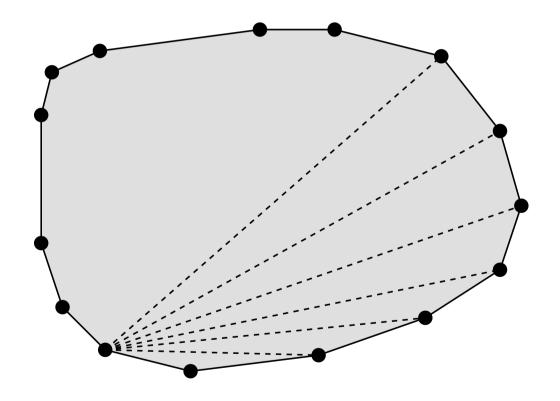
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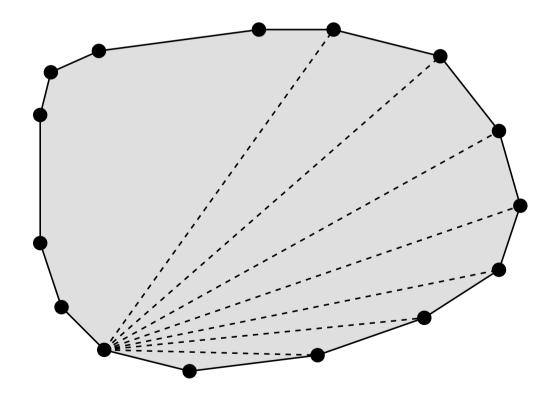
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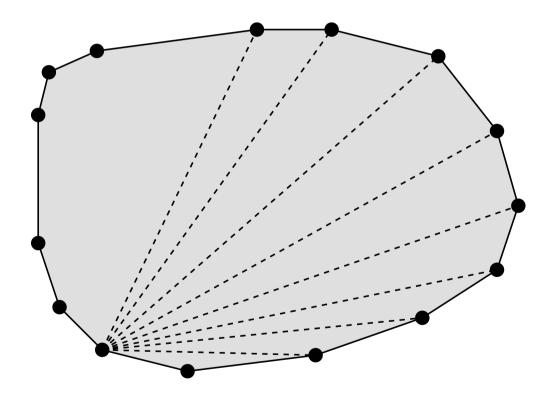
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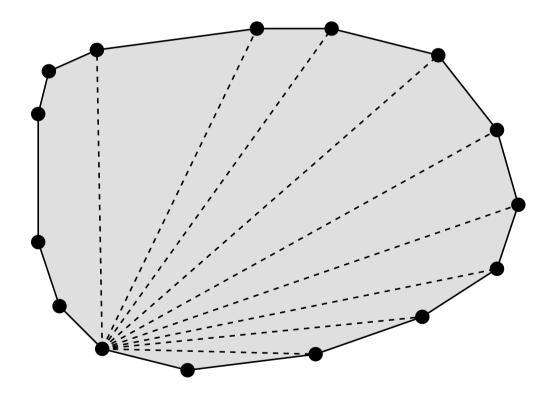
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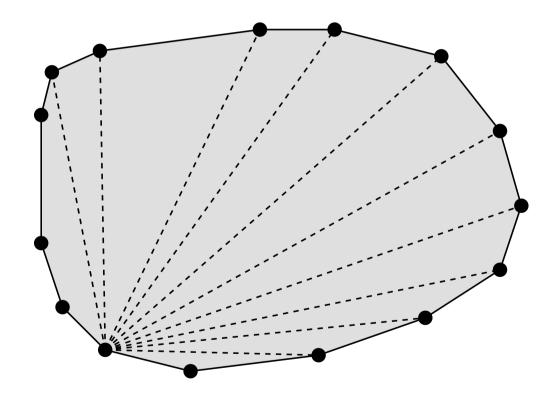
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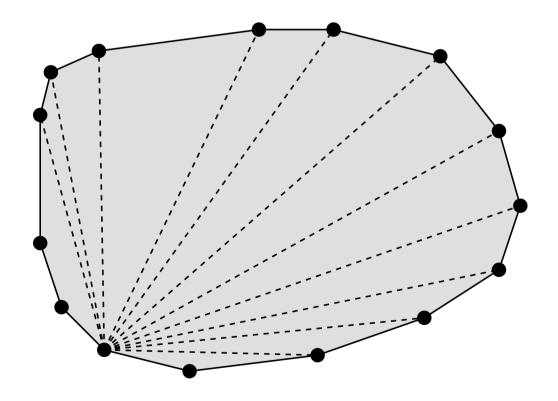
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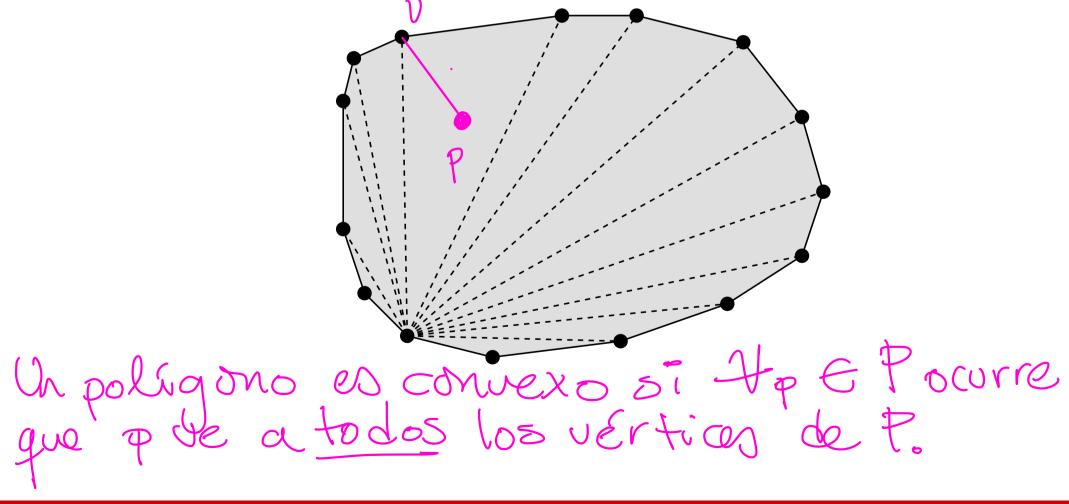
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Triangulating a convex polygon



Is it possible to triangulate a polygon more efficiently?

Triangulating a convex polygon $\forall p \in \mathcal{V}$

Trivially done in O(n) time.

Triangulating a star-shaped polygon

Can be done in O(n) time. Posed as problem.

Si Fp & P que puede vera to dos los vértices del polígoros · los polígonos con exos son estrellados.

Is it possible to triangulate a polygon more efficiently?

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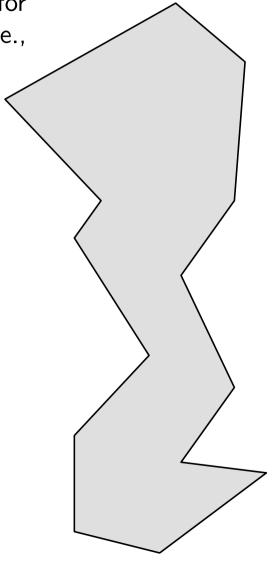
Triangulating a monotone polygon

It can also be done in O(n) time. In the following we will see how.

Monotone polygon

Monotone polygon

Monotone polygon



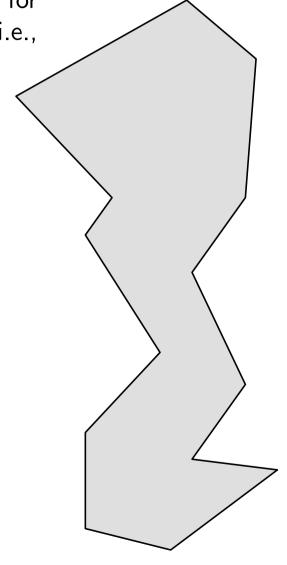
Monotone polygon

Monotone polygon

A polygon P is called **monotone** with respect to a direction r if, for every line r' orthogonal to r, the intersection $P \cap r'$ is connected (i.e., it is a segment, a point or the empty set).

Local characterization

A polygon is y-monotone if and only if it does not have any cusp.

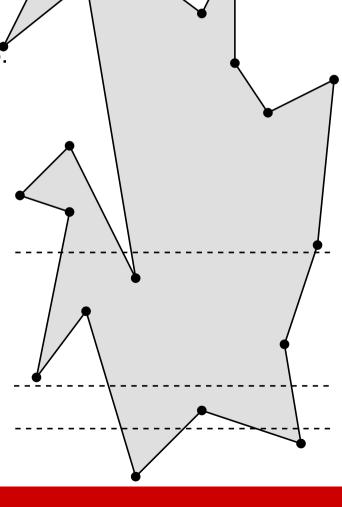


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Local characterization

A polygon is y-monotone if and only if it does not have any cusp.

A **cusp** is a reflex vertex v of the polygon such that its two incident edges both lie to the same side of the horizontal line through v.

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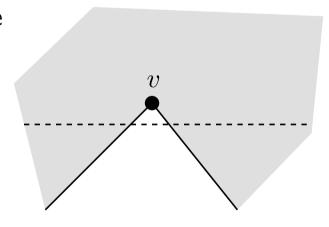
Local characterization

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Proof:

If the polygon has a local maximum cusp v, an infinitesimal downwards translation of the horizontal line through v would intersect the polygon in at least two connected components.



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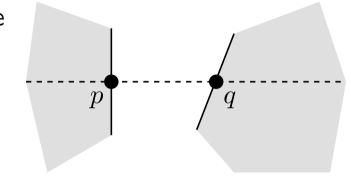
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If the polygon is not y-monotone, let r be a horizontal line intersecting the polygon in two or more connected components. Consider two consecutive components, with facing endpoints p and q as in the figure. The polygon boundary needs to connect p and q. No matter whether it goes above or below the horizontal line, it will have a cusp.

Monotone polygon

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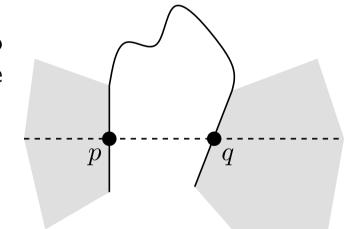
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If the polygon has a local maximum cusp v, an infinitesimal downwards translation of the horizontal line through v would intersect the polygon in at least two connected components.



If the polygon is not y-monotone, let r be a horizontal line intersecting the polygon in two or more connected components. Consider two consecutive components, with facing endpoints p and q as in the figure. The polygon boundary needs to connect p and q. No matter whether it goes above or below the horizontal line, it will have a cusp.

Monotone polygon

A polygon P is called **monotone** with respect to a direction r if, for every line r' orthogonal to r, the intersection $P \cap r'$ is connected (i.e., it is a segment, a point or the empty set).

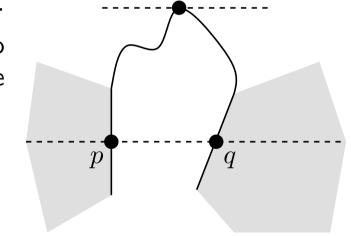
Local characterization

A polygon is y-monotone if and only if it does not have any cusp.

A **cusp** is a reflex vertex v of the polygon such that its two incident edges both lie to the same side of the horizontal line through v.

Proof:

If the polygon has a local maximum cusp v, an infinitesimal downwards translation of the horizontal line through v would intersect the polygon in at least two connected components.



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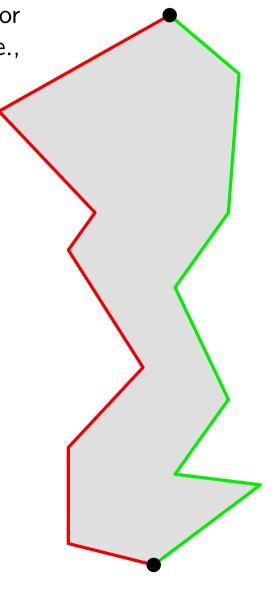
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Corollary

If a polygon is y-monotone, then it can be decomposed into two y-monotone non intersecting chains sharing their endpoints.



Triangulating a monotone polygon

Triangulating a monotone polygon

The vertices of the polygon P are processed by decreasing order of their y-coordinate.

Triangulating a monotone polygon

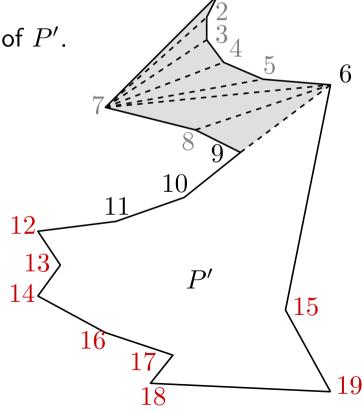
The vertices of the polygon P are processed by decreasing order of their y-coordinate.

During the process a queue Q is used to store the vertices that have already been visited but are still needed in order to generate the triangulation. Characteristics of Q:

- The topmost (i.e., largest y-coordinate) vertex in Q, is a convex vertex of the subpolygon P' still to be triangulated.

- All the remaining vertices in Q are reflex.

- All the vertices in Q belong to the same monotone chain of P'.



Triangulating a monotone polygon

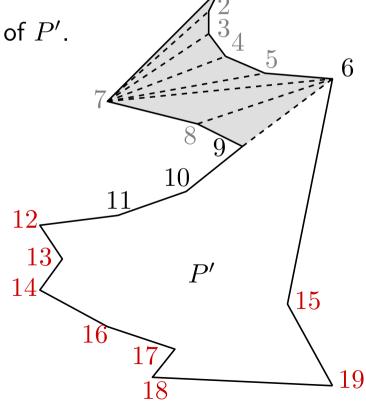
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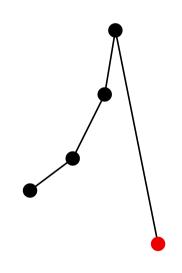
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Processing a vertex v_i :

• If v_i belongs to the opposite chain, report the diagonals connecting v_i to every vertex of Q and delete them all from Q, except the last one. Add v_i to Q.



Triangulating a monotone polygon

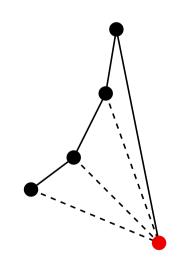
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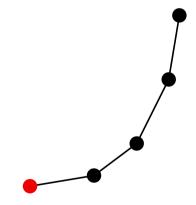
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- If v_i belongs to the opposite chain, report the diagonals connecting v_i to every vertex of Q and delete them all from Q, except the last one. Add v_i to Q.
- If v_i belongs to the same chain and produces a reflex turn, add v_i to Q.



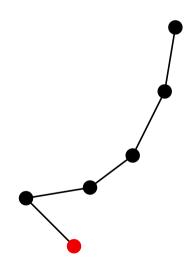
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- ullet If v_i belongs to the same chain and produces a reflex turn, add v_i to Q.
- If v_i belongs to the same chain and produces a convex turn, report the diagonal connecting v_i to the penultimate element of Q, delete the last element of Q and process v_i again.



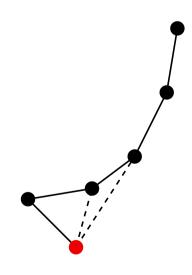
Triangulating a monotone polygon

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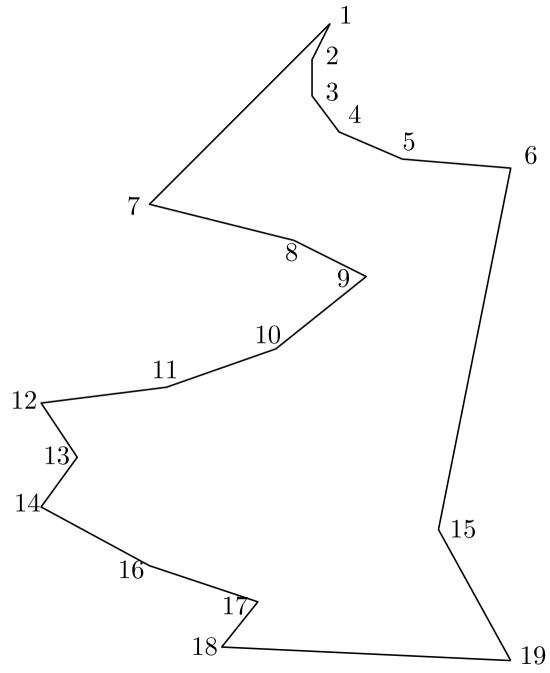
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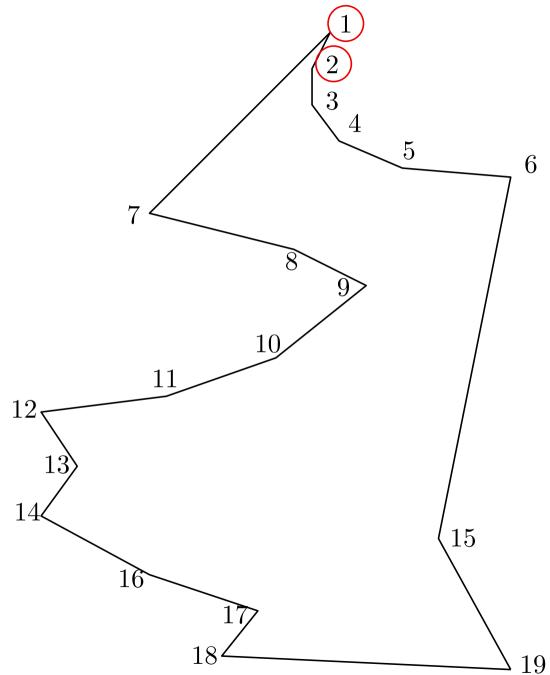
Triangulating a monotone polygon



Triangulating a monotone polygon

Start

Queue state



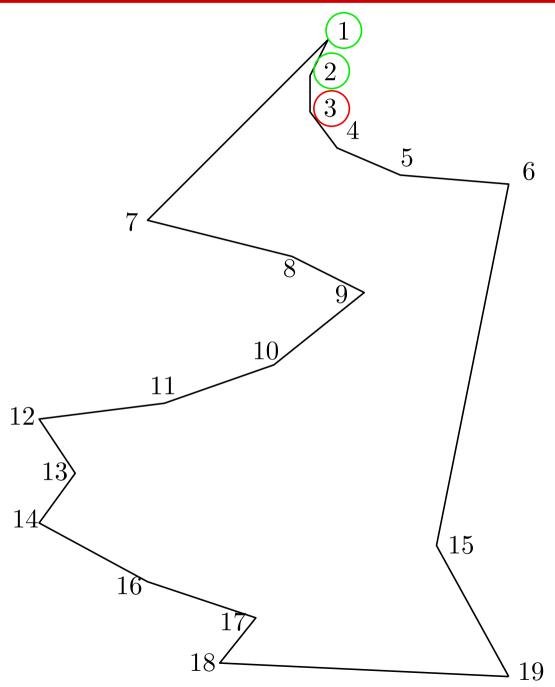
Triangulating a monotone polygon

Current vertex: 3

Add

Queue state:

1, 2, 3



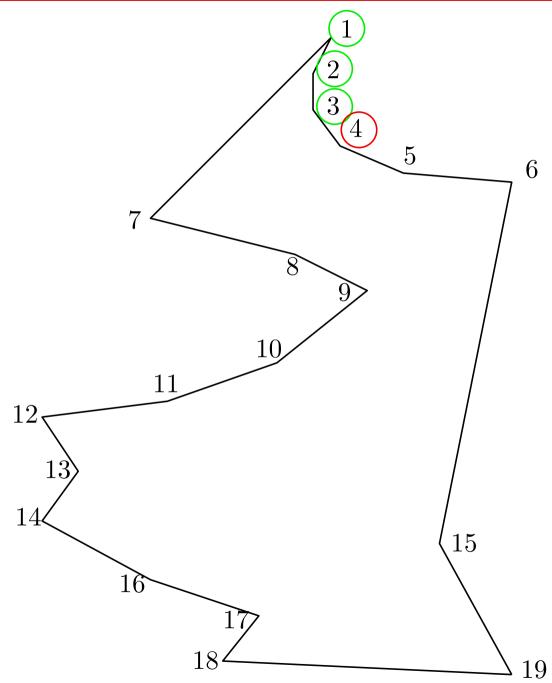
Triangulating a monotone polygon

Current vertex: 4

Add

Queue state:

1, 2, 3, 4



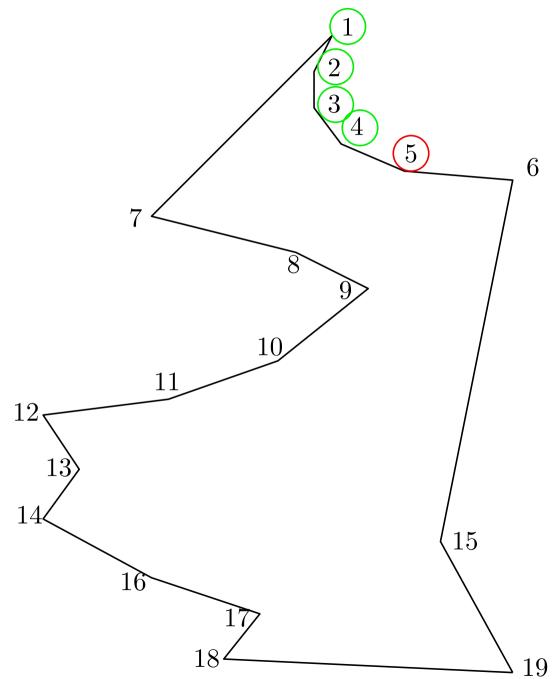
Triangulating a monotone polygon

Current vertex: 5

Add

Queue state:

1, 2, 3, 4, 5



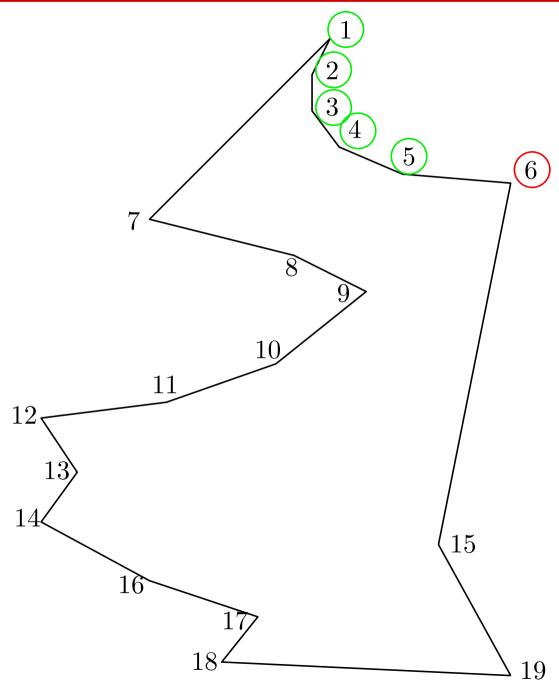
Triangulating a monotone polygon

Current vertex: 6

Add

Queue state:

1, 2, 3, 4, 5, 6

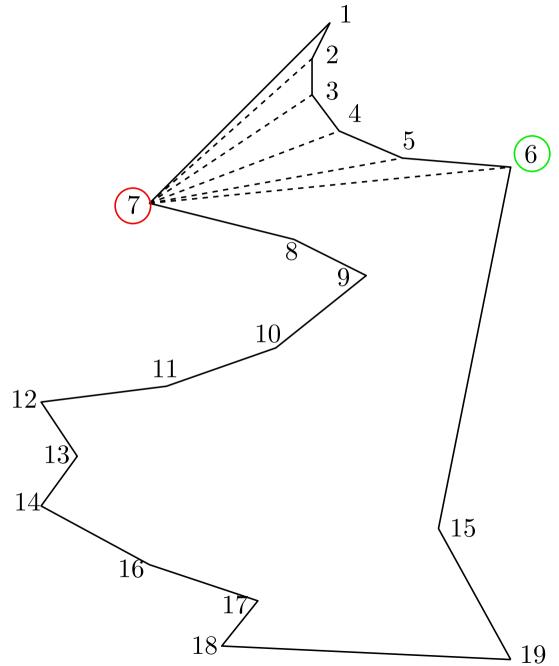


Triangulating a monotone polygon

Current vertex: 7

Opposite chain

Queue state:

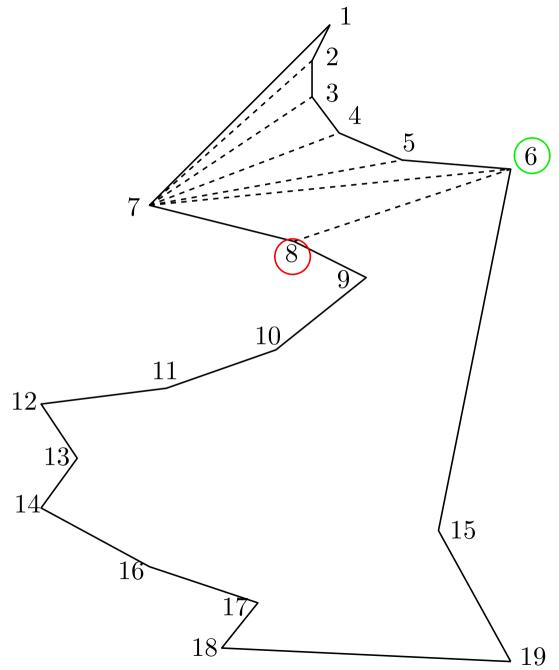


Triangulating a monotone polygon

Current vertex: 8

Ear

Queue state:

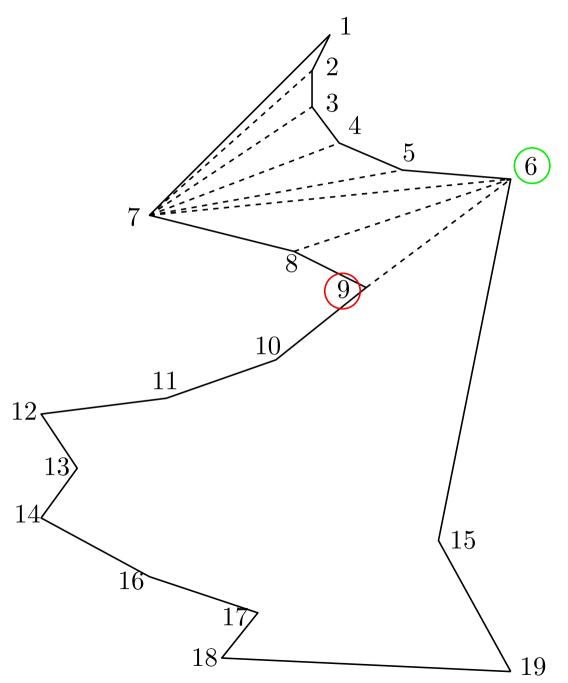


Triangulating a monotone polygon

Current vertex: 9

Ear

Queue state:



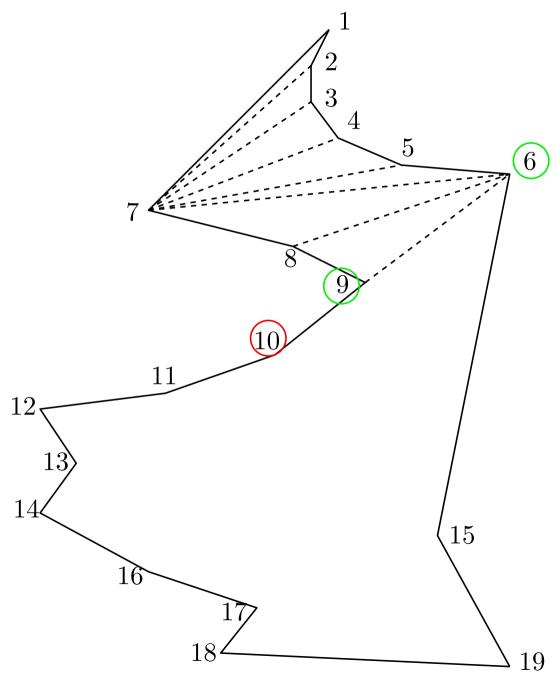
Triangulating a monotone polygon

Current vertex: 10

Add

Queue state:

6, 9, 10



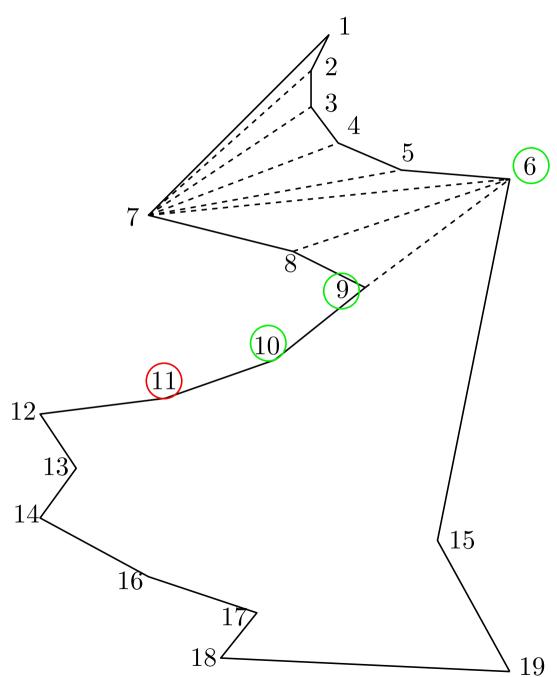
Triangulating a monotone polygon

Current vertex: 11

Add

Queue state:

6, 9, 10, 11



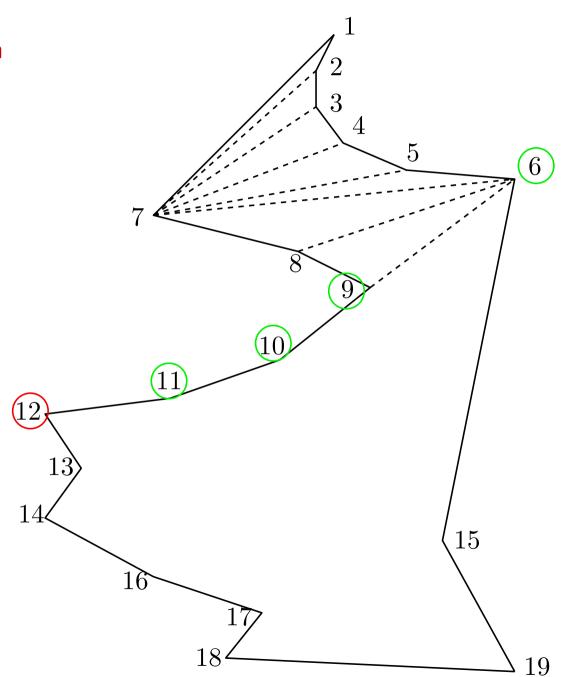
Triangulating a monotone polygon

Current vertex: 12

Add

Queue state:

6, 9, 10, 11, 12



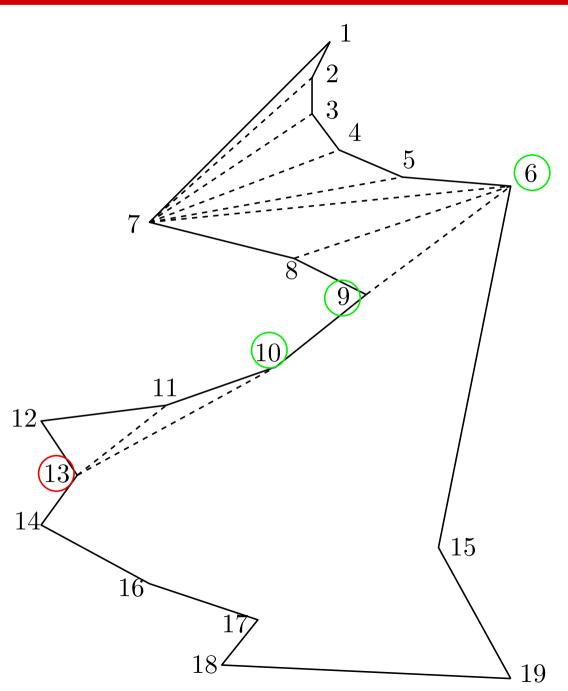
Triangulating a monotone polygon

Current vertex: 13

Ear

Queue state:

6, 9, 10, 13



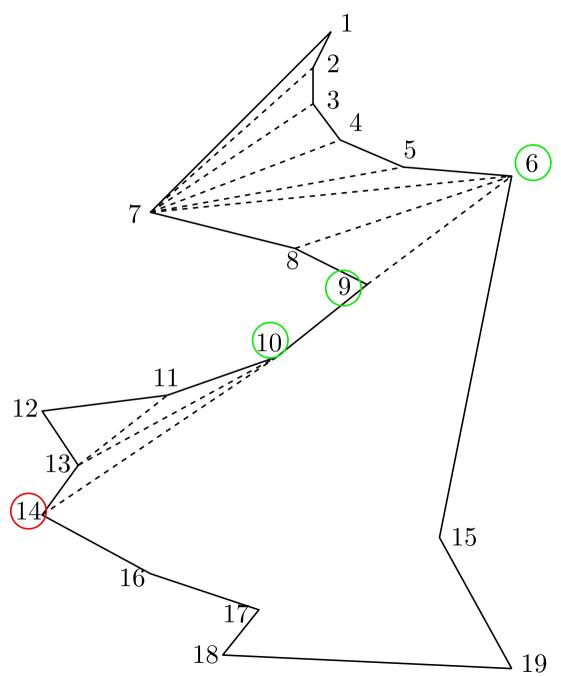
Triangulating a monotone polygon

Current vertex: 14

Ear

Queue state:

6, 9, 10, 14

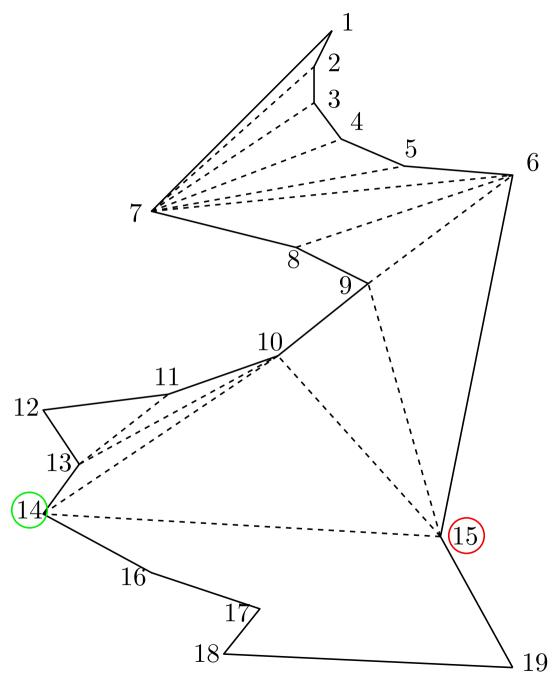


Triangulating a monotone polygon

Current vertex: 15

Opposite chain

Queue state:

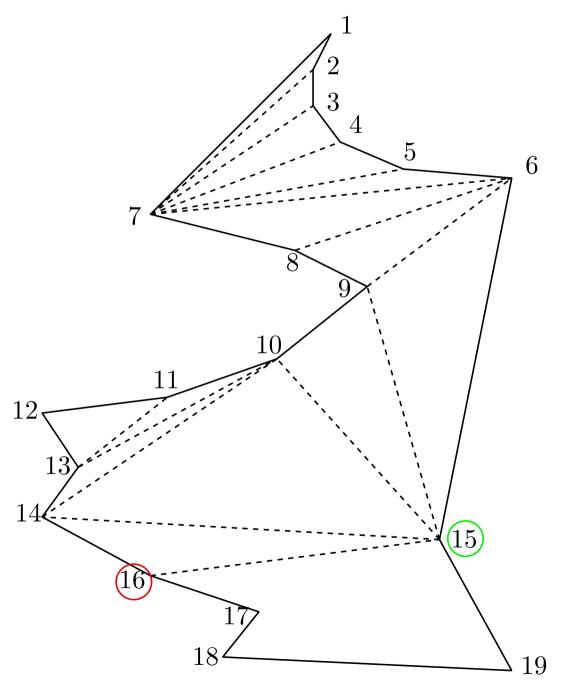


Triangulating a monotone polygon

Current vertex: 16

Opposite chain

Queue state:

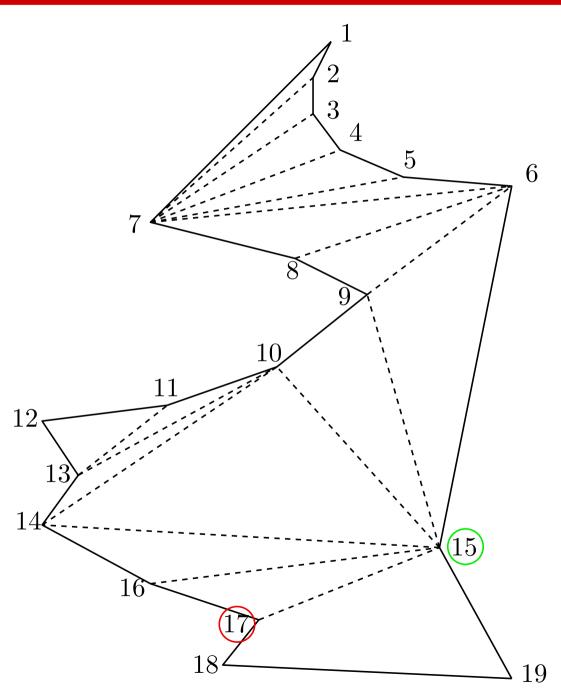


Triangulating a monotone polygon

Current vertex: 17

Ear

Queue state:

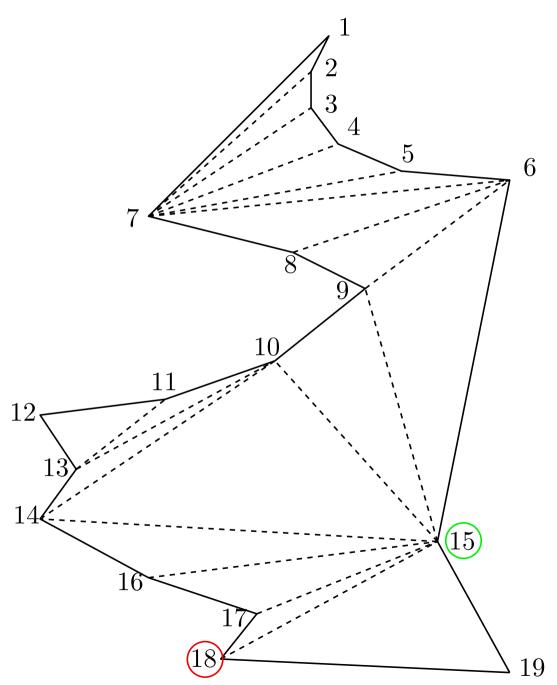


Triangulating a monotone polygon

Current vertex: 18

Ear

Queue state:

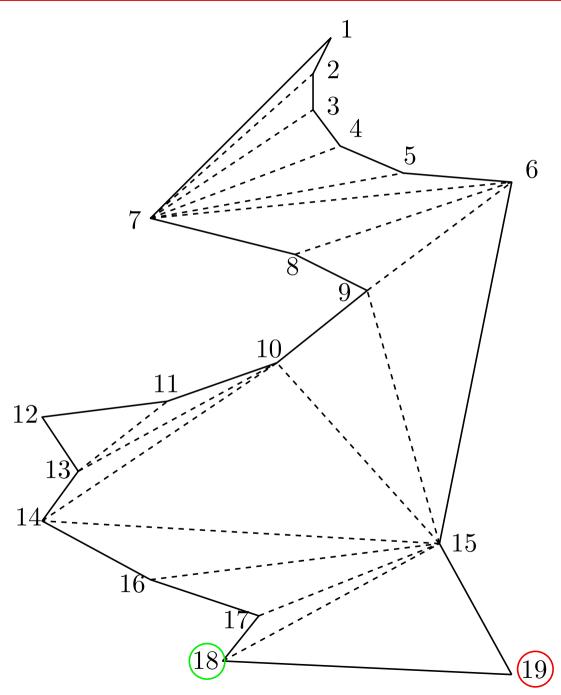


Triangulating a monotone polygon

Current vertex: 19

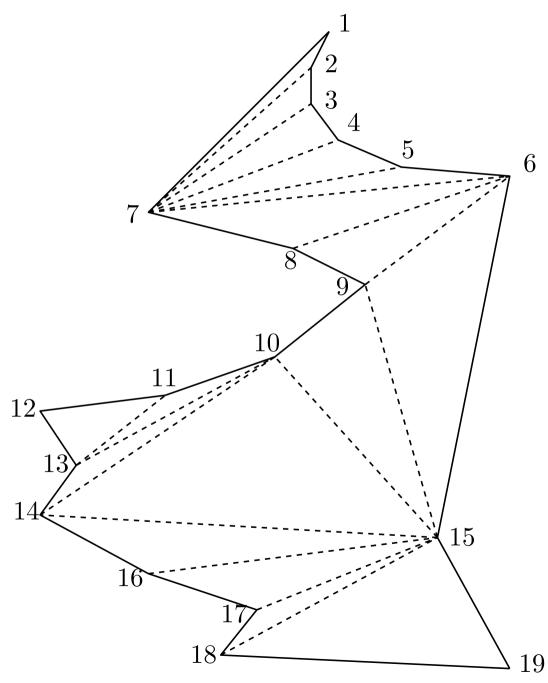
Opposite chain

Queue state:



Triangulating a monotone polygon

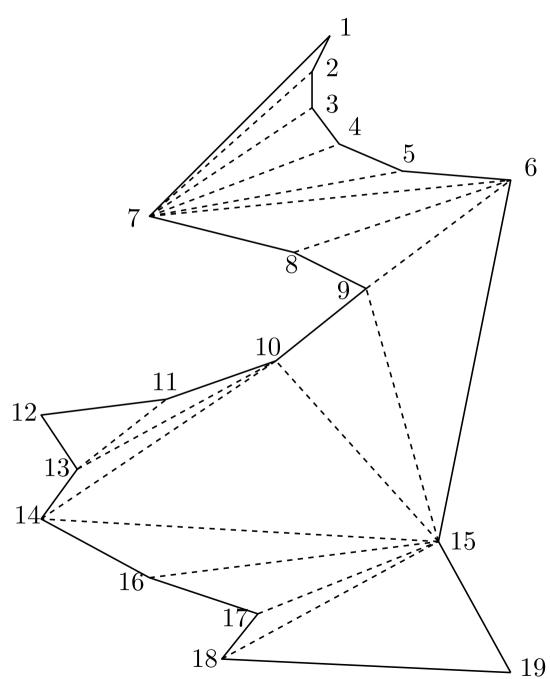
End



Triangulating a monotone polygon

Running time: O(n)

Each vertex is removed from the queue Q in O(1) time.



Summarizing

Running time for triangulating a polygon:

- $O(n^2)$ by subtracting ears
- $O(n^2)$ by inserting diagonals

If the polygon is convex:

• O(n) trivially

If the polygon is monotone:

ullet O(n) scanning the monotone chains in order

Summarizing

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Is it possible to be more efficient more general polygons?

Summarizing

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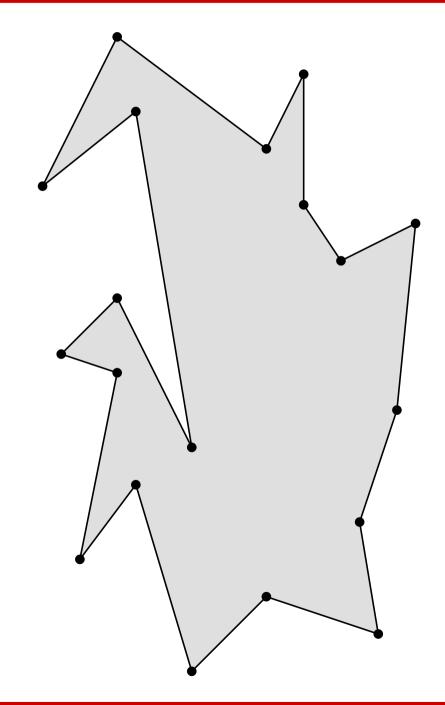
If the polygon is monotone:

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Is it possible to be more efficient more general polygons? Yes!

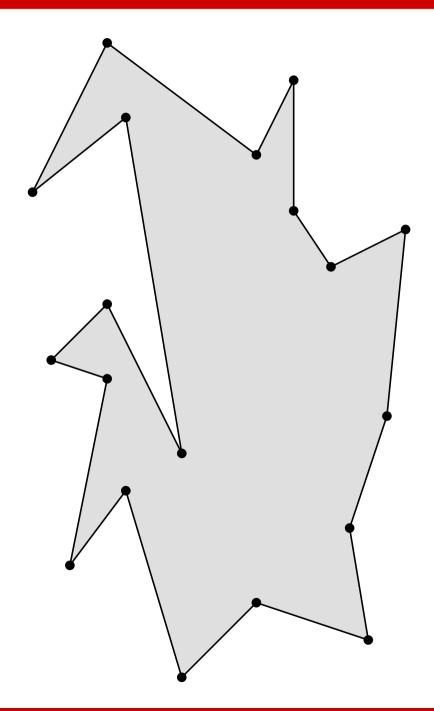
- 1. Decompose the polygon into monotone subpolygons
- 2. Triangulate the monotone subpolygons

Monotone partition



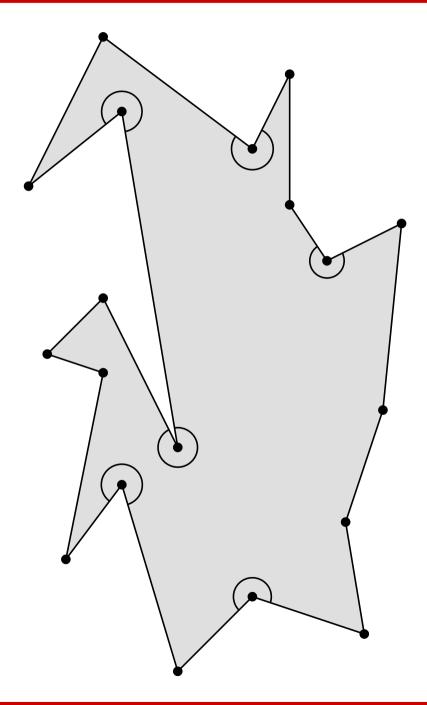
Monotone partition

In order to create a monotone partition of a polygon, all cusps need to be "broken" by internal diagonals.



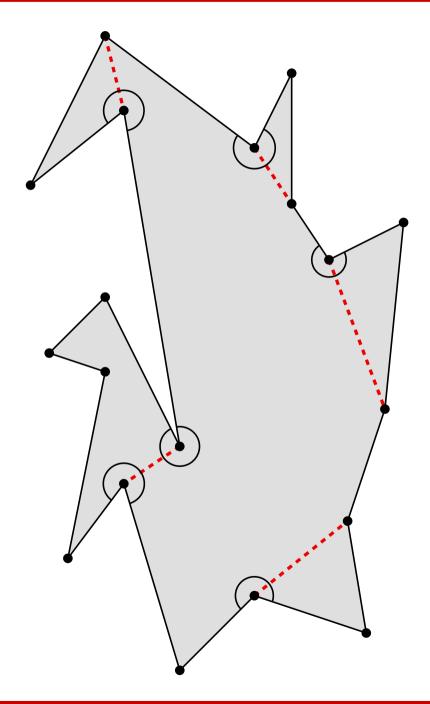
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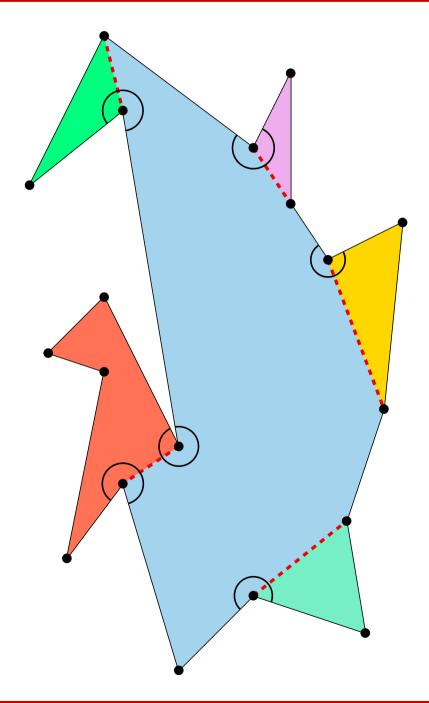
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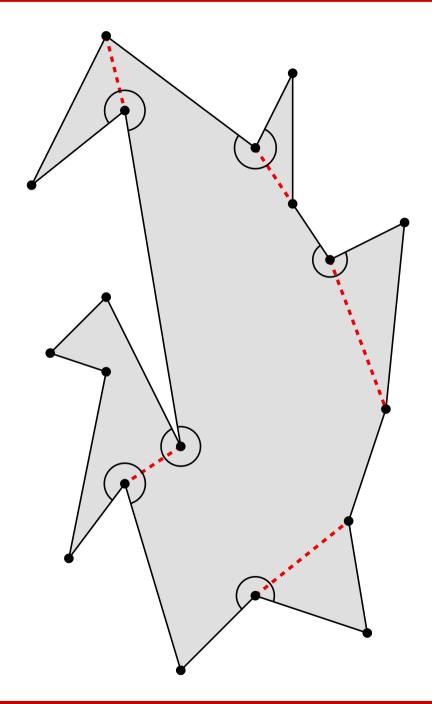
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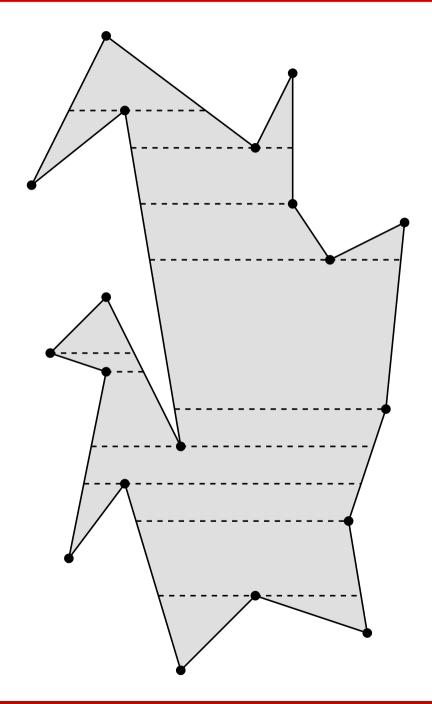
This can be done starting from a **trapezoidal decomposition** of the polygon.



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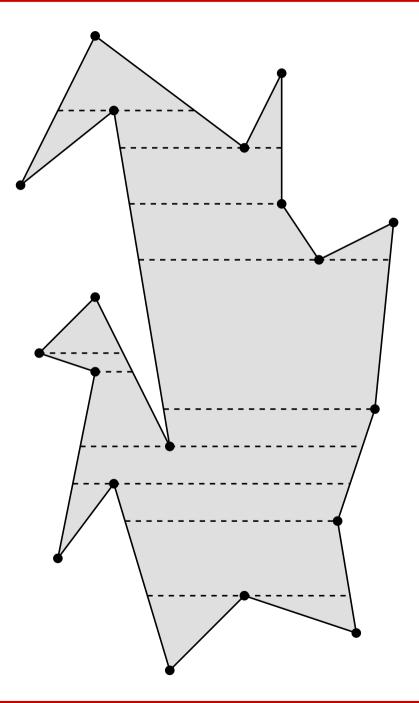
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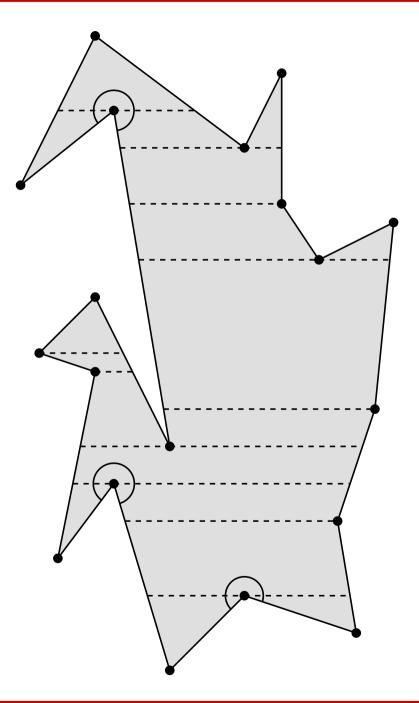
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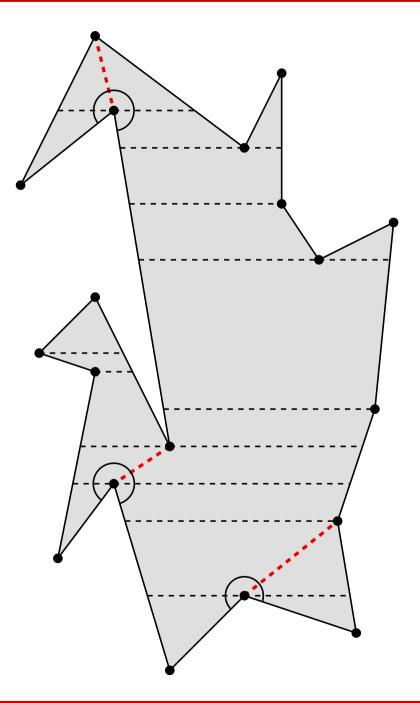
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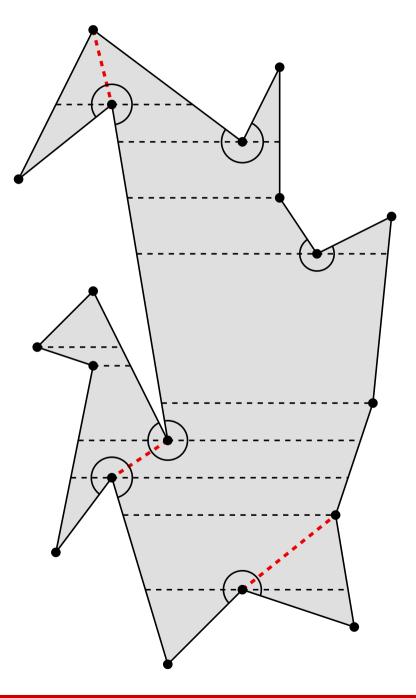
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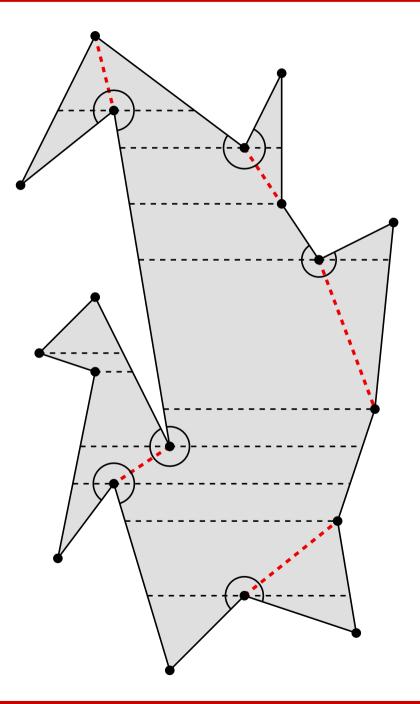
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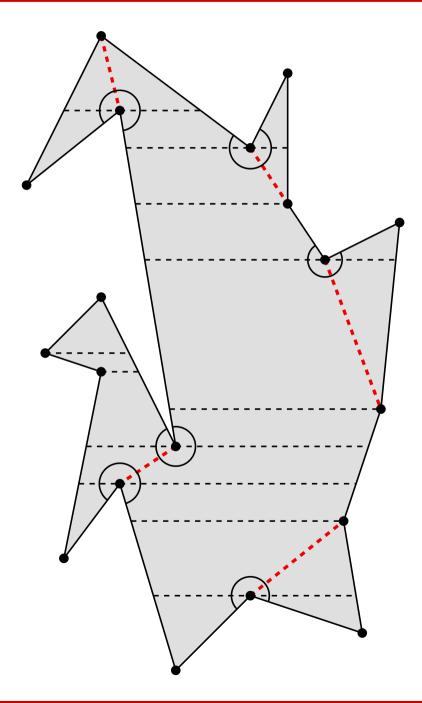
This can be done starting from a **trapezoidal decomposition** of the polygon.

Connect each cusp with the opposite vertex in its trapezoid (the upper trapezoid, if the cusp is a local maximum, the lower one, if it is a local minimum).

This gives rise to a correct algorithm:

- The diagonals do not intersect, because they belong to different trapezoids.
- The polygon ends up decomposed into monotone subpolygons.

Sweep line algorithm



Monotone partition

Sweep line algorithm

Monotone partition

Sweep line algorithm

A straight line (horitzontal, in this case) scans the object (the polygon) and allows detecting and constructing the desired elements (cusps, trapezoids, diagonals), leaving the problem solved behind it. The sweeping process is discretized.

Monotone partition

Sweep line algorithm

A straight line (horitzontal, in this case) scans the object (the polygon) and allows detecting and constructing the desired elements (cusps, trapezoids, diagonals), leaving the problem solved behind it. The sweeping process is discretized.

Essential elements of a sweep line algorithm:

• Events queue

Priority queue keeping the information of the algorithm stops. In our problem, the events will be the vertices of the polygon, sorted by their y-coordinate, all known in advance.

Sweep line

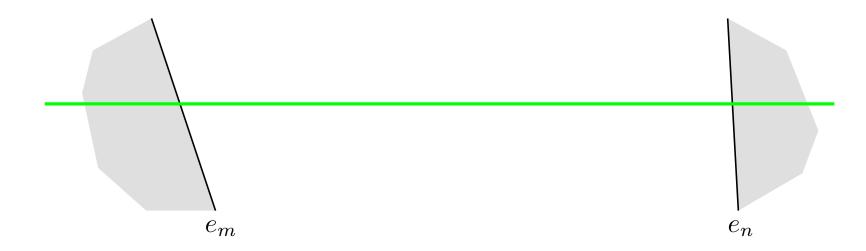
Data structure storing the information of the portion of the object intersected by the sweep line. It gets updated at each event. In our problem, it will contain the information of the edges of the polygon intersected by the sweep line, sorted by abscissa, as well as the list of active trapezoids and ther upper vertex.

Monotone partition

- Passing vertex: replace
- Local minimum cusp: delete
- Local maximum cusp: insert
- Initial vertex: insert
- Final vertex: delete

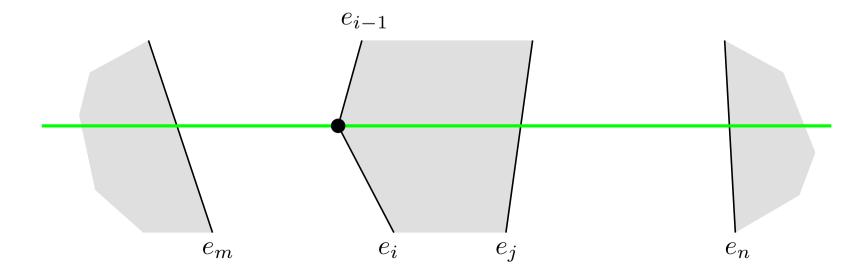
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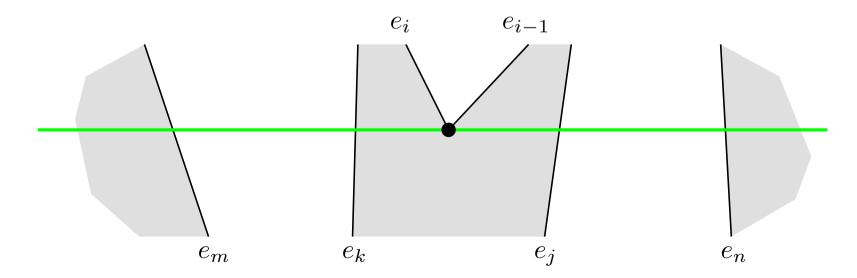
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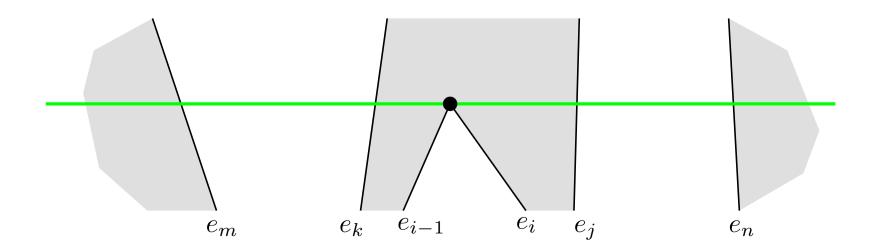
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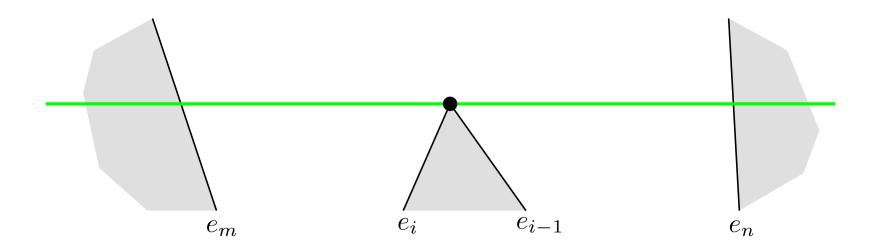
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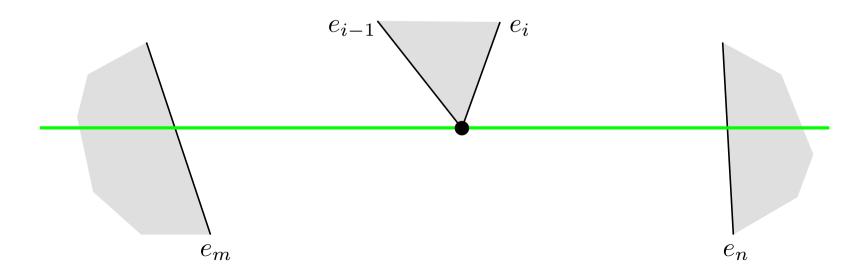
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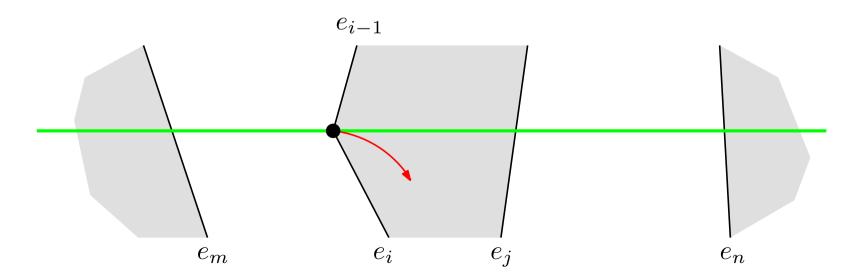
Updating the sweep line:

- Passing vertex: replace
- Local minimum cusp: delete
- Local maximum cusp: insert
- Initial vertex: insert
- Final vertex: delete

Monotone partition

Updating the sweep line:

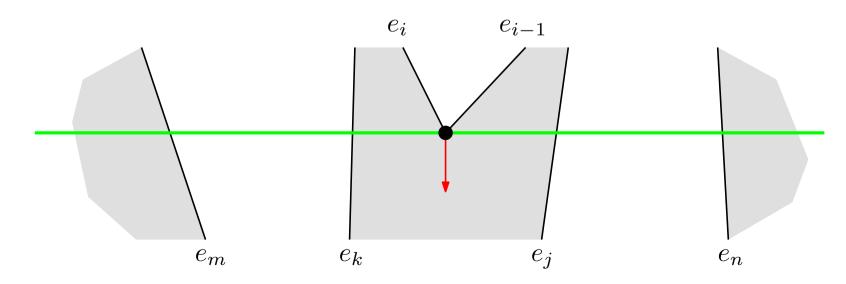
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Monotone partition

Updating the sweep line:

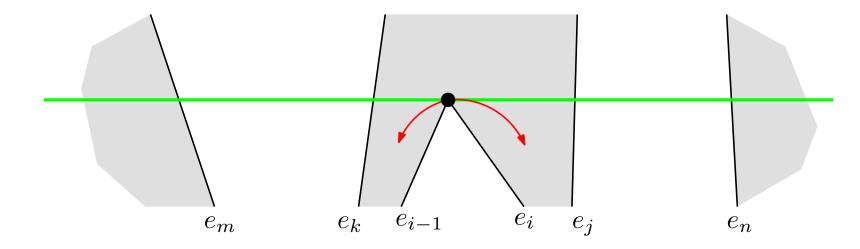
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Monotone partition

Updating the sweep line:

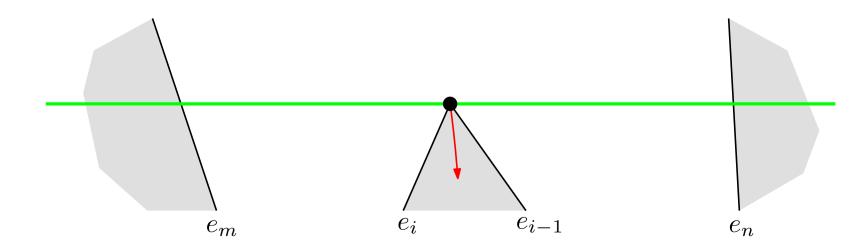
- Passing vertex: replace
- Local minimum cusp: delete
- Local maximum cusp: insert
- Initial vertex: insert
- Final vertex: delete



Monotone partition

Updating the sweep line:

- Passing vertex: replace
- Local minimum cusp: delete
- Local maximum cusp: insert
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Monotone partition

Updating the sweep line:

- Passing vertex: replace
- Local minimum cusp: delete
- Local maximum cusp: insert
- Initial vertex: insert
- Final vertex: delete

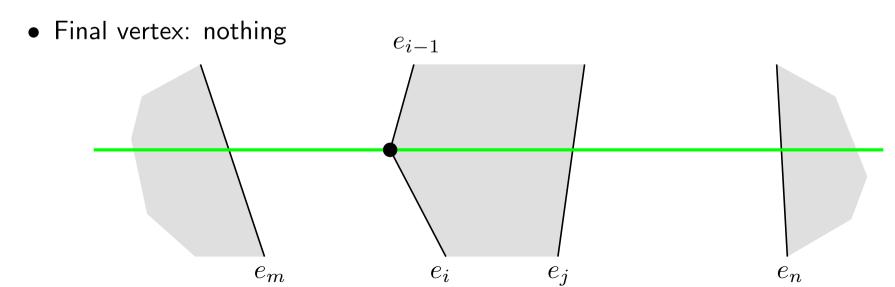
 e_{i-1} e_i e_m e_n

Monotone partition

- Passing vertex: nothing
- Local minimum cusp: wait until it can be connect to the final vertex of the starting trapezoid
- Local maximum cusp: connect it with the initial vertex of the ending trapezoid
- Initial vertex: nothing
- Final vertex: nothing

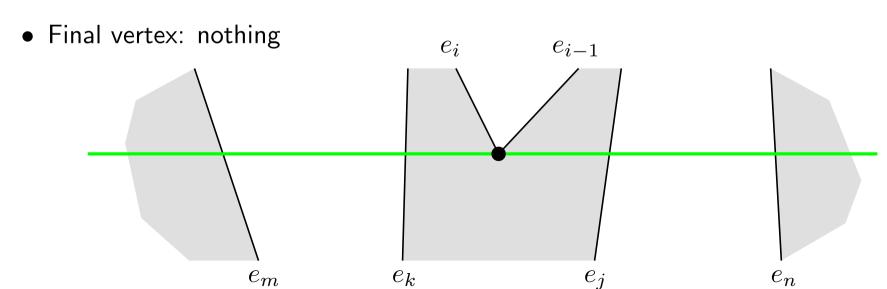
Monotone partition

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- Local maximum cusp: connect it with the initial vertex of the ending trapezoid
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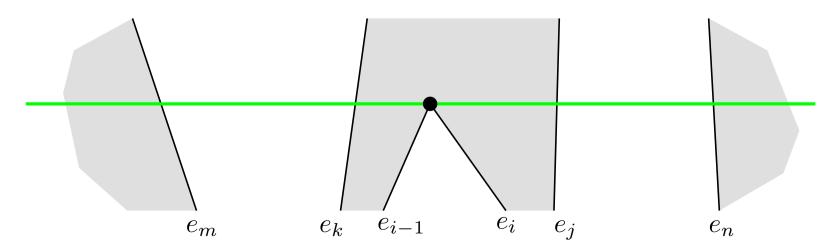
Monotone partition

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- Local minimum cusp: wait until it can be connect to the final vertex of the starting trapezoid
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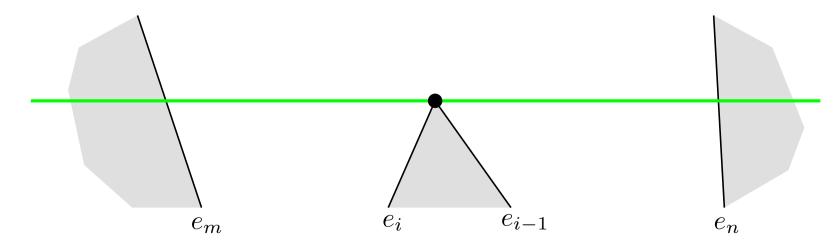
Monotone partition

- Passing vertex: nothing
- Local minimum cusp: wait until it can be connect to the final vertex of the starting trapezoid
- Local maximum cusp: connect it with the initial vertex of the ending trapezoid
- Initial vertex: nothing
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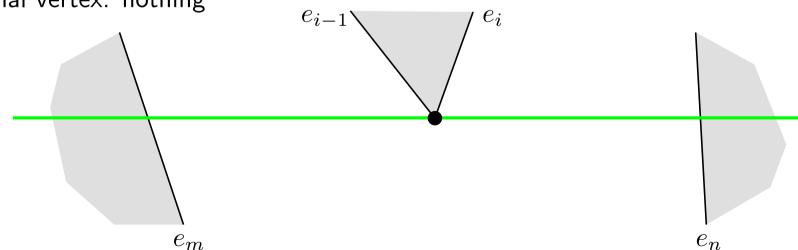
Monotone partition

- Passing vertex: nothing
- Local minimum cusp: wait until it can be connect to the final vertex of the starting trapezoid
- Local maximum cusp: connect it with the initial vertex of the ending trapezoid
- Initial vertex: nothing
- Final vertex: nothing



Monotone partition

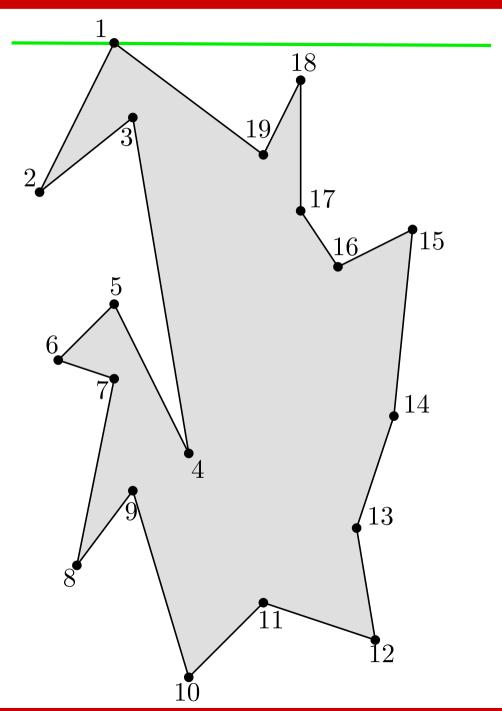
- Passing vertex: nothing
- Local minimum cusp: wait until it can be connect to the final vertex of the starting trapezoid
- Local maximum cusp: connect it with the initial vertex of the ending trapezoid
- Initial vertex: nothing
- Final vertex: nothing



Monotone partition

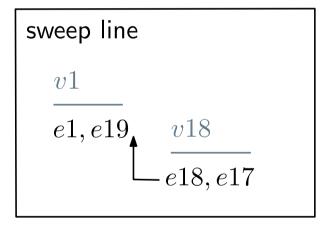
vertex 1

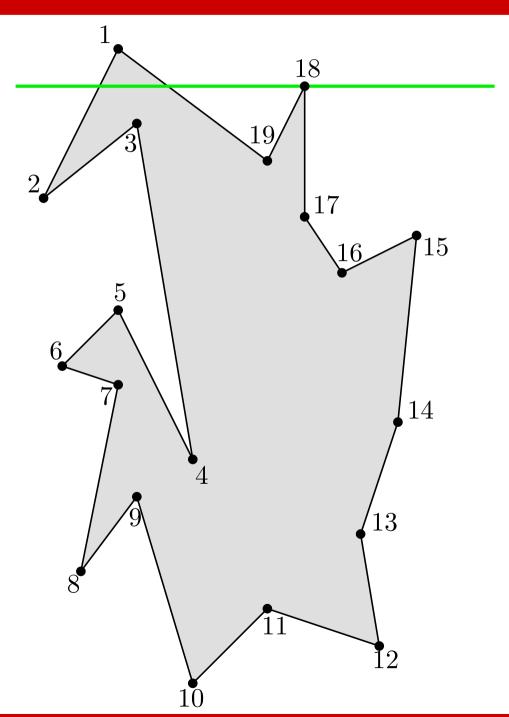
sweep line $\dfrac{v1}{e1,e19}$



Monotone partition

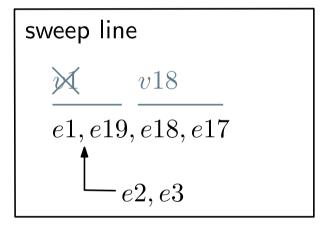
vertex 18

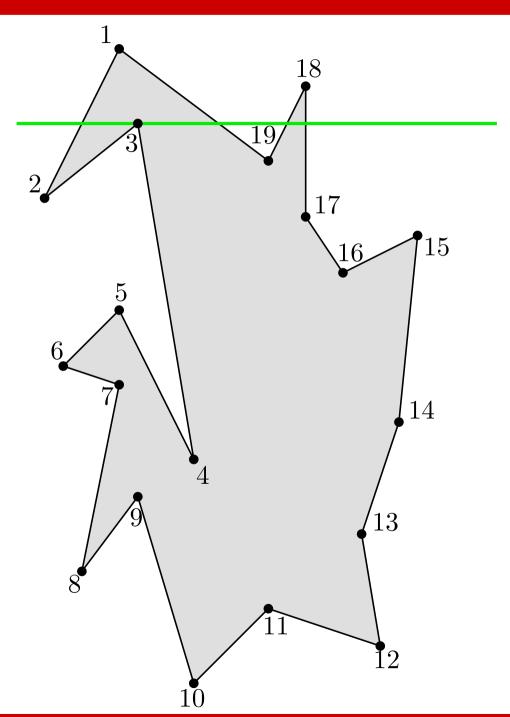




Monotone partition

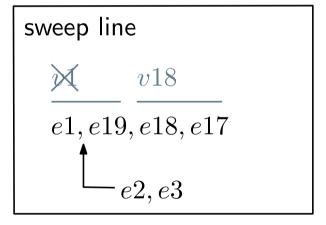
vertex 3



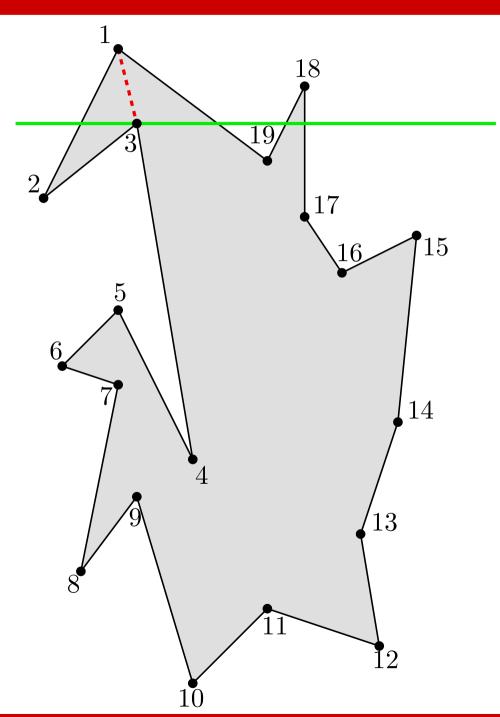


Monotone partition

vertex 3



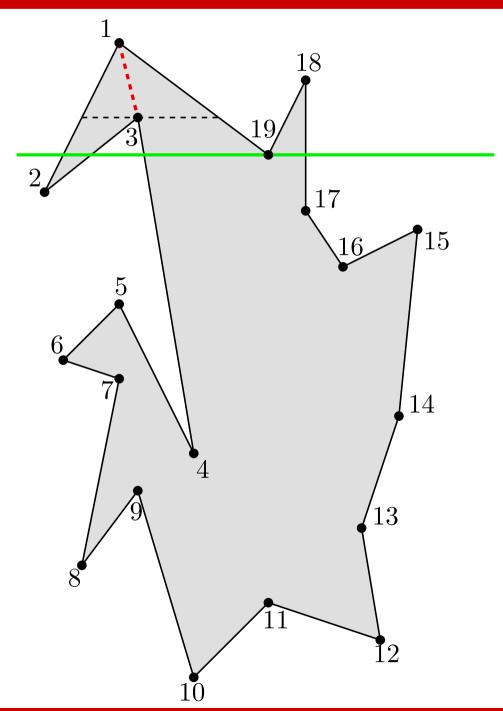
Diagonal v1-v3



Monotone partition

vertex 19

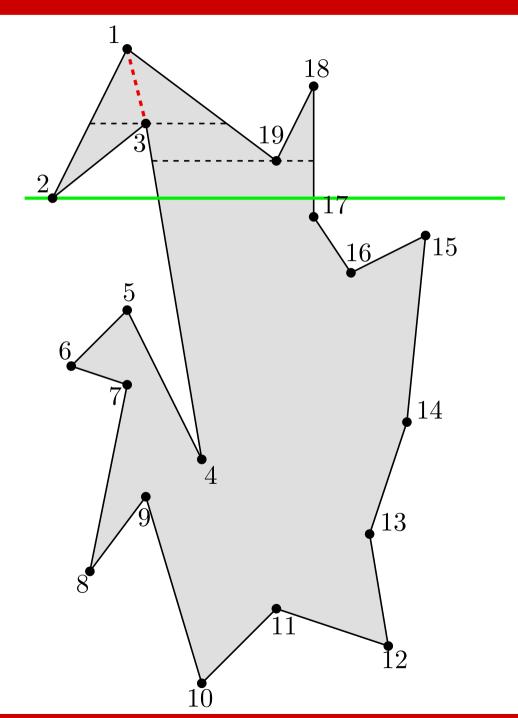
sweep line $\frac{v3}{e1,e2}, \underbrace{\cancel{\cancel{3}}}_{e3}, \underbrace{\cancel{\cancel{\cancel{3}}}}_{\cancel{\cancel{2}}}, \underbrace{\cancel{\cancel{\cancel{3}}}}_{\cancel{\cancel{2}}}, \underbrace{\cancel{\cancel{2}}}_{\cancel{\cancel{2}}}, \underbrace{\cancel{\cancel{2}}}_{\cancel{\cancel{$



Monotone partition

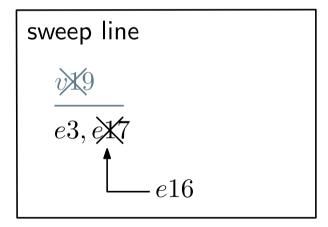
vertex 2

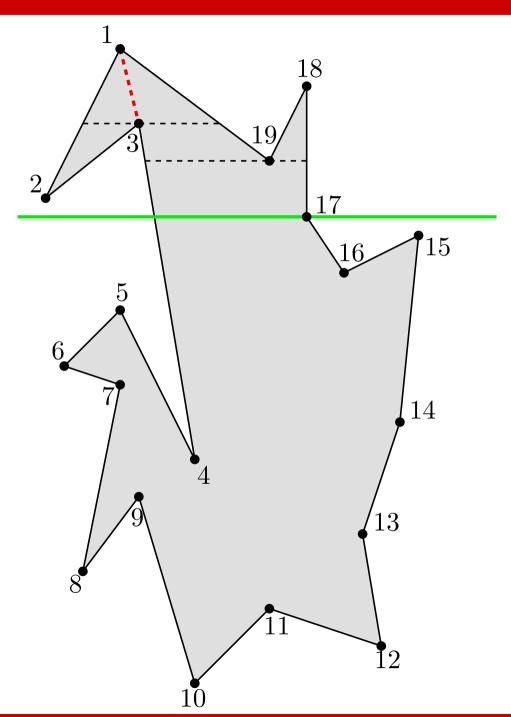
sweep line
$$\frac{v3}{\cancel{\lambda},\cancel{e}\cancel{\lambda}}, \frac{v19}{e3,e17}$$



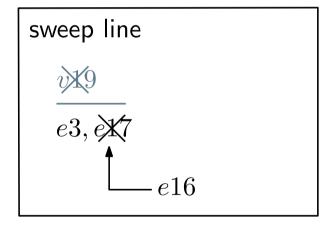
Monotone partition

vertex 17

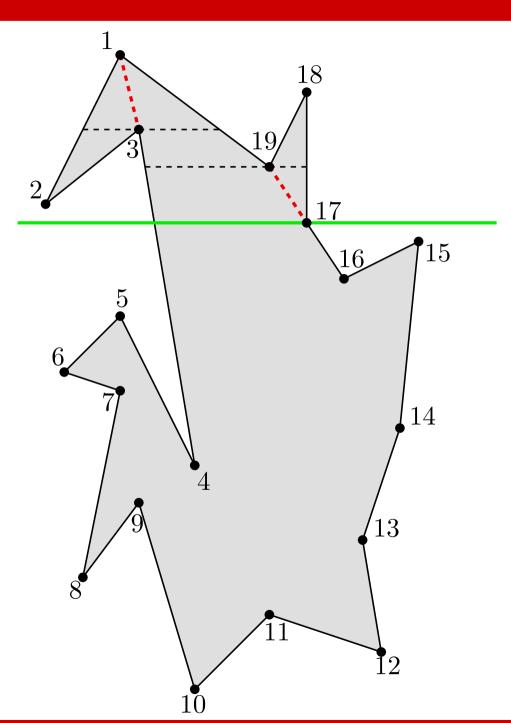






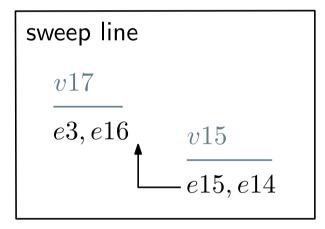


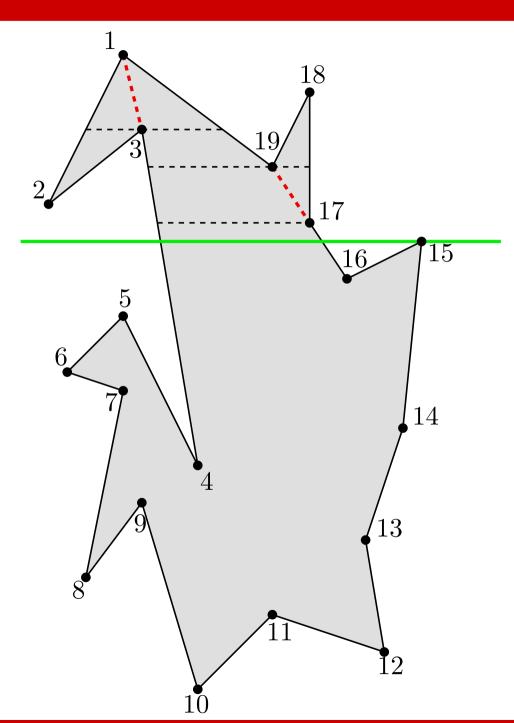
Diagonal v19 - v17



Monotone partition

vertex 15



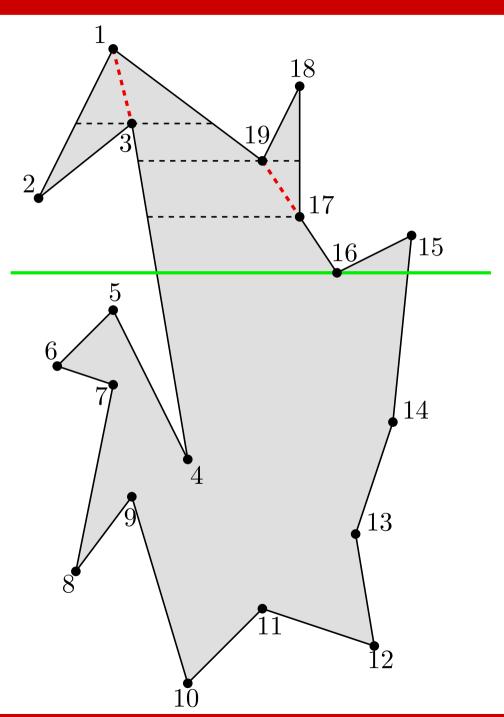


Monotone partition

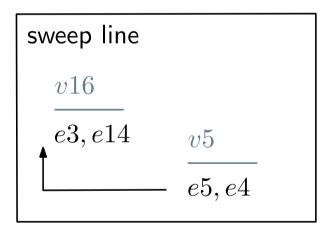
vertex

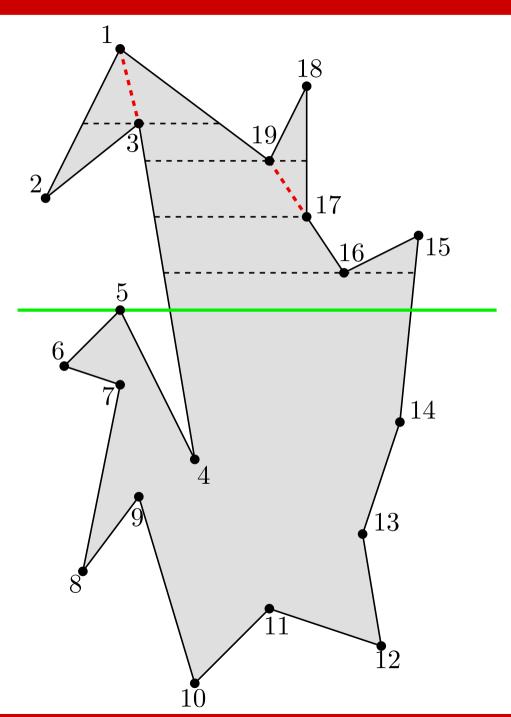
16

sweep line

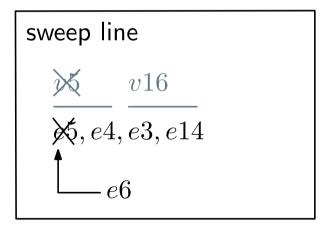


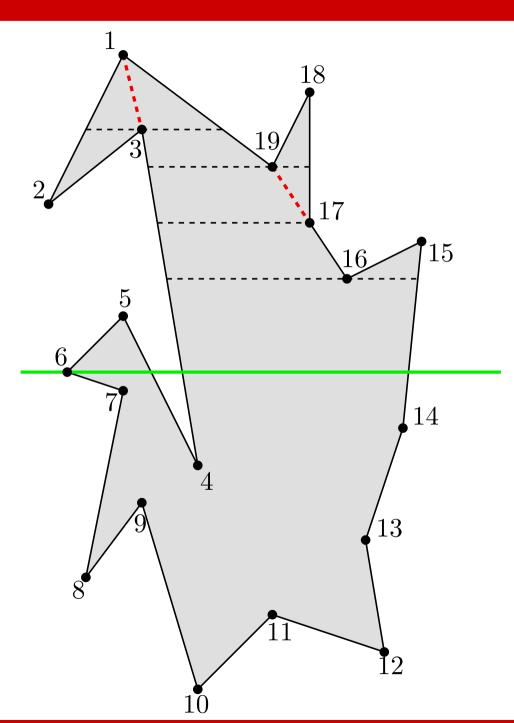




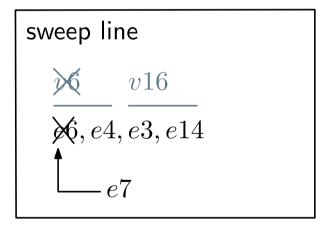


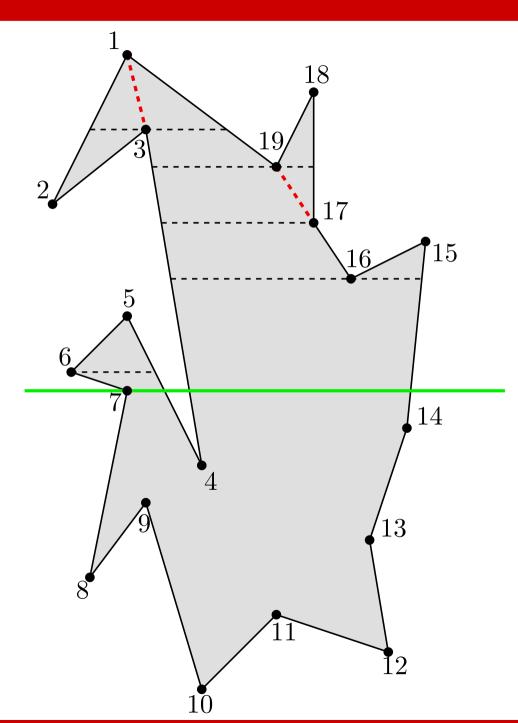




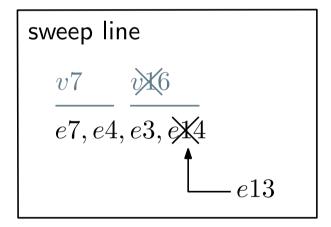


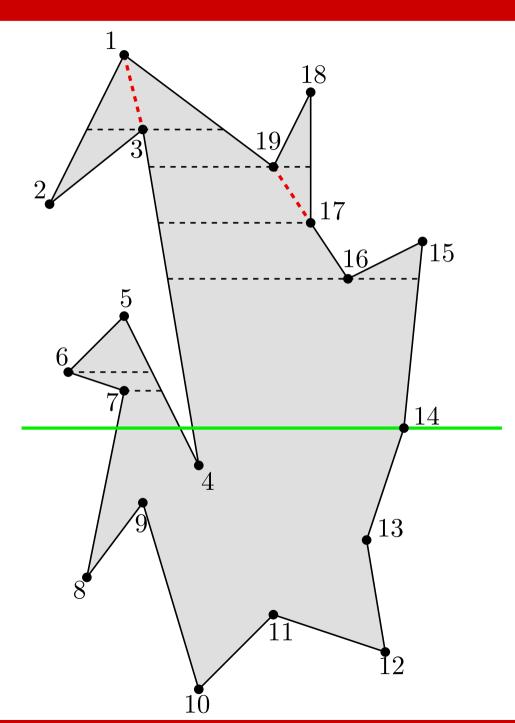






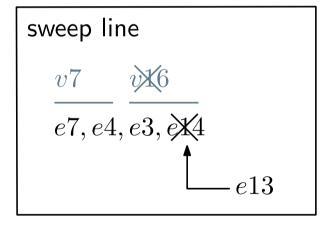




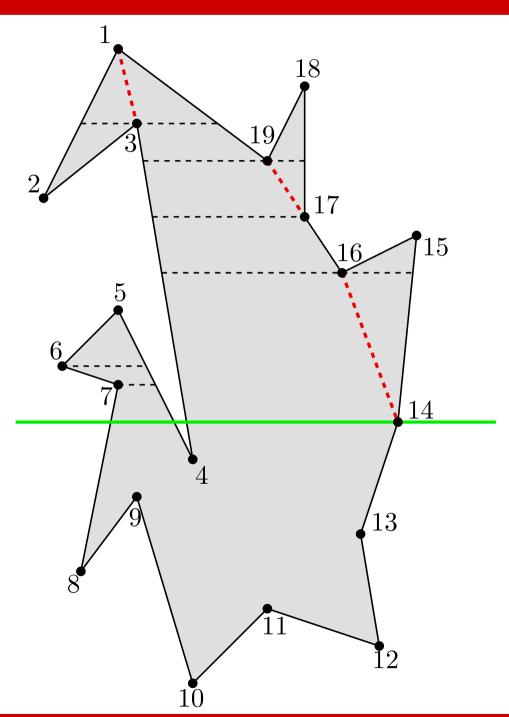


Monotone partition

vertex 14



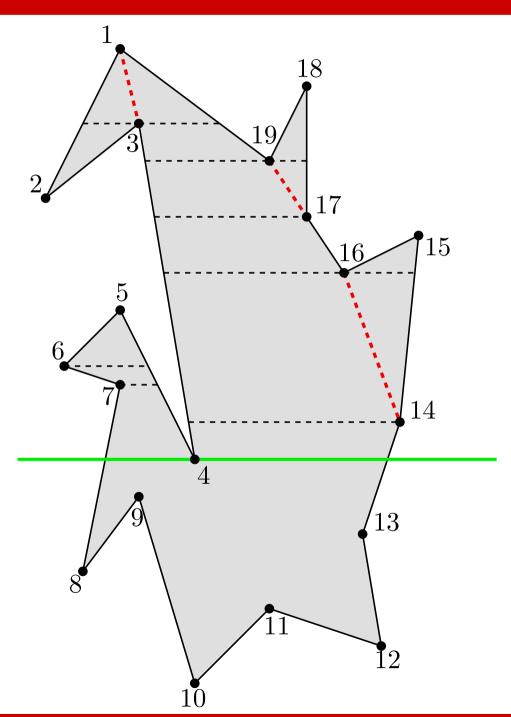
Diagonal v16 - v14



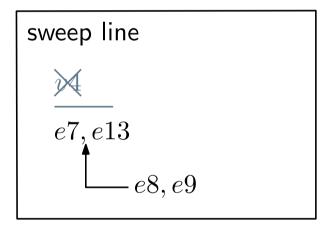
Monotone partition

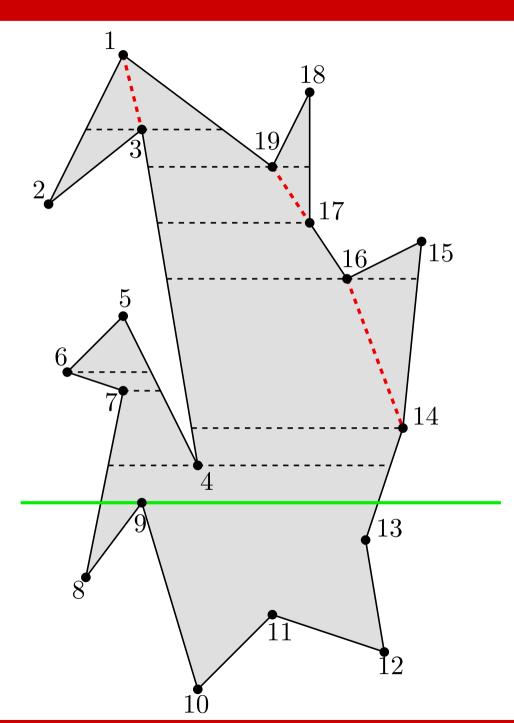
vertex 4

sweep line $\frac{\cancel{\cancel{2}}}{e7,\cancel{\cancel{4}}}, \cancel{\cancel{\cancel{3}}}, e13$

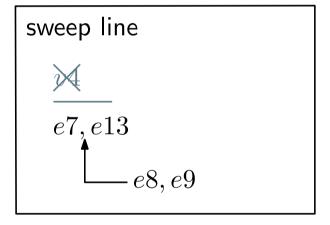




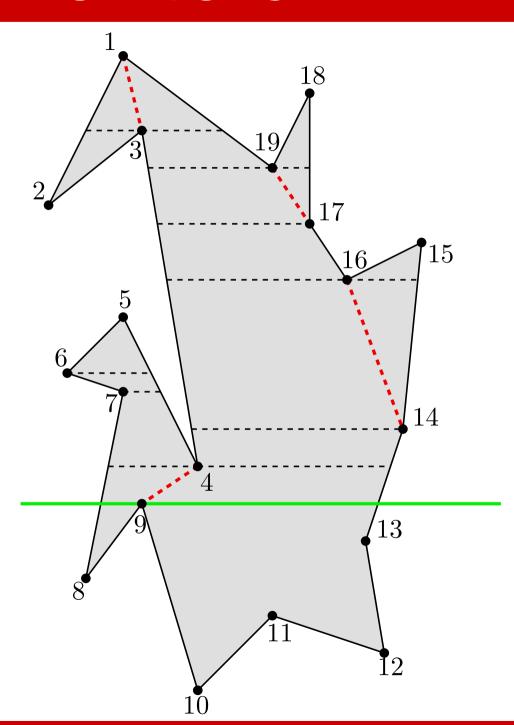






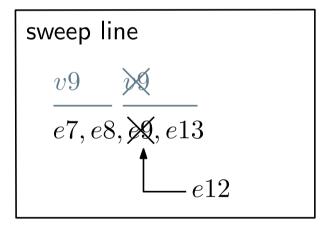


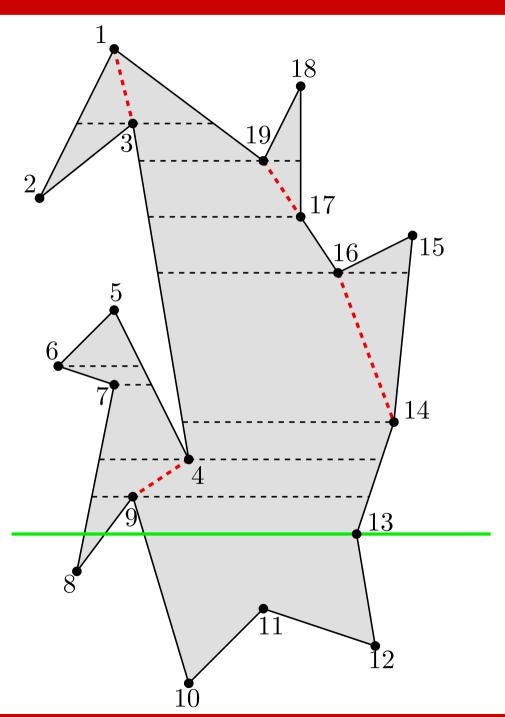
Diagonal v4 - v9



Monotone partition

vertex 13

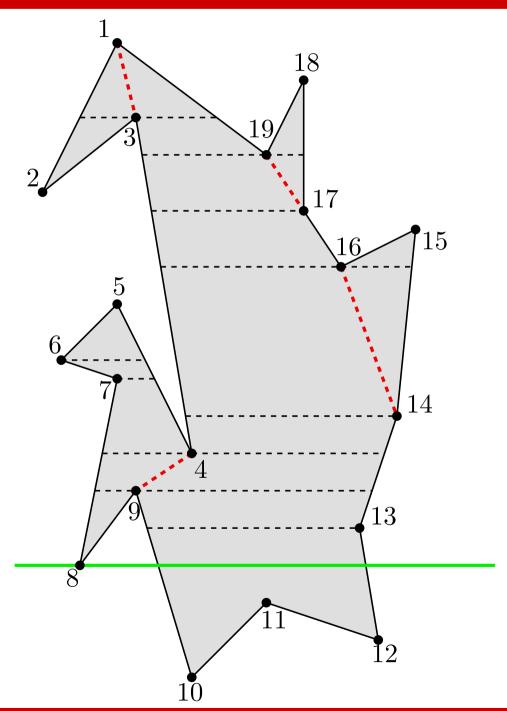




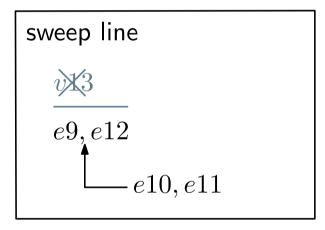
Monotone partition

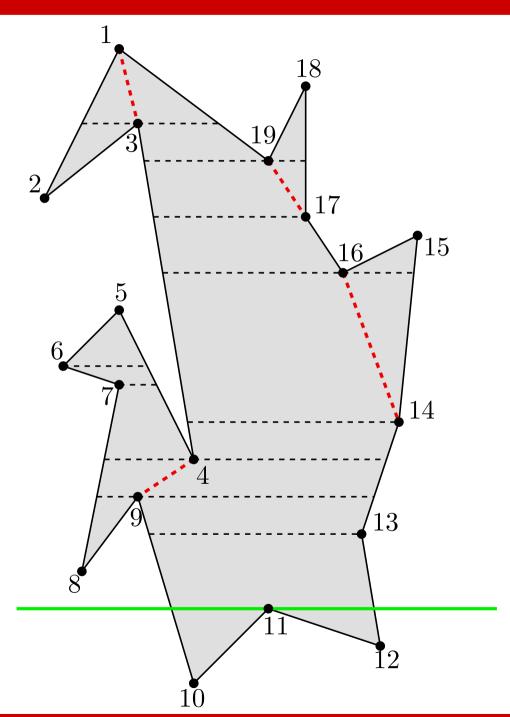
vertex 8

sweep line $\frac{v9}{\cancel{\times},\cancel{\otimes},e9,e12}$

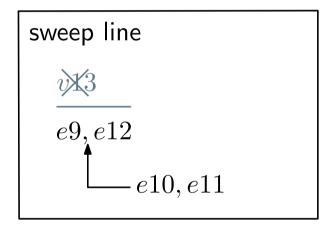




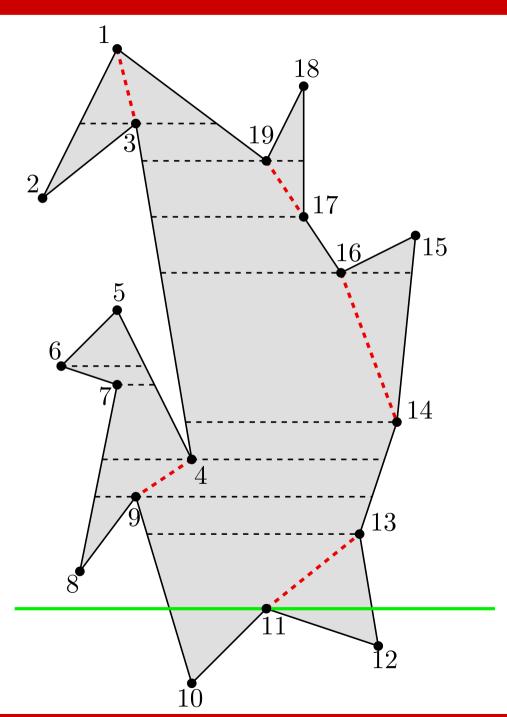








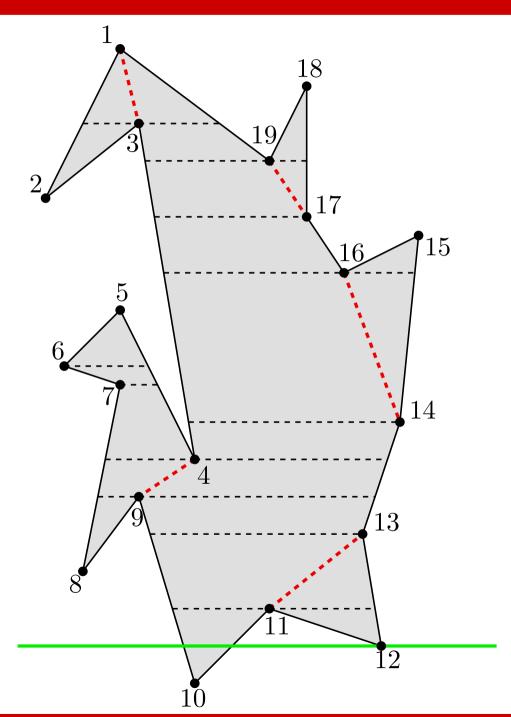
 ${\sf Diagonal}\ v13-v11$



Monotone partition

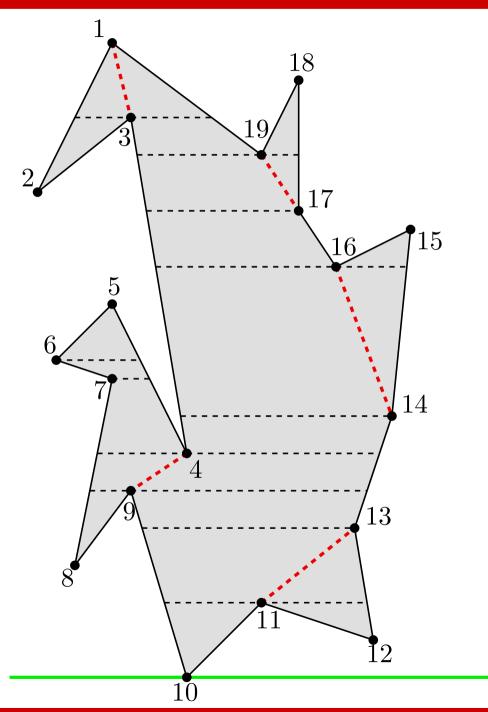
vertex 12

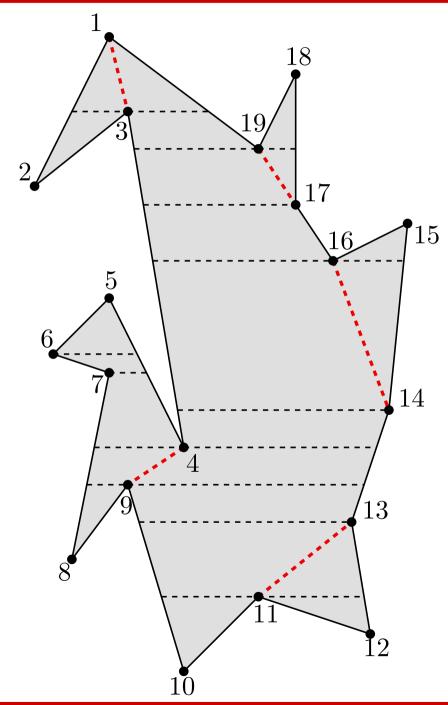
sweep line $\frac{v11}{e9, e10}, \frac{v11}{e^{2}}$

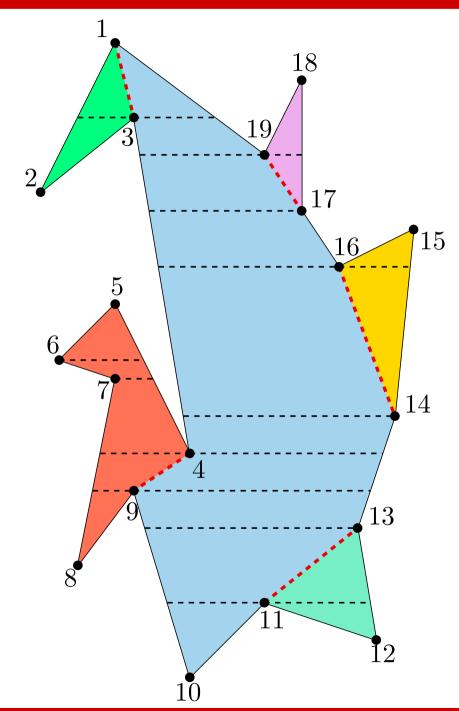


Monotone partition

vertex 10





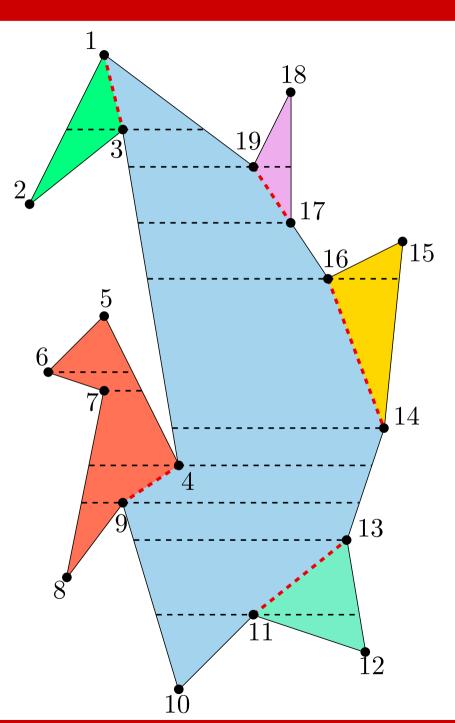


Monotone partition

Running time:

- Sorting the vertices in the event queue: $O(n \log n)$ time.
- On each event, update sweep line: replace, insert or delete vertices or edges in $O(\log n)$ time each.
- There are n events.

The algorithm runs in $O(n \log n)$ time.



Summarizing

Running time of polygon triangulation:

- $O(n^2)$ by substracting ears
- $O(n^2)$ by inserting diagonals
- $O(n \log n)$ by:
 - 1. Decomposing the polygon into monotone subpolygons in $O(n \log n)$ time
 - 2. Triangulating each monotone subpolygon in O(n) time

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Is it possible to triangulate a polygon in $o(n \log n)$ time?

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Is it possible to triangulate a polygon in $o(n \log n)$ time?

Yes.

There exists an algorithm to triangulate an n-gon in O(n) time, but it is too complicated and, in practice, it is not used.

STORING THE POLYGON TRIANGULATION

Possible options, advantages and disadvantages

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Storing the list of all the diagonals of the triangulation

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Advantage: small memory usage.

Disadvantage: it suffices to draw the triangulation, but it does not contain the proximity information. For example, finding the triangles incident to a given diagonal, or finding the neighbors of a given triangle are expensive computations.

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For each triangle, storing the sorted list of its vertices and edges, as well as the sorted list of its neighbors.

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Advantage: allows to quickly recover neighborhood information.

Disadvantage: the stored data is redundant and it uses more space than required.

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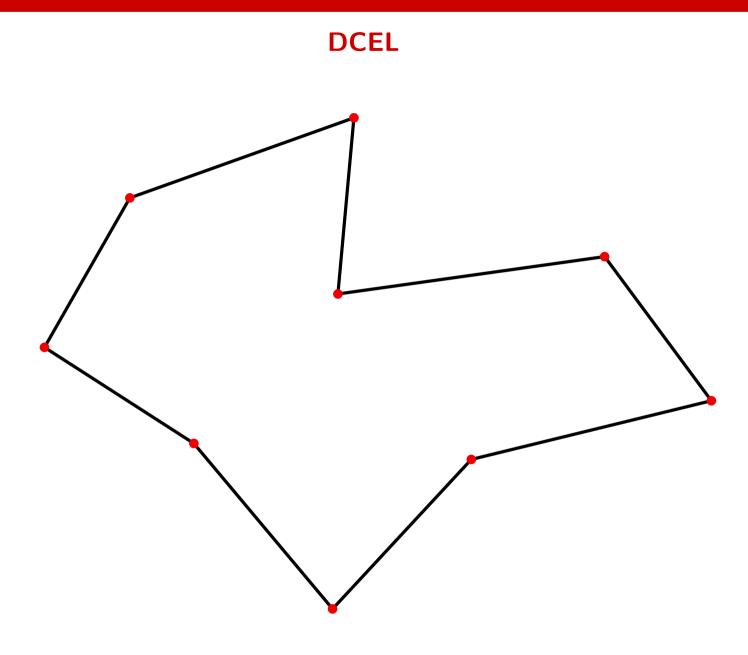
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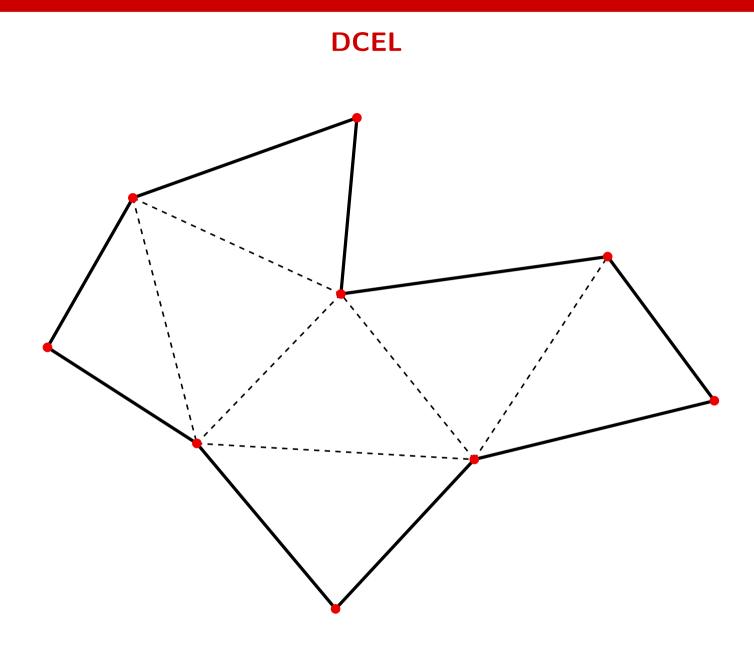
Advantage: allows to quickly recover neighborhood information.

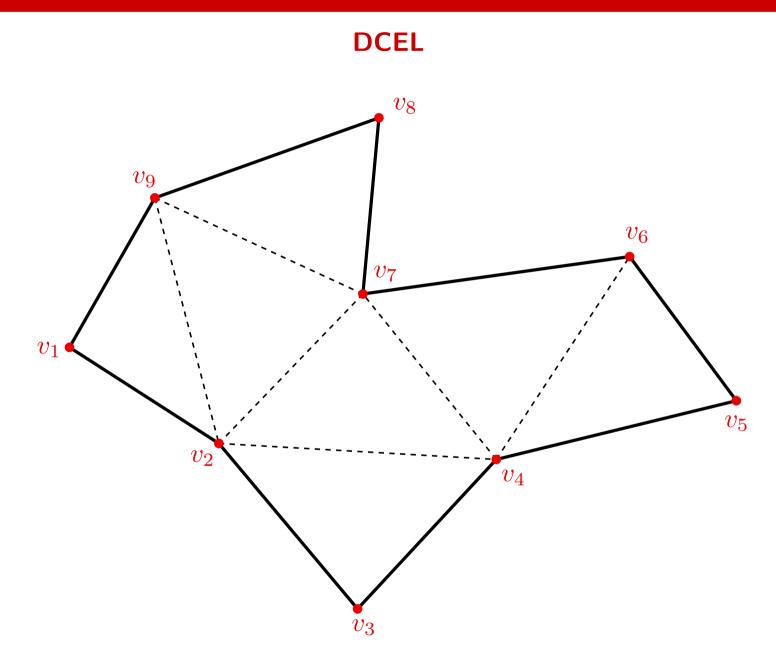
Disadvantage: the stored data is redundant and it uses more space than required.

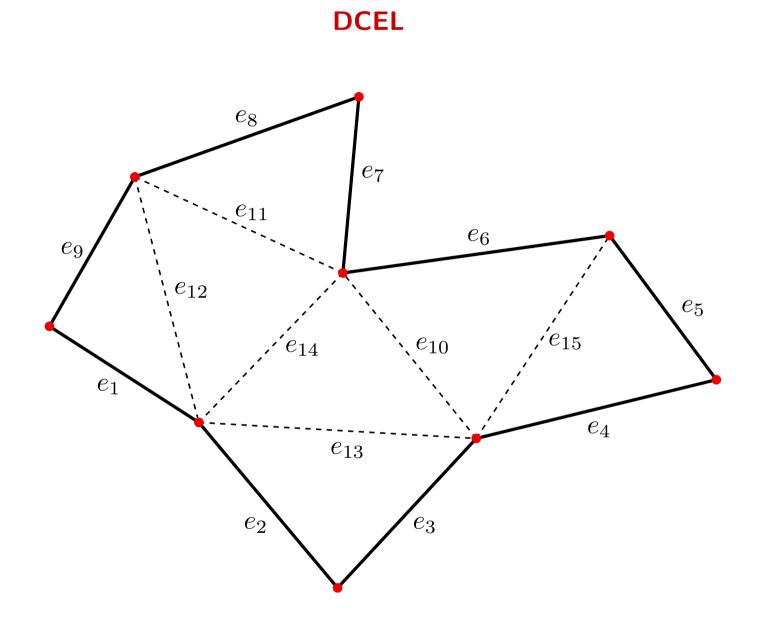
The data structure which is most frequently used to store a triangulation is the DCEL (doubly connected edge list).

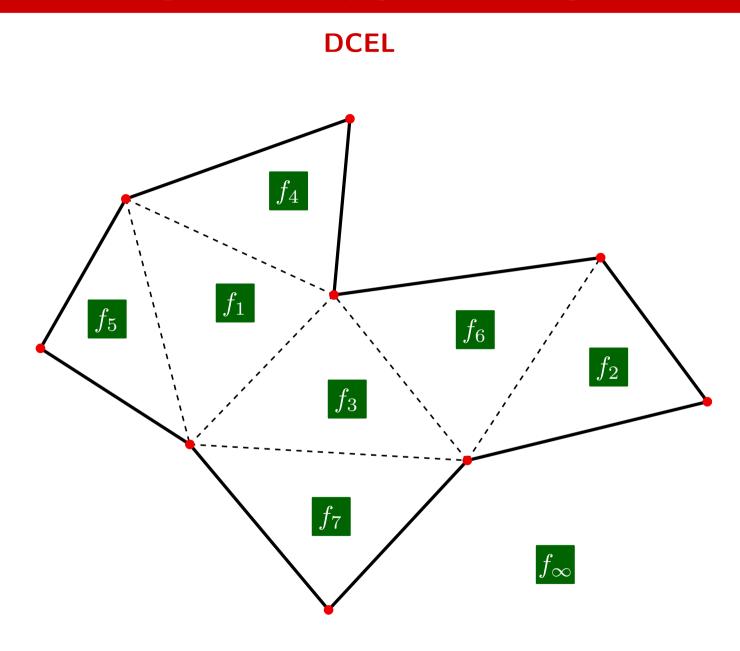
The DCEL is also used to store plane partitions, polyhedra, meshes, etc.

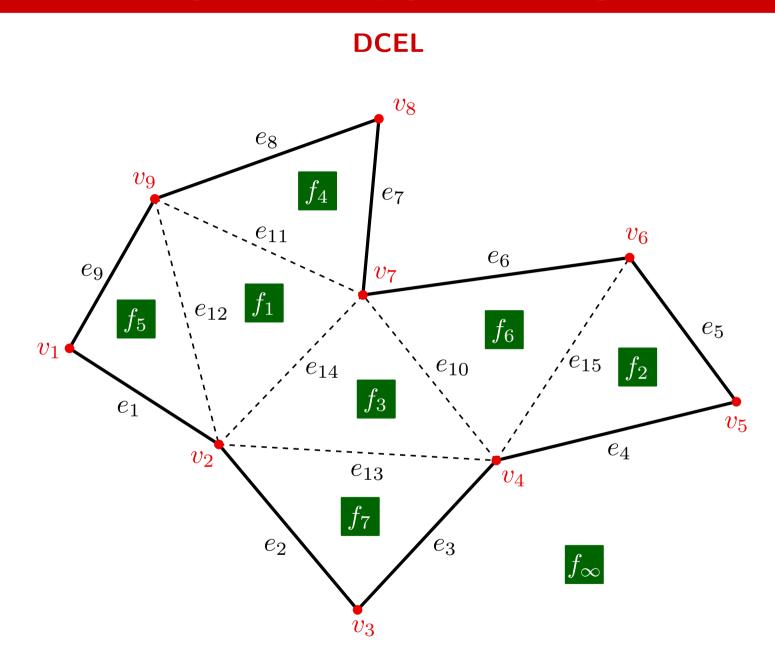












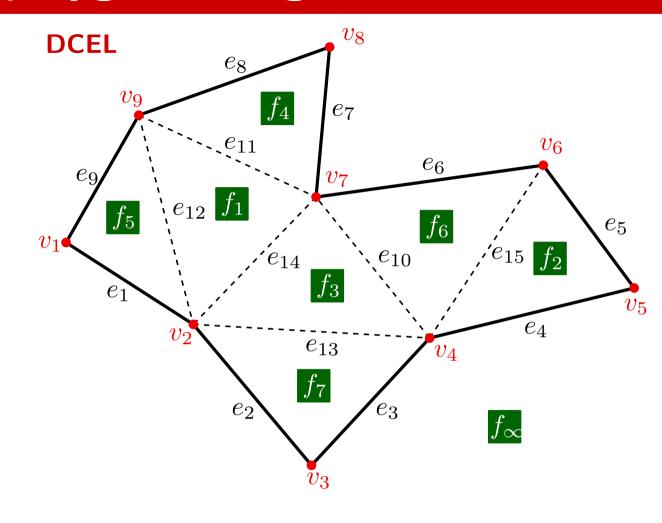


Table of vertices

v	x	y	e
1	x_1	y_1	1
2	x_2	y_2	1
3	x_3	y_3	2
4	x_4	y_4	10
5	x_5	y_5	4
6	x_6	y_6	6
7	x_7	y_7	10
8	x_8	y_8	8
9	x_9	y_9	9

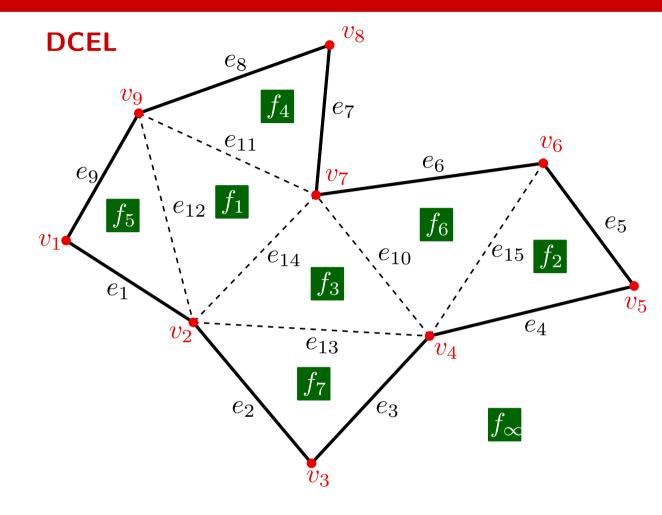
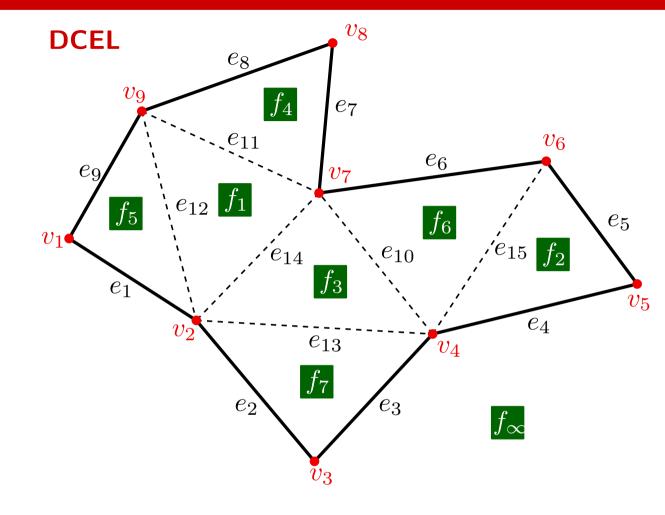
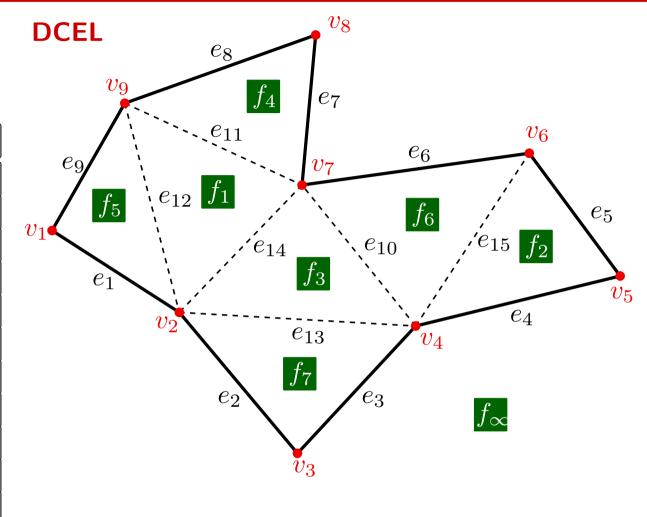


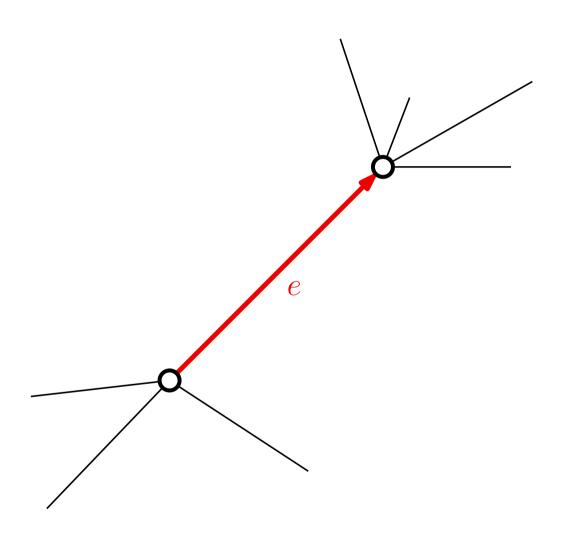
Table of faces

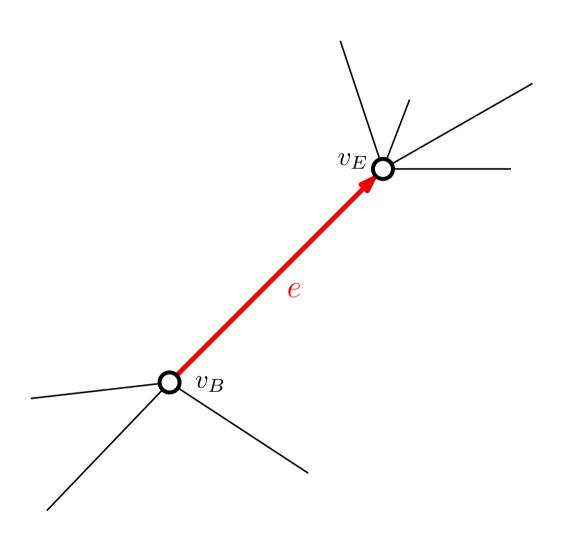
-£	
	e
1	11
2	4
3	10
4	11
5	1
6	6
7	2
∞	9

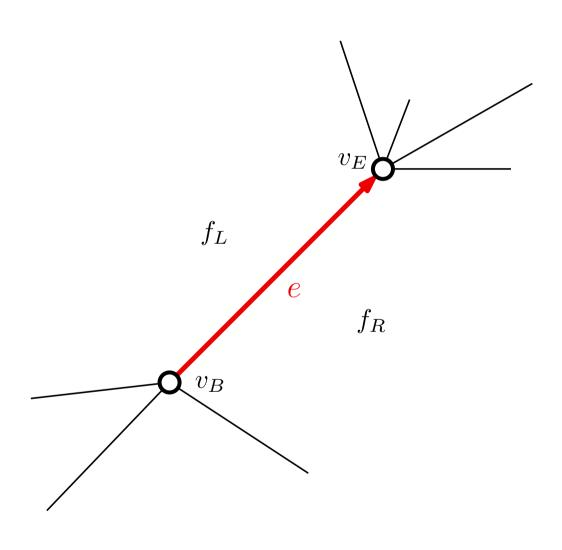


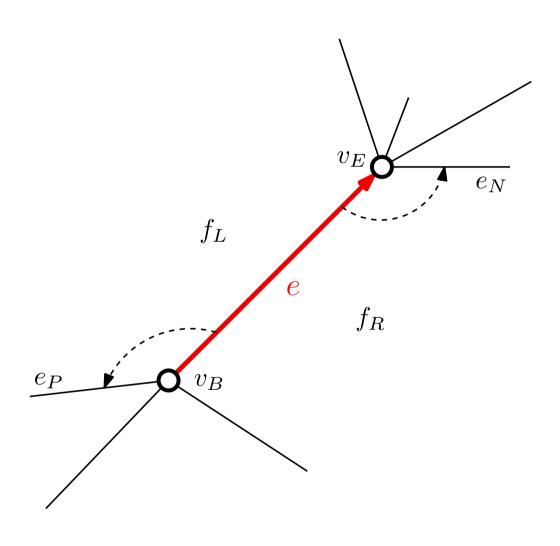
e	v_B	v_E	f_L	f_R	e_P	e_N
1	1	2	5	∞	9	2
2	2	3	7	∞	13	3
3	4	3	∞	7	4	2
4	4	5	2	∞	15	5
5	5	6	2	∞	4	6
6	6	7	6	∞	15	7
7	7	8	4	∞	11	8
8	8	9	4	∞	7	9
9	9	1	5	∞	12	1
10	4	7	3	6	13	6
11	9	7	4	1	8	14
12	2	9	5	1	1	11
13	2	4	3	7	14	3
14	2	7	1	3	12	10
15	4	6	6	2	10	5



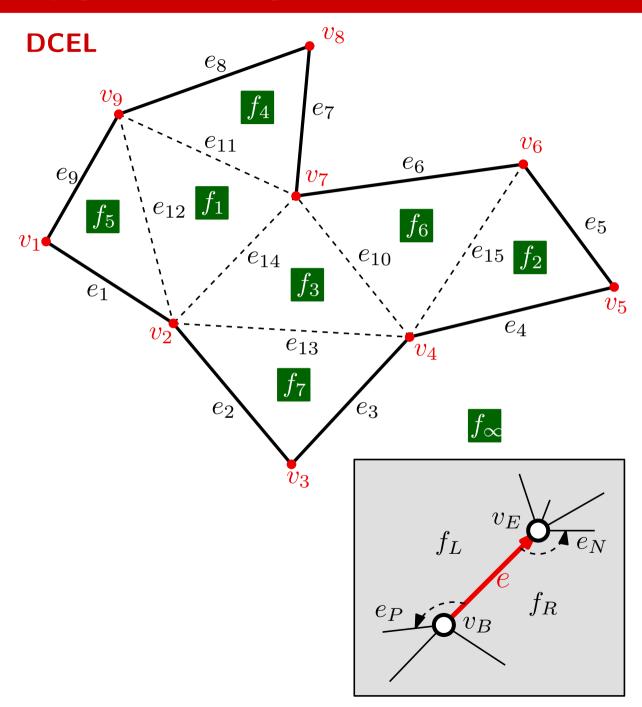








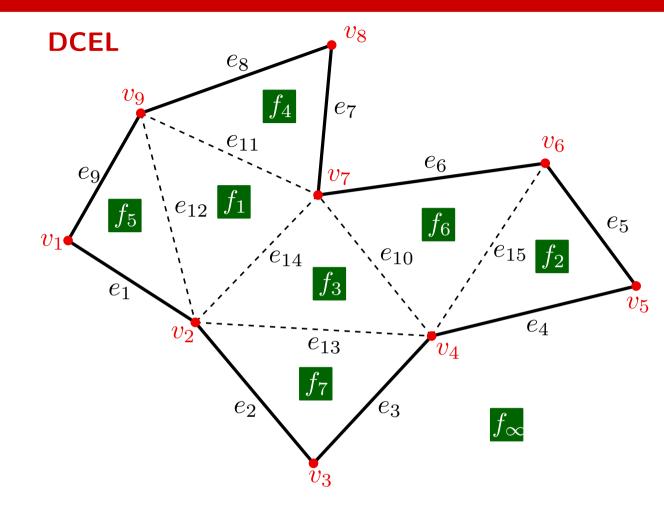
e	v_B	v_E	f_L	f_R	e_P	e_N
1	1	2	5	∞	9	2
2	2	3	7	∞	13	3
3	4	3	∞	7	4	2
4	4	5	2	∞	15	5
5	5	6	2	∞	4	6
6	6	7	6	∞	15	7
7	7	8	4	∞	11	8
8	8	9	4	∞	7	9
9	9	1	5	∞	12	1
10	4	7	3	6	13	6
11	9	7	4	1	8	14
12	2	9	5	1	1	11
13	2	4	3	7	14	3
14	2	7	1	3	12	10
15	4	6	6	2	10	5



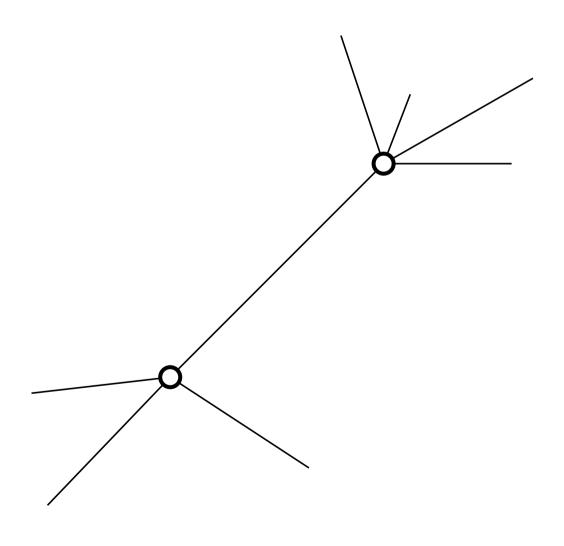
Storage space

- For each face:
 - 1 pointer
- For each vertex:
 - 2 coordinates + 1 pointer
- For each edge:
 - 6 pointers

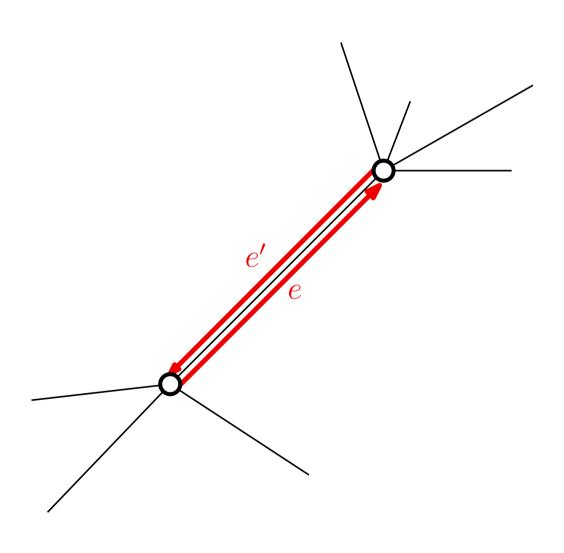
In total, the storage space is O(n).



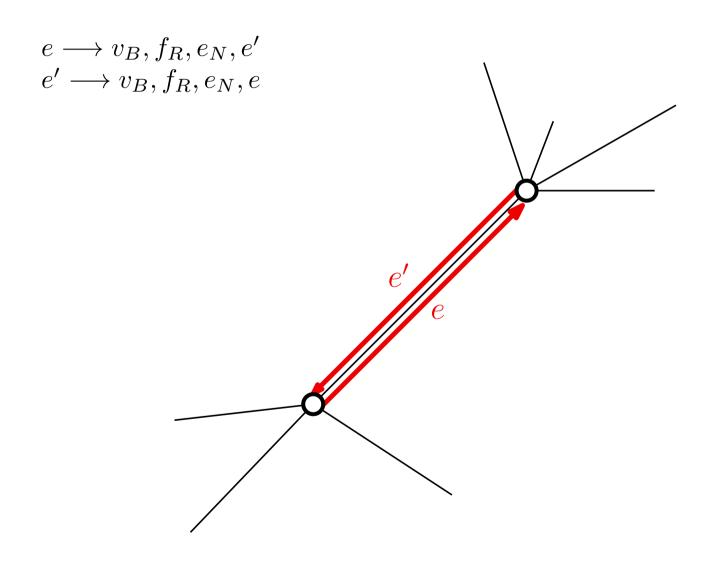
DCEL



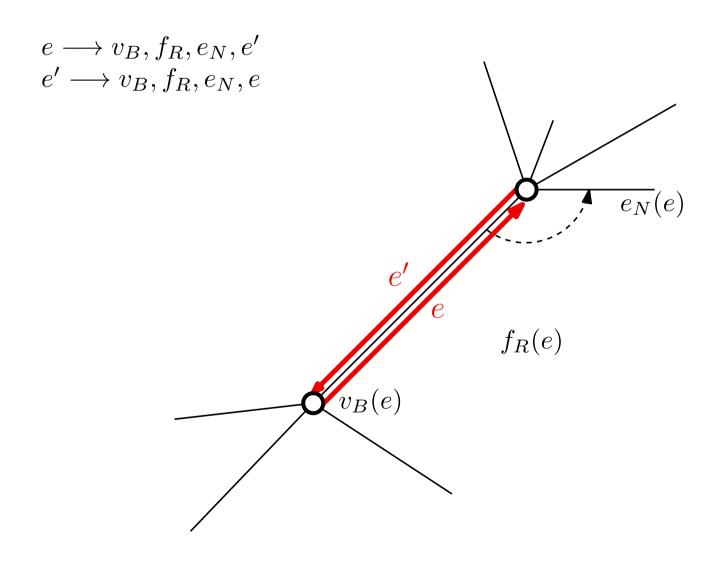
DCEL



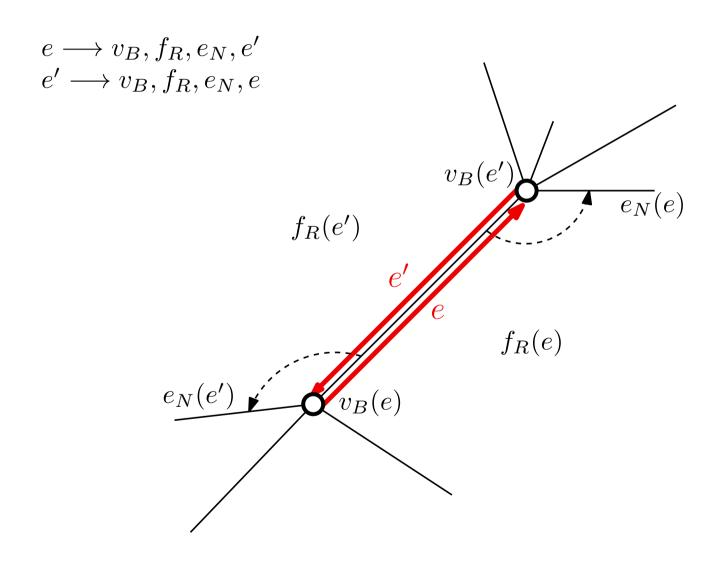
DCEL

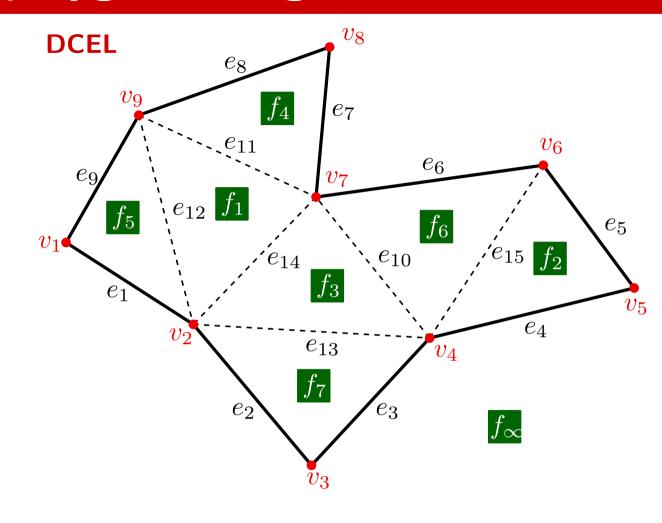


DCEL

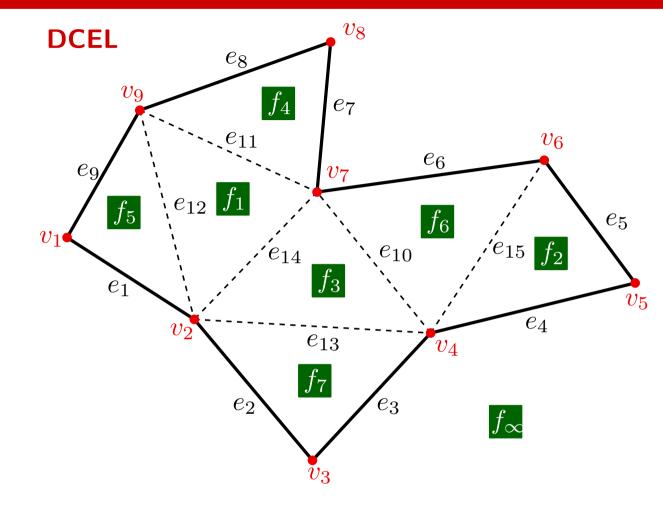


DCEL

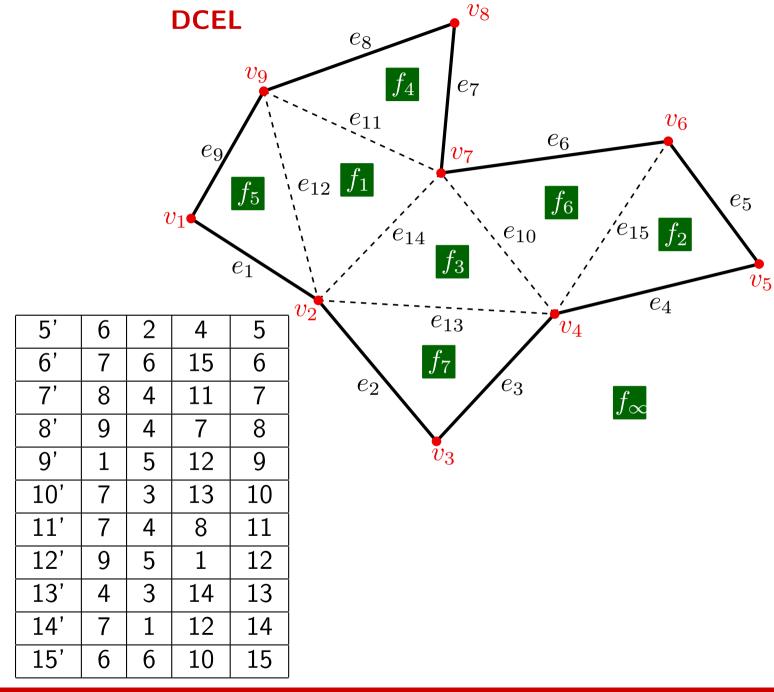




lacksquare	v_B	v_E	f_L	f_R	e_P	e_N
1	1	2	5	∞	9	2
2	2	3	7	∞	13	3
3	4	3	∞	7	4	2
4	4	5	2	∞	15	5
5	5	6	2	∞	4	6
6	6	7	6	∞	15	7
7	7	8	4	∞	11	8
8	8	9	4	∞	7	9
9	9	1	5	∞	12	1
10	4	7	3	6	13	6
11	9	7	4	1	8	14
12	2	9	5	1	1	11
13	2	4	3	7	14	3
14	2	7	1	3	12	10
15	4	6	6	2	10	5



e	v_B	f_R	e_N	e'
1	1	∞	2 3 2 5 6 7 8 9 1 6	1'
1 2 3 4 5 6 7 8 9	2	∞	3	1' 2' 3' 4' 5' 6' 7' 8' 9'
3	4	7	2	3'
4	4	∞	5	4'
5	5	∞	6	5
6	6	∞	7	6'
7	7	∞	8	7'
8	8	∞	9	8'
9	9	∞	1	9'
10	4	6	6	10'
11	9	1	14	11'
12	2	1	11	12'
13	2	7	3	13'
14	2	3	10	14'
15	4	2	5	15'
1'	2	5	9	1
11 12 13 14 15 1' 2' 3' 4'	1 2 4 4 5 6 7 8 9 4 9 2 2 2 4 2 3 3	$egin{array}{c c} \infty & & & & \\ \hline \infty & & & & \\ \hline \infty & & & \\ \hline 6 & & & \\ \hline 1 & & & \\ \hline 7 & & & \\ \hline 3 & & & \\ \hline 5 & & \\ \hline 7 & & \\ \hline \infty & & \\ \hline 2 & & \\ \hline \end{array}$	14 11 3 10 5 9 13 4 15	11' 12' 13' 14' 15' 1 2 3
3'	3	∞	4	3
4'	5	2	15	4



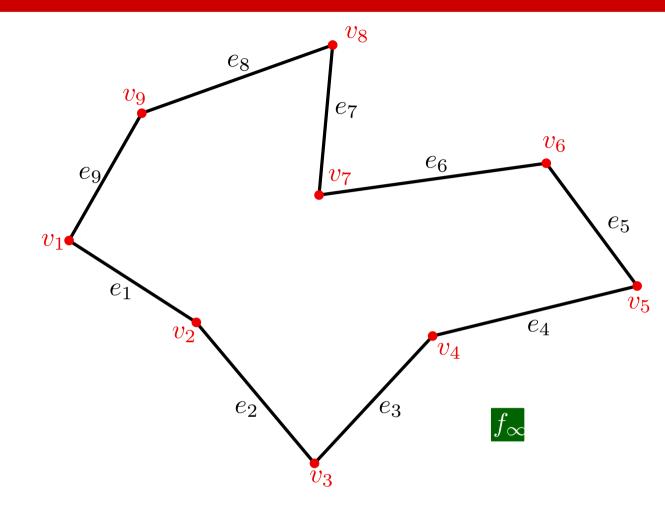
How to build the DCEL

How to build the DCEL

Algorithm 1: substracting ears

How to build the DCEL

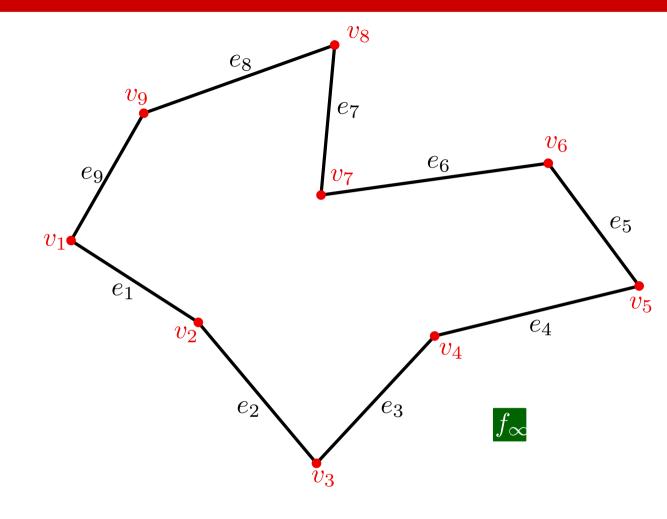
Algorithm 1: substracting ears



How to build the DCEL

Algorithm 1: substracting ears

Initialize



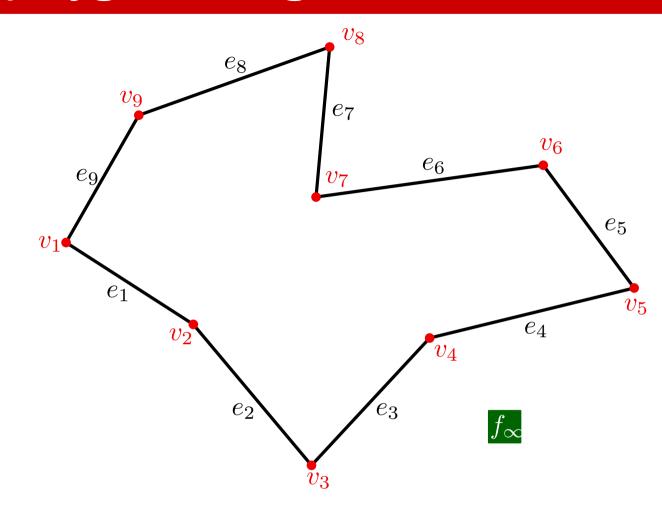
How to build the DCEL

Algorithm 1: substracting ears

Initialize

Table of vertices

v	x	y	e
1	x_1	y_1	1
2	x_2	y_2	2
3	x_3	y_3	3
4	x_4	y_4	4
5	x_5	y_5	5
6	x_6	y_6	6
7	x_7	y_7	7
8	x_8	y_8	8
9	x_9	y_9	9



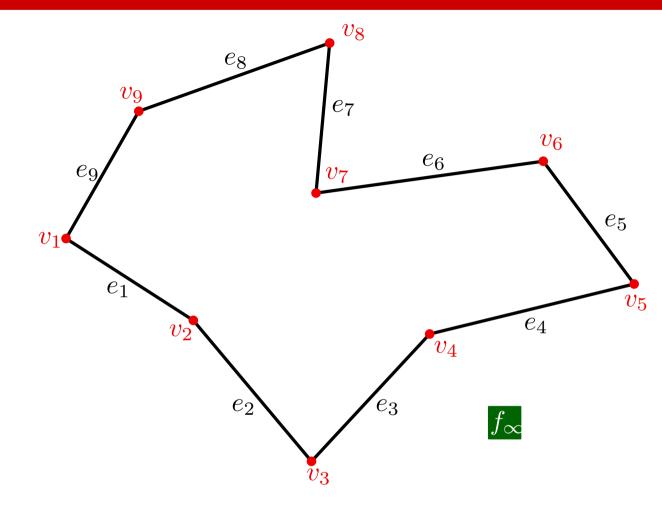
How to build the DCEL

Algorithm 1: substracting ears

Initialize

Table of faces

f	e
∞	9

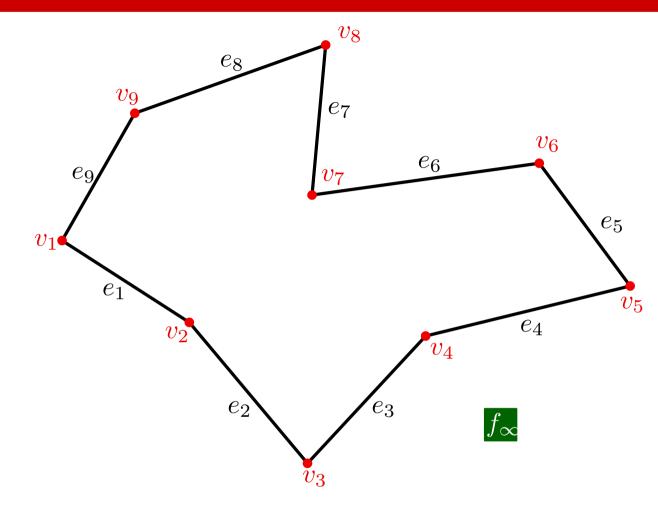


How to build the DCEL

Algorithm 1: substracting ears

Initialize

e	v_B	v_E	f_L	f_R	e_P	e_N
1	1	2		∞		2
2	2	3		∞		3
3	3	4		∞		4
4	4	5		∞		5
5	5	6		∞		6
6	6	7		∞		7
7	7	8		∞		8
8	8	9		∞		9
9	9	1		∞		1

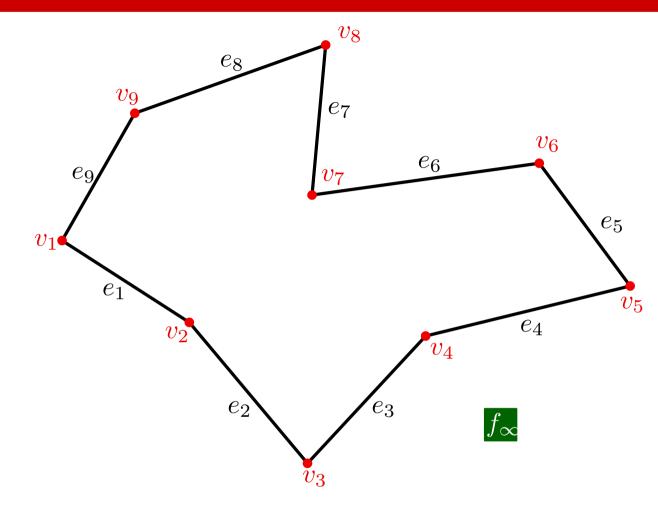


How to build the DCEL

Algorithm 1: substracting ears

Initialize

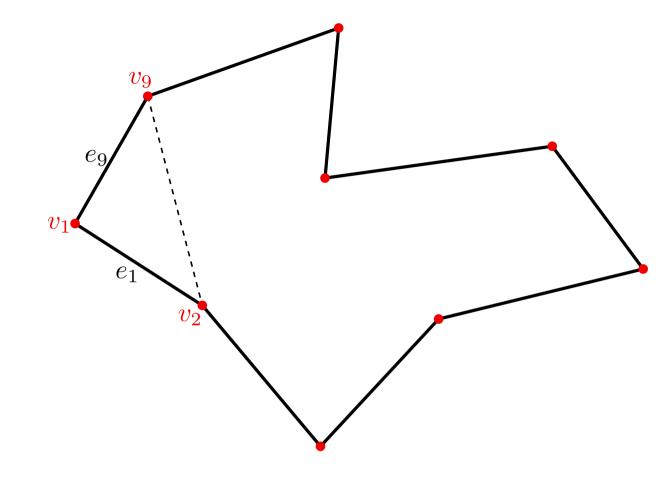
$oxed{e}$	v_B	v_E	f_L	f_R	e_P	e_N
1	1	2		∞		2
2	2	3		∞		3
3	4	3	∞		4	
4	4	5		∞		5
5	5	6		∞		6
6	6	7		∞		7
7	7	8		∞		8
8	8	9		∞		9
9	9	1		∞		1



How to build the DCEL

Algorithm 1: substracting ears

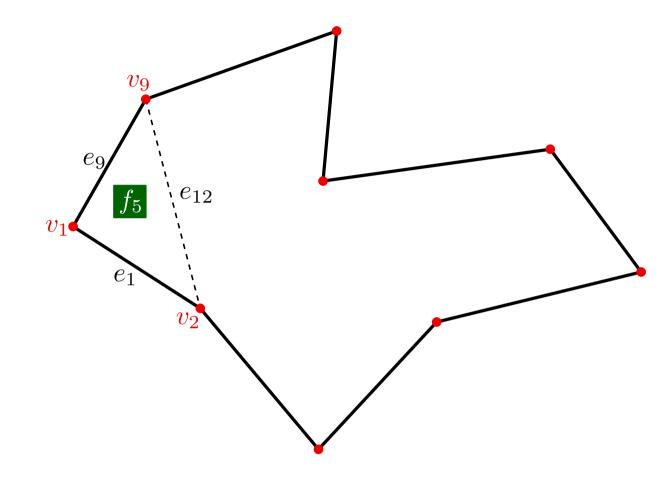
Advance



How to build the DCEL

Algorithm 1: substracting ears

Advance



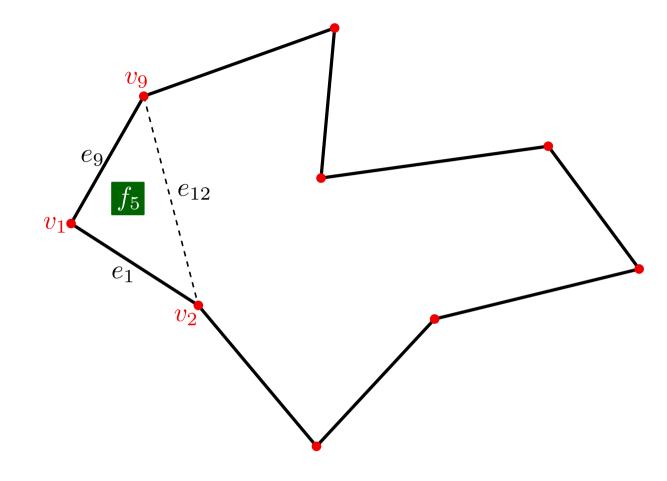
How to build the DCEL

Algorithm 1: substracting ears

Advance

Table of faces

\int	e
5	9



How to build the DCEL

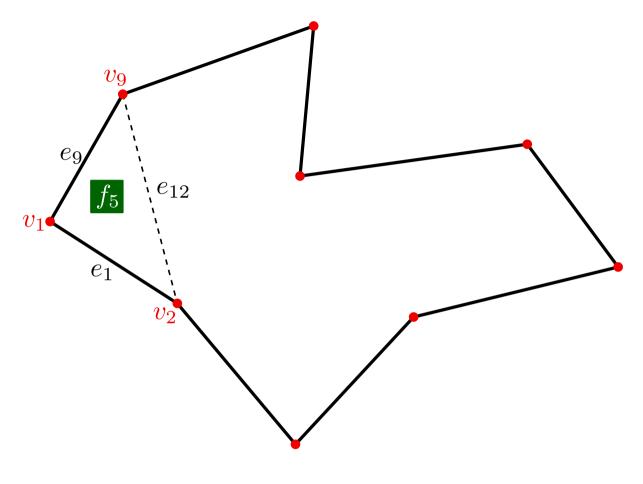
Algorithm 1: substracting ears

Advance

Table of faces

f	e
5	9

e	v_B	v_E	f_L	f_R	e_P	e_N
1	1	2	5	∞	9	2
9	9	1	5	∞	12	1
12	2	9	5		1	

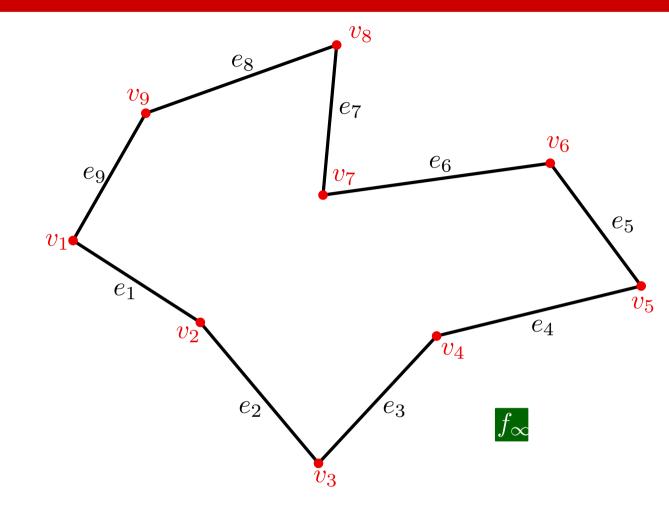


How to build the DCEL

Algorithm 2: inserting diagonals

How to build the DCEL

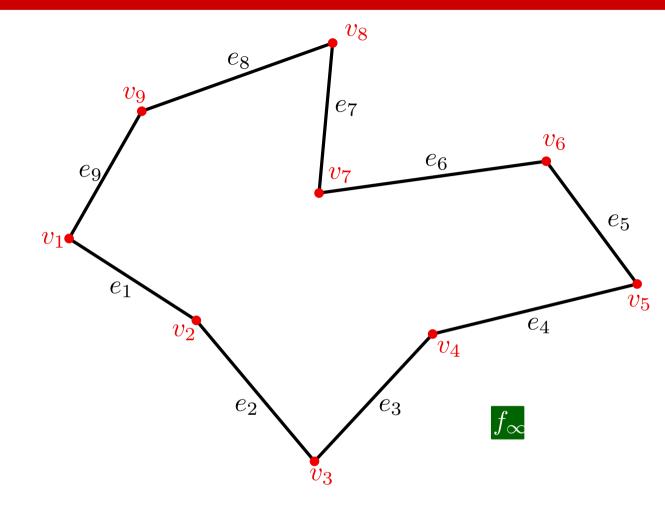
Algorithm 2: inserting diagonals



How to build the DCEL

Algorithm 2: inserting diagonals

Initialize



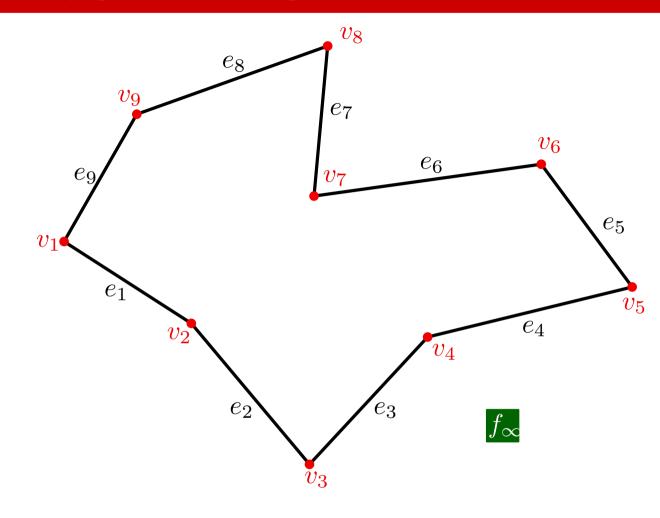
How to build the DCEL

Algorithm 2: inserting diagonals

Initialize

Table of vertices

v	x	y	e
1	x_1	y_1	1
2	x_2	y_2	2
3	x_3	y_3	3
4	x_4	y_4	4
5	x_5	y_5	5
6	x_6	y_6	6
7	x_7	y_7	7
8	x_8	y_8	8
9	x_9	y_9	9



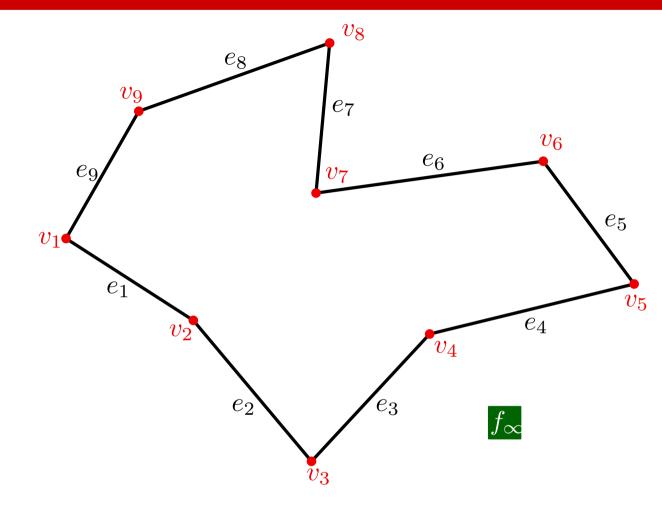
How to build the DCEL

Algorithm 2: inserting diagonals

Initialize

Table of faces

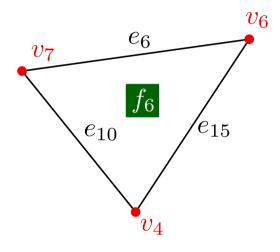
f	e
∞	9



How to build the DCEL

Algorithm 2: inserting diagonals

Base step



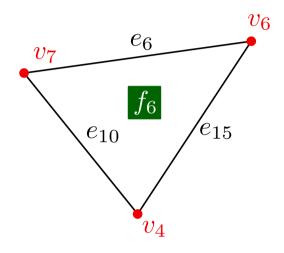
How to build the DCEL

Algorithm 2: inserting diagonals

Base step

Table of faces

$\int f$	e
6	10



How to build the DCEL

Algorithm 2: inserting diagonals

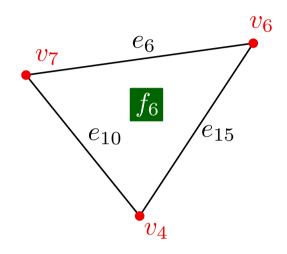
Base step

Table of faces

\int	e
6	10

DCEL

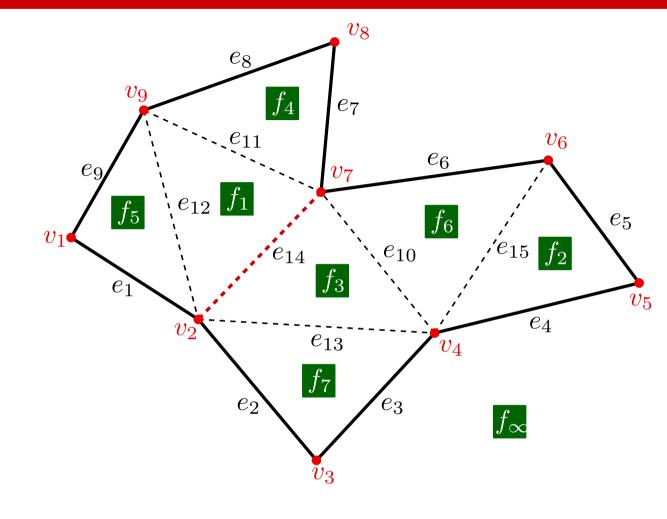
e	v_B	v_E	f_L	f_R	e_P	e_N
6	6	7	6	∞	15	10
10	7	4	6	∞	6	15
15	4	6	6	∞	10	6



How to build the DCEL

Algorithm 2: inserting diagonals

Merge step



How to build the DCEL

Algorithm 2: inserting diagonals

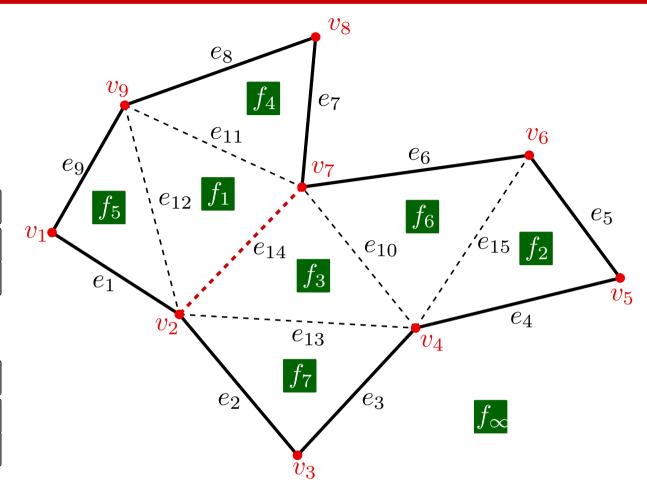
Merge step

DCEL 1

e	v_B	v_E	$\int f_L$	f_R	e_P	e_N
1	1	2	5	∞	9	14
14	2	7	1	∞	12	7

DCEL 2

e	v_B	v_E	f_L	f_R	e_P	e_N
6	6	7	6	∞	15	14
14	2	7	∞	3	2	10



How to build the DCEL

Algorithm 2: inserting diagonals

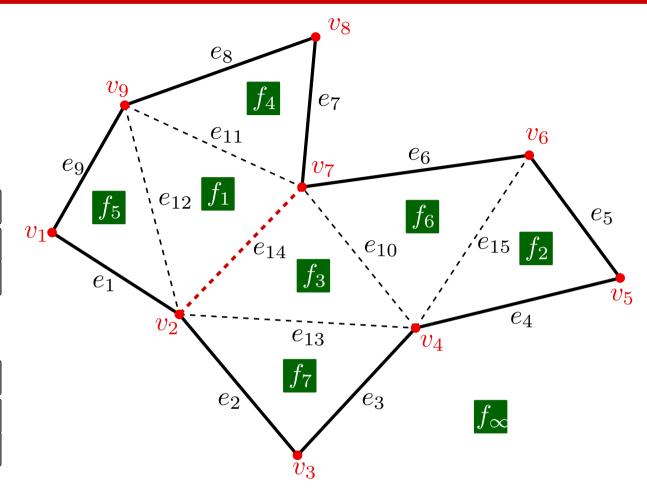
Merge step

DCEL 1

e	v_B	v_E	$\int f_L$	f_R	e_P	e_N
1	1	2	5	∞	9	14
14	2	7	1	>	12	X

DCEL 2

e	v_B	v_E	f_L	f_R	e_P	e_N
6	6	7	6	∞	15	14
14	2	7	>x<	3	X	10



How to build the DCEL

Algorithm 2: inserting diagonals

Merge step

DCEL 1

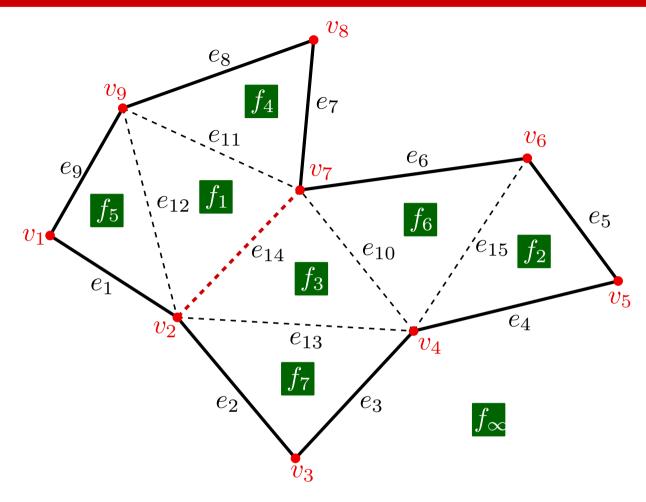
e	v_B	v_E	f_L	f_R	e_P	e_N
1	1	2	5	∞	9	14
14	2	7	1	>	12	X

DCEL 2

e	v_B	v_E	f_L	f_R	e_P	e_N
6	6	7	6	∞	15	14 (
14	2	7	>×<	3	X	10

Merged DCEL

e	v_B	v_E	f_L	f_R	e_P	e_N
1	1	2	5	∞	9	2
6	6	7	6	∞	15	7
14	2	7	1	3	12	10



How to build the DCEL

Algorithm 3:

How to build the DCEL

Algorithm 3:

- 1. Decompose into monotone polygons
- 2. Triangulate monotone pieces

How to build the DCEL

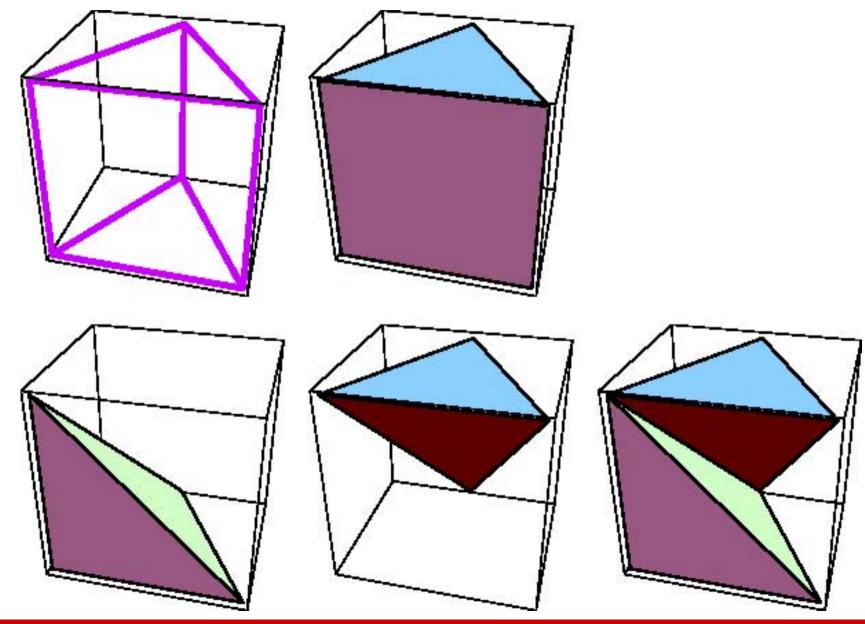
Algorithm 3:

- 1. Decompose into monotone polygons
- 2. Triangulate monotone pieces

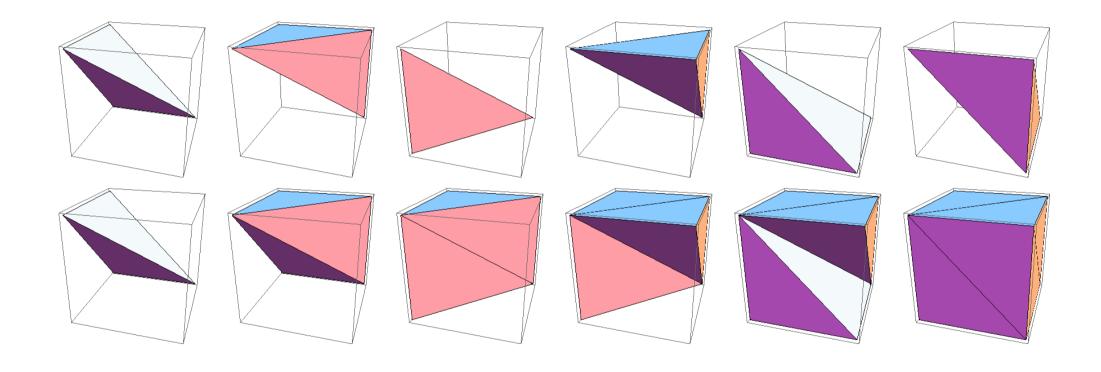
Computing the DCEL is done by combining previous strategies:

- Separating ears for triangulating each monotone subpolygon.
- Merging DCELs for putting together the monotone pieces.

A polyhedron that can be tetrahedralized:

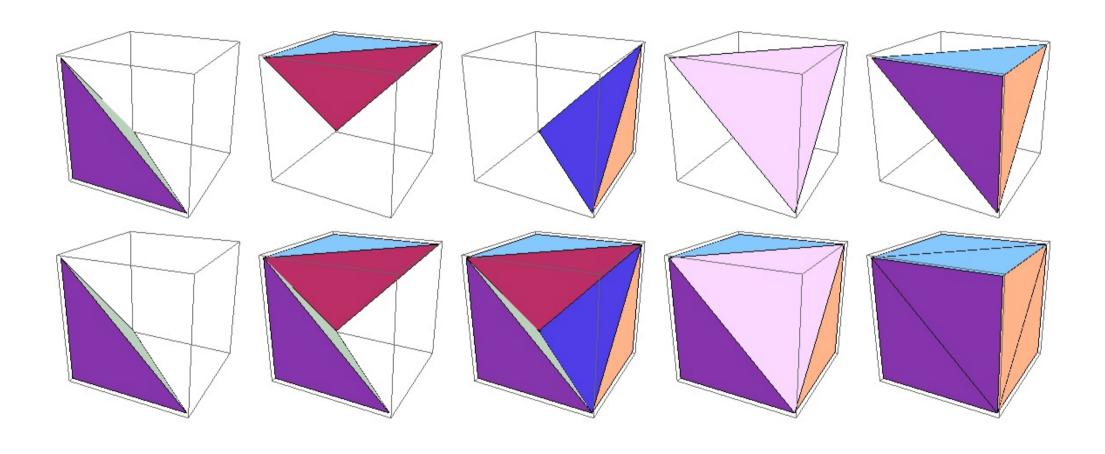


A cube can be decomposed into 6 tetrahedra...



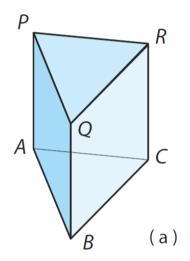
A cube can be decomposed into 6 tetrahedra...

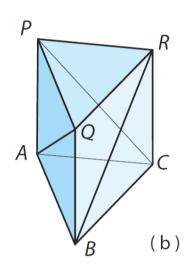
but also into 5!

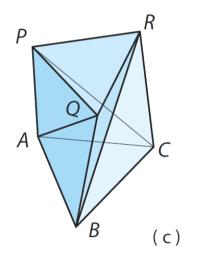


A polyhedron that cannot be tetrahedralized:

Schönhardt polyhedron







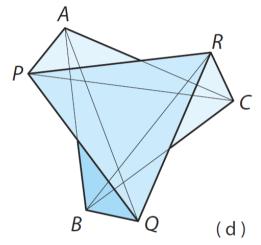
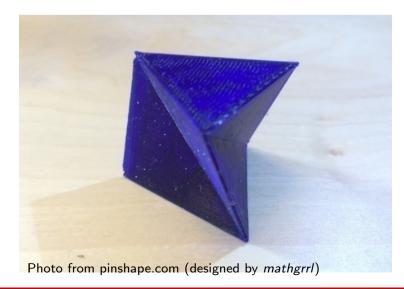


Figure from the book by Devadoss and O'Rourke

Smallest polyhedron that cannot be tetrahedralized



TRIANGULATING POLYGONS

TO LEARN MORE

- J. O'Rourke, Computational Geometry in C (2nd ed.), Cambridge University Press, 1998.
- M. de Berg, O. Cheong, M. van Kreveld, M. Overmars, **Computational Geometry: Algorithms and Applications (3rd rev. ed.)**, Springer, 2008.

TRIANGULATING POLYGONS

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- M. de Berg, O. Cheong, M. van Kreveld, M. Overmars, **Computational Geometry: Algorithms and Applications (3rd rev. ed.)**, Springer, 2008.

A NICE APPLICATION

The art gallery theorem

• J. O'Rourke, **Art Gallery Theorems and Algorithms**, Oxford University Press, 1987. http://maven.smith.edu/~orourke/books/ArtGalleryTheorems/art.html